

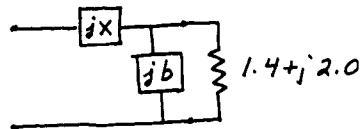
Chapter 5

5.1 (Smith chart solutions)

a) $z_L = 1.4 + j2.0$

inside $1+jx$ circle

SOLN #1: $b_1 = -0.10 \checkmark$
 $x_1 = -1.7 \checkmark$

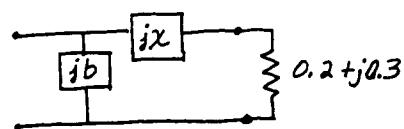


SOLN #2: $b_2 = 0.78 \checkmark$
 $x_2 = 1.7 \checkmark$

b) $z_L = 0.2 + j0.3$

outside $1+jx$ circle

SOLN #1: $x_1 = 0.10 \checkmark$
 $b_1 = 2.0 \checkmark$

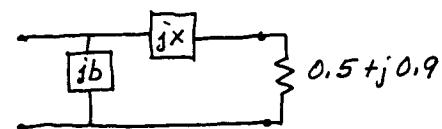


SOLN #2: $x_2 = -0.70 \checkmark$
 $b_2 = -2.0 \checkmark$

c) $z_L = 0.5 + j0.9$

outside $1+jx$ circle

SOLN #1: $x_1 = -0.40 \checkmark$
 $b_1 = 0.96 \checkmark$

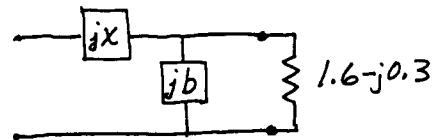


SOLN #2: $x_2 = -1.4 \checkmark$
 $b_2 = -0.96 \checkmark$

d) $z_L = 1.6 - j0.3$

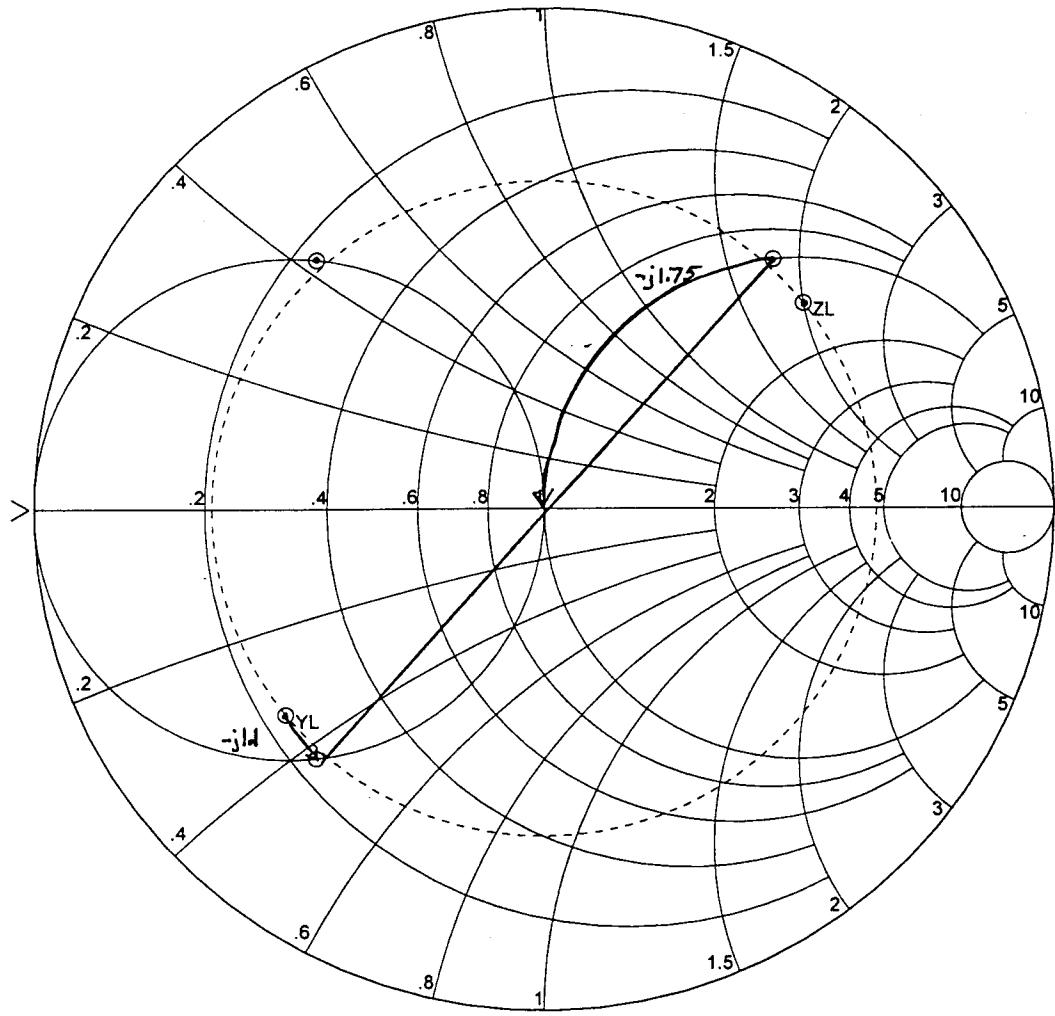
inside $1+jx$ circle

SOLN #1: $b_1 = 0.38 \checkmark$
 $x_1 = 0.80 \checkmark$



SOLN #2: $b_2 = -0.62 \checkmark$
 $x_2 = -0.80 \checkmark$

(The Smith chart for 5.1a is shown on the following page.)



Smith chart for Problem 5.1a

2

5.5

(Smith chart solutions)

The normalized load impedance is $z_L = 0.40 - j1.2$. To intersect the $1+jx$ circle, we must move back from the load either of the following distances:

$$d_1 = 0.19 + (0.5 - 0.355) = 0.335 \lambda \checkmark$$

or, $d_2 = 0.31 + (0.5 - 0.355) = 0.455 \lambda \checkmark$

The reactances necessary for matching are then,

$$X_{S1} = -2.1$$

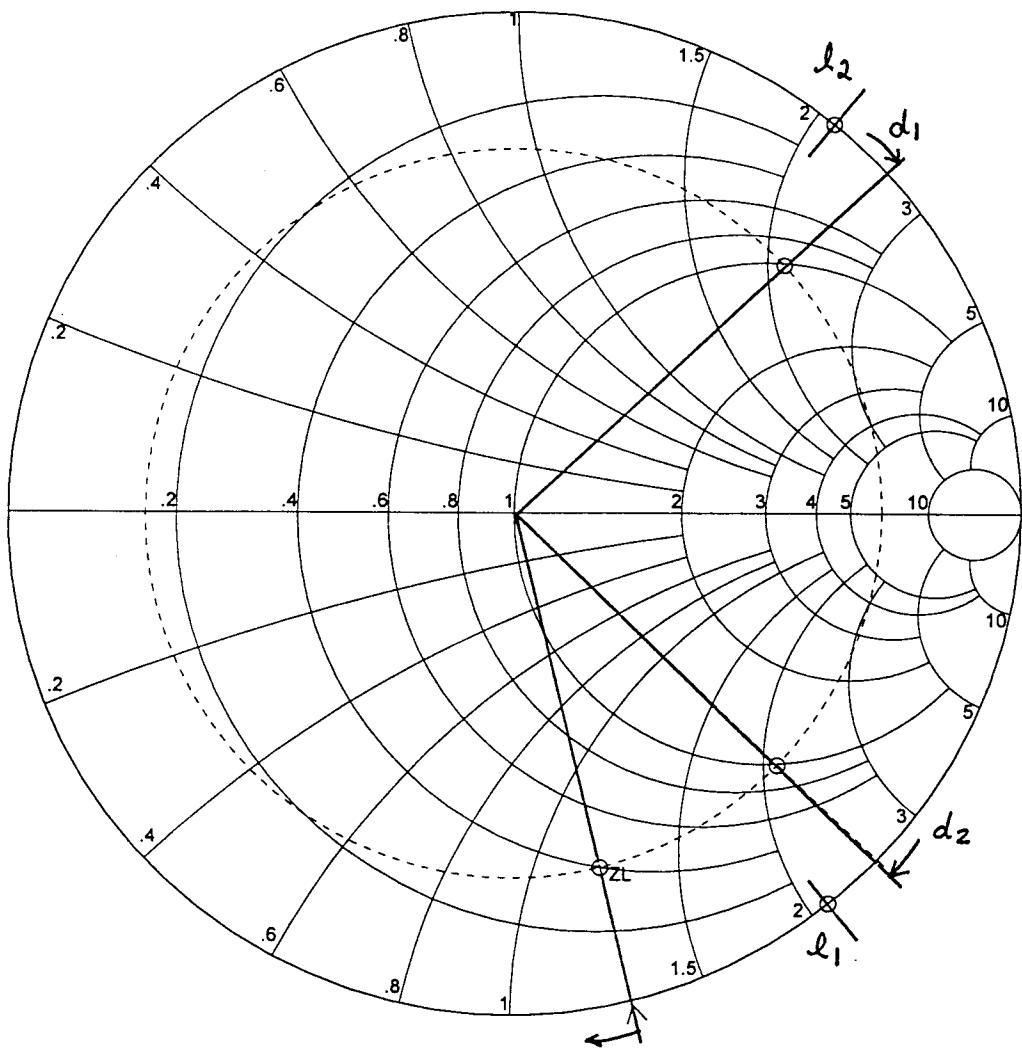
$$X_{S2} = 2.1$$

Then the open-circuited stub lengths are,

$$l_1 = 0.32 - 0.25 = 0.07 \lambda \checkmark$$

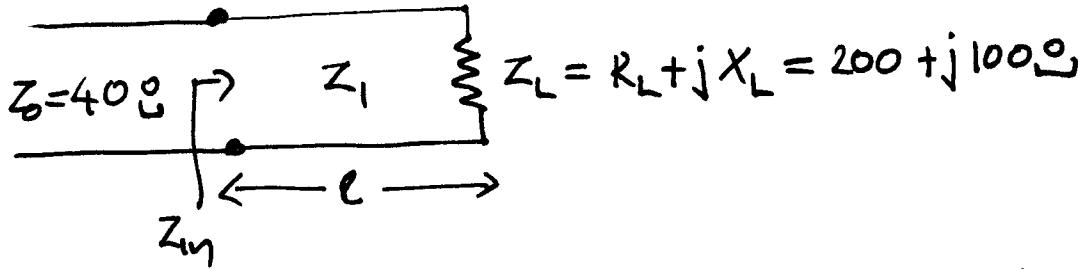
$$l_2 = 0.25 + 0.18 = 0.43 \lambda \checkmark$$

(The Smith chart for this problem is shown on the following page.)



Smith chart for Problem 5.5

Problem 5.7.



To achieve matching $Z_m = Z_0 = Z_1 \frac{Z_L + jZ_L t}{Z_1 + jZ_L t}$, $t = \tan \phi L$

$$\text{Hence } Z_0 Z_1 + j Z_0 Z_L t = Z_1 Z_L + j Z_1^2 t$$

$$\text{Equating real parts: } Z_0 Z_1 - Z_0 X_L t = Z_1 R_L \dots \dots \quad (1)$$

$$\text{--/-- imaginary parts: } Z_0 R_L t = Z_1 X_L + Z_1^2 t \quad - - \quad (2)$$

$$\text{Let } u = - \frac{Z_0 X_L}{R_L - Z_0} \text{ then from (1) } Z_1 = u t \quad \dots \dots \quad (3)$$

$$\text{from (2), (3)} : Z_1^2 + u X_L - Z_0 R_L = 0$$

$$\text{Hence } Z_1 = \sqrt{Z_0} \sqrt{R_L + \frac{X_L^2}{R_L - Z_0}} \quad (4)$$

$$\text{and } t = \tan \phi L = \frac{Z_1}{u} = -Z_1 \frac{R_L - Z_0}{Z_0 X_L} \quad (5)$$

Qn

In the example: $Z_0 = 40$, $R_L = 200$, $X_L = 100$.

Hence,

i.e.

$$\boxed{Z_1 = 102.5 \angle -4.10^\circ} \quad \text{and} \quad \tan \beta L = -4.10$$

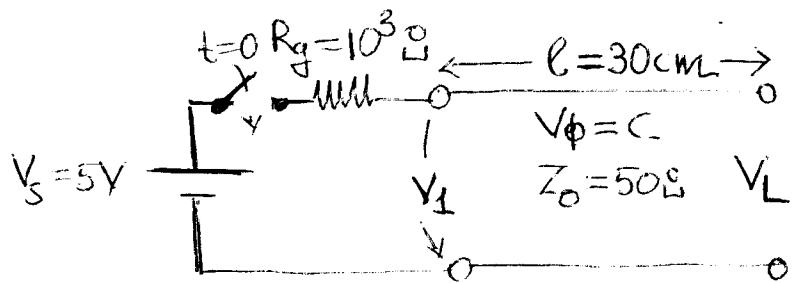
In general to achieve matching Z_1 must be real.

Hence from (4)

i) $R_L > Z_0$ then Z_1 is always real.

ii) $R_L < Z_0$ then $R_L > \frac{X_L^2}{Z_0 - R_L}$ i.e.

$$X_L^2 < R_L(Z_0 - R_L)$$

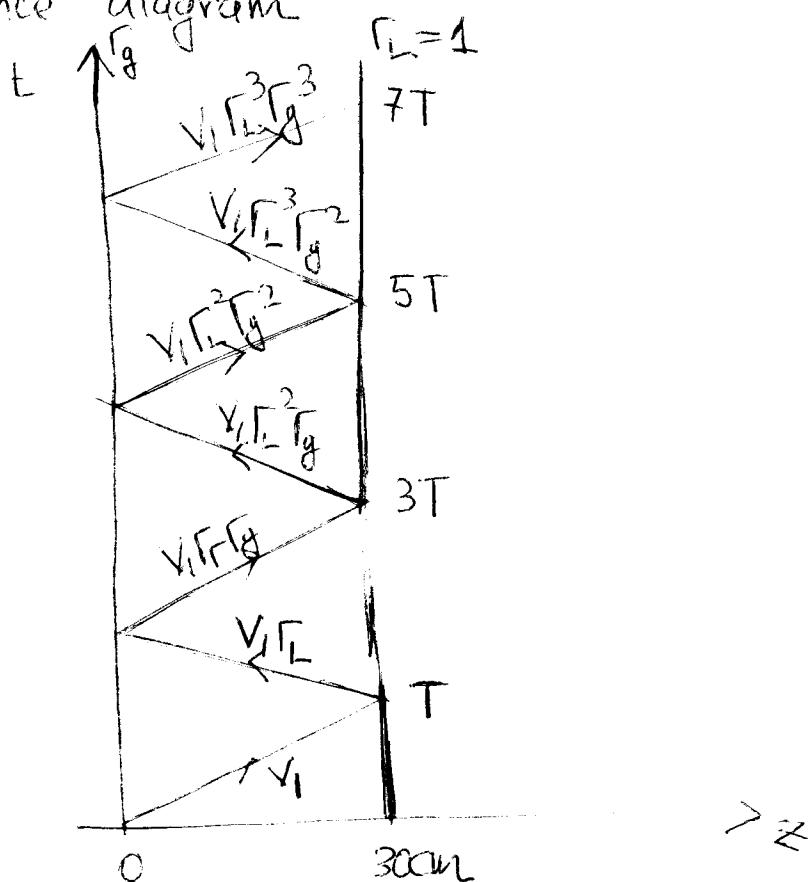


$$\Gamma_g = 0.9048 \quad \Gamma_L = 1$$

a) Transit time, $T = \frac{l}{c} = 1\text{ns}$

b) At $t=0$, $V_I = \frac{V_s Z_0}{R_g + Z_0} = 0.2381V$

c) Bounce diagram



d) Noting that $\Gamma_L = 1$, a general expression for the load voltage is

$$V_L = 2V_1 + 2V_1 \Gamma_g + 2V_1 \Gamma_g^2 + 2V_1 \Gamma_g^3 + \dots$$

Hence, $V_L = 2V_1 \left(1 + \frac{\Gamma_g}{T} + \frac{\Gamma_g^2}{2T} + \frac{\Gamma_g^3}{5T} + \dots \right)$

Summing the geometric progress the load voltage at

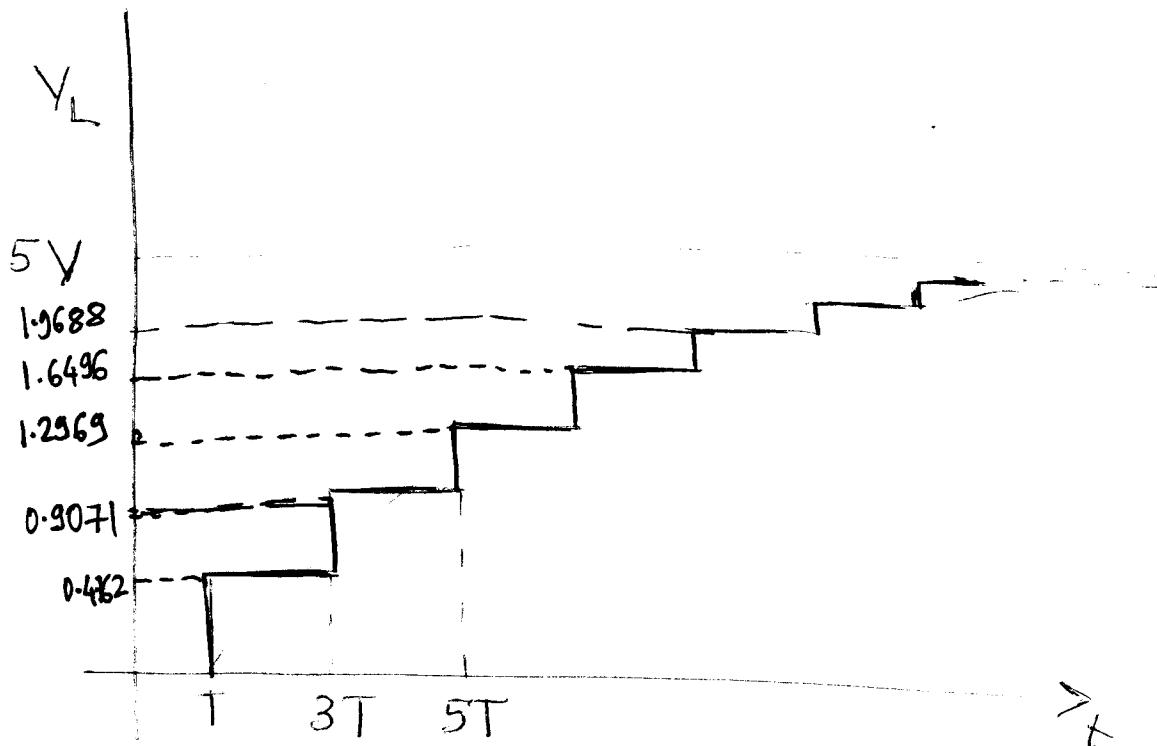
$\tau = T + 2T(n+1)$ is $V_L = 2V_1 \frac{1 - \Gamma_g^n}{1 - \Gamma_g}$, $n=1, 2, 3, \dots$

e) As $t \rightarrow \infty$ then $n \rightarrow \infty$ and

$$V_L = 2V_1 \frac{1}{1 - \Gamma_g} = 0.2381 \frac{2}{(1-0.9048)} = 5V = V_S$$

as expected

f) Using part (d) the step-response at the load is



Therefore, the gate is triggered at 5V with a delay which approaches an exponential variation with time.

(g) From (d) Let $V_L = 0.9V_S$, hence

$$0.9V_S = 2V_1 \cdot \frac{1 - \bar{f}_g^n}{1 - \bar{f}_g} \Rightarrow \frac{1 - \bar{f}_g^n}{1 - \bar{f}_g} = K$$

where $K = \frac{0.9V_S}{2V_1}$. Therefore, with $K = 9.45$

$$n = \frac{\log[1 - K(1 - \bar{f}_g)]}{\log(\bar{f}_g)} = 23$$

i.e. $n = 23$ and $t = T + 2T(22) = T = 45T = 45ns!$

Your fast logic becomes quite slow!