## nservation of Energy & Poynting Theorem

• From Maxwell's equations we have

$$\begin{split} \nabla \times \vec{E} &= -\vec{M}_i - \frac{\partial B}{\partial t} = -\vec{M}_i - \vec{M}_d \\ \nabla \times \vec{H} &= \vec{J}_i + \vec{J}_c + \frac{\partial \vec{D}}{\partial t} = \vec{J}_i + \vec{J}_c + \vec{J}_d \end{split}$$

• From above it **can be shown** (HW)

$$\nabla \cdot \vec{E} \times \vec{H} + \vec{H} \cdot \left(\vec{M}_i + \vec{M}_d\right) + \vec{E} \cdot \left(\vec{J}_i + \vec{J}_c + \vec{J}_d\right) = 0 \text{ or}$$
$$\oiint_{S} \vec{E} \times \vec{H} \cdot d\vec{s} + \iiint_{v} \vec{H} \cdot \left(\vec{M}_i + \vec{M}_d\right) dv + \iiint_{v} \vec{E} \cdot \left(\vec{J}_i + \vec{J}_c + \vec{J}_d\right) dv = 0$$

• We **rewrite** the above according to

$$\oint_{S} \vec{E} \times \vec{H} \cdot d\vec{s} + \iiint_{v} \left( \vec{H} \cdot \vec{M}_{i} + \vec{E} \cdot \vec{J}_{i} \right) dv + \iiint_{v} \left( \vec{H} \cdot \vec{M}_{d} \right) dv + \iiint_{v} \left( \vec{E} \cdot \vec{J}_{d} \right) dv + \iiint_{v} \vec{E} \cdot \vec{J}_{c} \ dv = 0$$

$$\oint_{S} \vec{E} \times \vec{H} \cdot d\vec{s} + \iiint_{v} \left( \vec{H} \cdot \vec{M}_{i} + \vec{E} \cdot \vec{J}_{i} \right) dv + \iiint_{v} \left( \vec{H} \cdot \frac{\partial \vec{B}}{\partial t} \right) dv + \iiint_{v} \left( \vec{E} \cdot \frac{\partial \vec{D}}{\partial t} \right) dv + \iiint_{v} \vec{E} \cdot \vec{J}_{c} \ dv = 0$$

• Let us **define**  $\vec{H} \cdot \vec{M}_i + \vec{E} \cdot \vec{J}_i = -\rho_{\text{supp}}$ , where  $\rho_{\text{supp}} \equiv$ **Supplied power density** [Watt/m<sup>3</sup>]. Then

$$\iiint_{v} \left( \vec{H} \cdot \vec{M}_{i} + \vec{E} \cdot \vec{J}_{i} \right) dv = -\iiint_{v} \rho_{\text{supp}} dv = -P_{\text{supp}} \left[ \text{Watt} \right]$$

• Moreover we assume that **medium is not dispersive or lossy**, then

• 
$$\iiint_{v} \vec{H} \cdot \vec{M}_{d} \, dv = \iiint_{v} \vec{H} \cdot \frac{\partial}{\partial t} \vec{B} \, dv = \iiint_{v} \vec{H} \cdot \frac{\partial}{\partial t} \, \mu \vec{H} \, dv =$$
$$\iiint_{v} \frac{1}{2} \frac{\partial}{\partial t} \left( \mu \, \vec{H} \cdot \vec{H} \right) dv = \frac{\partial}{\partial t} \underbrace{\iiint_{v} \frac{1}{2} \, \mu |\vec{H}|^{2} \, dv}_{W_{m}} = \frac{\partial}{\partial t} W_{m}$$
$$W_{m} : \left[ \frac{H}{m} \cdot \frac{A^{2}}{m^{2}} m^{3} = HA^{2} = \frac{V \cdot s}{A} A^{2} = Watt \cdot s = J \right]$$
$$\frac{\partial}{\partial t} W_{m} = \text{Rate of change of stored magnetic energy: } [J/s = Watt]$$

• 
$$\iiint_{v} \vec{E} \cdot \vec{J}_{d} \, dv = \iiint_{v} \vec{E} \cdot \frac{\partial}{\partial t} \varepsilon \, \vec{E} \, dv = \iiint_{v} \frac{1}{2} \frac{\partial}{\partial t} \varepsilon \left| \vec{E} \right|^{2} \, dv = \frac{\partial}{\partial t} \iiint_{v} \frac{1}{2} \varepsilon \left| \vec{E} \right|^{2} \, dv = \frac{\partial}{\partial t} W_{e}$$
$$W_{e} : \left[ \frac{F}{m} \cdot \frac{V^{2}}{m^{2}} m^{3} = J \right]$$
$$\frac{\partial}{\partial t} W_{e} = \text{Rate of change of stored electric energy } [J/s = Watt]$$
$$• \iiint_{v} \vec{E} \cdot \vec{J}_{c} \, dv = \iiint_{v} \vec{E} \cdot \sigma \vec{E} \, dv = \iiint_{v} \sigma \left| \vec{E} \right|^{2} dv = P_{\text{disp}}$$

 $P_{\text{disp}} \equiv \mathbf{Dissipated power} \text{ (ohmic loss): } \left[ \frac{1}{\Omega \cdot m} \cdot \frac{V^2}{m^2} \cdot m^3 = \frac{V^2}{\Omega} = \text{Watt} \right]$ 

•  $\oint \vec{E} \times \vec{H} \cdot d\vec{s} = P_{\text{exit}}$ 

 $P_{\text{exit}} \equiv \mathbf{Power exiting the volume enclosed by surface } S : \left\lfloor \frac{\mathbf{A}}{\mathbf{m}} \cdot \frac{\mathbf{V}}{\mathbf{m}} \mathbf{m}^2 = \text{Watt} \right\rfloor$ 

• We can rewrite Poynting Equation

 $\frac{P_{\text{exit}}}{\partial t} + \frac{\partial}{\partial t} W_m + \frac{\partial}{\partial t} W_e + P_{\text{disp}} = P_{\text{sup}}$  This is **Conservation of Energy** 

### Time Harmonic or Sinusoidal Steady State Electromagnetic Fields

• In time harmonic picture the **instantaneous field**  $\vec{E}(x, y, z, t)$  and the **complex spatial field**  $\vec{E}(x, y, z)$  are related by

 $E(x, y, z, t) = \operatorname{Re}\left[\overline{E}(x, y, z)e^{j\omega t}\right]$  $H(x, y, z, t) = \operatorname{Re}\left[\overline{H}(x, y, z)e^{j\omega t}\right]$  $\vdots$ 

• **Remark 1:** Fields can also be described as **imaginary parts**  $E(x, y, z, t) = \text{Im}[E(x, y, z)e^{j\omega t}]$ 

• Remark 2: Most engineering books (not all) use time dependency of  $e^{j\omega t}$ , most physics books (not all) use  $e^{-i\omega t}$ ,  $i \leftrightarrow -j$ 

• **Remark 3: We will see that for**  $e^{j\omega t}$  the wave  $e^{-jkz}e^{j\omega t}$  and for  $e^{-i\omega t}$  the wave  $e^{ikz}e^{-i\omega t}$  are **positively traveling waves** 



• With help of  $e^{j\omega t}$  time dependency  $\frac{\partial}{\partial t} \Leftrightarrow j\omega$ 

• This is similar to **circuit analysis** for which  $\frac{\partial}{\partial t} \leftrightarrow s = \sigma + j\omega \leftrightarrow j\omega$ 

• Ex: 
$$\nabla \times \vec{E} = -\frac{\partial B}{\partial t}$$
  
 $\nabla \times \vec{E}(\vec{r})e^{j\omega t} = -\frac{\partial}{\partial t}\mu\vec{H}(\vec{r})e^{j\omega t}$   
 $e^{j\omega t} \nabla \times \vec{E}(\vec{r}) = -\mu j\omega \vec{H}(\vec{r})e^{j\omega t} \Rightarrow \nabla \times \vec{E}(x, y, z) = -j\omega\mu \vec{H}(x, y, z)$ 

• Or in **integral form** 

$$\oint_c \vec{E} \cdot d\vec{l} = -j\omega \iint_S \mu \ \vec{H} \cdot d\vec{s}$$

## Poynting theorem for time harmonic fields

• 
$$\nabla \times \vec{E} = -\vec{M}_i - j\omega\mu \vec{H}$$
 and  $\nabla \times \vec{H} = \vec{J}_i + j\omega\varepsilon \vec{E} + \sigma \vec{E} \Rightarrow$  (1)

• 
$$\nabla \times \vec{H}^* = \vec{J}_i^* - j\omega\varepsilon \,\vec{E}^* + \sigma \,\vec{E}^*$$
 (2)

• From (1) and (2) we have (HW)  

$$-\frac{1}{2}\left(\vec{H}^{*}\cdot\vec{M}_{i}+\vec{E}\cdot\vec{J}_{i}^{*}\right)=\nabla\cdot\frac{1}{2}\vec{E}\times\vec{H}^{*}+\frac{1}{2}\sigma|\vec{E}|^{2}+j\omega\left[\frac{1}{2}\mu|\vec{H}|^{2}-\frac{1}{2}\varepsilon|\vec{E}^{2}|\right]$$
Or  

$$-\frac{1}{2}\iiint_{v}\left(\vec{H}^{*}\cdot\vec{M}_{i}+\vec{E}\cdot\vec{J}_{i}^{*}\right)dv=\oint_{S}\frac{1}{2}\vec{E}\times\vec{H}^{*}\cdot d\vec{s}+\iiint_{v}\frac{1}{2}\sigma|\vec{E}|^{2}dv+j\omega\left[\iiint_{v}\frac{1}{2}\mu|\vec{H}|^{2}dv-\iiint_{v}\frac{1}{2}\varepsilon|\vec{E}|^{2}dv\right]$$
• If  $\varepsilon$  and  $\mu$  are complex ( $\varepsilon \rightarrow \varepsilon' - j\varepsilon''$  and  $\mu \rightarrow \mu' - j\mu''$ ) then their imaginary parts  
contribution to the dissipated power must be added to  $P_{d}=\iiint_{1}\frac{1}{2}\sigma|\vec{E}|^{2}$ . In other  
words, the term  $j\omega\left[\iiint_{v}\frac{1}{2}\mu|\vec{H}|^{2}dv-\iiint_{v}\frac{1}{2}\varepsilon|\vec{E}|^{2}dv\right]$  is considered as reactive (purely  
imaginary).

## **Poynting Vector**

• Instantaneous Poynting Vector is defined as  $\overline{S}(\overline{r},t) = \overline{E}(\overline{r},t) \times \overline{H}(\overline{r},t)$ 

• Note: in the followings I use the scripted letters  $\vec{E}, \vec{H},...$  to designate instantaneous fields, i.e.  $\mathcal{E}(\vec{r},t)$  and  $\vec{H}(\vec{r},t)$ , and regular letters  $\vec{E}(\vec{r}), \vec{H}(\vec{r})$ , to designate the time harmonic fields, i.e., only the spatial dependency

- We are to write the  $S(\vec{r},t)$  in terms of time harmonic fields  $\vec{E}(\vec{r}), \vec{H}(\vec{r})$  $\vec{S}(\vec{r},t) = \operatorname{Re}\left[\vec{E}(\vec{r})e^{j\omega t}\right] \times \operatorname{Re}\left[\vec{H}(\vec{r},t)e^{j\omega t}\right]$
- Note that:  $\frac{\text{Re}[\vec{A}] \times \text{Re}[\vec{B}] \neq \text{Re}[\vec{A} \times \vec{B}]}{\text{Re}[\vec{A} \times \vec{B}]}$

• 
$$\vec{S}(\vec{r},t) = \vec{E}(\vec{r},t) \times \vec{\mathcal{H}}(\vec{r},t) = \left[\frac{\vec{E}e^{j\omega t} + \vec{E}^*e^{-j\omega t}}{2}\right] \times \left[\frac{\vec{H}e^{j\omega t} + \vec{H}^*e^{-j\omega t}}{2}\right] \Rightarrow$$
  
 $\vec{S}(\vec{r},t) = \vec{E}(\vec{r},t) \times \vec{\mathcal{H}}(\vec{r},t) = \frac{1}{2} \operatorname{Re}\left[\vec{E} \times \vec{H}^* + \vec{E} \times \vec{H}e^{j2\omega t}\right]$ 

• Now let's calculate the **time average of** *S* 

$$\vec{S}_{\text{ave}} = \left\langle \vec{S} \right\rangle = \frac{1}{T} \int_{0}^{T} \vec{S} \, dt$$

then

$$\langle \vec{S} \rangle = \frac{1}{T} \int_{0}^{T} \frac{1}{2} \operatorname{Re} \left[ \vec{E} \times \vec{H}^{*} + \vec{E} \times \vec{H} e^{j2\omega t} \right] dt$$

$$= \frac{1}{2} \operatorname{Re} \left[ \frac{1}{T} \int_{0}^{T} \vec{E} \times \vec{H}^{*} dt \right] + \frac{1}{2} \operatorname{Re} \left[ \frac{1}{T} \int_{0}^{T} \vec{E} \times \vec{H} e^{j2\omega t} dt \right]$$

$$= \frac{1}{2} \operatorname{Re} \left[ \vec{E} \times \vec{H}^{*} \right] + 0 \Longrightarrow$$

$$\vec{S}_{\text{ave}} = \langle \vec{S} \rangle = \frac{1}{2} \operatorname{Re} \left[ \vec{E} \times \vec{H}^{*} \right]$$

• Whereas, the **instantaneous Poynting vector** in terms of the time-harmonic fields is given by:

$$\vec{\mathcal{S}}(\vec{r},t) = \frac{1}{2} \operatorname{Re}\left[\vec{E} \times \vec{H}^*\right] + \frac{1}{2} \operatorname{Re}\left[\vec{E} \times \vec{H}e^{j2\omega t}\right] = \left\langle \vec{\mathcal{S}} \right\rangle + \frac{1}{2} \operatorname{Re}\left[\vec{E} \times \vec{H}e^{2j\omega t}\right]$$

## A remark on time average of energy densities

• Recall we defined **magnetic energy as**  $W_m(t) = \frac{1}{2} \iiint_v \mu |\hat{\mathcal{H}}(\bar{r},t)|^2 dv$ 

• Now, let's calculate the **time average of this quantity i.e.**, 
$$\langle W_m \rangle$$
  
 $W_m(t) = \frac{1}{2} \iiint_v \mu \vec{\mathcal{H}}(\vec{r},t) \cdot \vec{\mathcal{H}}(\vec{r},t) dv$  but  $\vec{\mathcal{H}}(\vec{r},t) = \operatorname{Re}[\vec{H}(\vec{r})e^{j\omega t}]$  then  
 $W_m(t) = \frac{1}{2} \iiint_v \mu \operatorname{Re}[\vec{H}e^{j\omega t}] \cdot \operatorname{Re}[\vec{H}e^{j\omega t}] dv$   
 $W_m = \frac{1}{2} \iiint_v \mu \frac{\vec{H}e^{j\omega t} + \vec{H}^*e^{-j\omega t}}{2} \cdot \frac{\vec{H}e^{j\omega t} + \vec{H}^*e^{-j\omega t}}{2} dv$   
 $= \frac{1}{2} \cdot \frac{\mu}{4} \iiint_v \{\vec{H} \cdot \vec{H}e^{2j\omega t} + (H \cdot He^{2j\omega t})^* + \vec{H} \cdot \vec{H}^* + (\vec{H} \cdot \vec{H}^*)^*\} dv$   
 $= \frac{1}{4} \iiint_v \mu \operatorname{Re}[\vec{H} \cdot \vec{H}e^{2j\omega t}] + |\vec{H}|^2 \mu dv$ 

• The time average is given by

$$\langle W_m \rangle = \frac{1}{4} \frac{1}{T} \iiint_v \int_0^T \mu \operatorname{Re} \left[ \vec{H} \cdot \vec{H} e^{2j\omega t} \right] dt dv + \frac{1}{4} \iiint_v \int_0^T \mu \left| \vec{H} \right|^2 dv dt \Longrightarrow$$
  
 
$$\langle W_m \rangle = \frac{1}{4} \iiint_v \mu \left| \vec{H} \right|^2 dv .$$

• Similarly  $\langle W_m \rangle = \frac{1}{4} \iiint \varepsilon \left| \vec{E} \right|^2 dv$ 

## **Lorentz-Lorenz Dispersion**

### • We model the oscillating electron and nucleus as a mass and spring

• This electron oscillator model is often called Lorentz model. It is **not really a model for atom as such**, but the way that an atom responds to a **perturbation**. At the time

when Lorentz formulated the model, **it was not known that nuclei have massive mass** as compared to the electrons.

• The Lorentz assumption was that in **absence of applied electric** field the **centroids of positive and negative charges coincide**, but when a **field is applied**, the electrons will experience a **Lorentz force** and will be **displaced from their equilibrium position**.

• He then wrote "the displacement immediately give raise to a new force by which the particle is pulled back toward its original position, and which we may therefore appropriately distinguish by the name of elastic force."



• Once field is applied the electron moves, but we assume nucleus remains stationary



• Spring has a restoring force  $F_{\text{hook}} = -S x$ S =Spring tension coefficient

• There is also **friction within the system:**  $F_{friction} = -D\frac{dx}{dt} = -Dv$ 

### D = **Friction coefficient**

• The friction (damping) is the result of **electron interacting** with other atoms, electrons, lattice potential, defects, vibrational mode of the material, etc.

• Equation of Motion:  

$$m\frac{d^{2}x}{dt^{2}} = \sum_{i} F_{i} = F_{ext} + F_{friction} + F_{hook}$$

$$F_{ext} = \text{External (applied) force} = QE = QE_{0}e^{j\omega t} \text{ (assuming time harmonic fields)}$$

$$F_{hook} = -Sx \text{ (spring or hook force)}$$

$$F_{friction} = -D\frac{dx}{dt} \text{ (friction force) then}$$
•  $m\frac{d^{2}x}{dt^{2}} + D\frac{dx}{dt} + Sx = QE_{0}e^{j\omega t} \Rightarrow \frac{d^{2}x}{dt^{2}} + \frac{D}{m}\frac{dx}{dt} + \frac{S}{m}x = \frac{QE_{0}}{m}e^{j\omega t}$ 

$$\gamma = \frac{D}{m} \qquad \& \qquad \omega_0^2 = \frac{S}{m}$$

$$\frac{d^2 x}{dt^2} + \gamma \frac{dx}{dt} + \omega_0^2 x = \frac{QE_0}{m} e^{j\omega t}$$

$$\frac{QE_0}{m} \text{ is } \frac{\text{force}}{\text{mass}} : \left[ \frac{N}{\text{kg}} = \frac{m}{\text{s}^2} = \text{acceleration} \right]$$

$$\gamma : \left[ \frac{1}{s} = \text{Hertz} \right] \qquad \qquad \omega_0 : \left[ \frac{1}{s} = \text{Hertz} \right]$$
(1)

•  $\frac{d^2x}{dt^2} + \gamma \frac{dx}{dt} + \omega_0^2 x = \frac{QE_0}{m} e^{j\omega t}$  is a second order, linear, non-homogeneous differential equation

• Solution to above consist of two parts: complementary  $(x_c)$  and particular  $(x_p)$  solutions

• Complementary solution, which is the transient response, is the solution of homogeneous differential equation (i.e. the forcing term  $\frac{QE_0}{m}e^{j\omega t}=0$ )

• Complementary solution (transient response)  $\rightarrow 0$  as  $t \rightarrow \infty$ 

• Particular solution, which is the steady state solution, is of interest to us.

• Let us **assume time-harmonic solutions such as**  $x_p = x_0 e^{j\omega t}$  and substitute this in our differential equation  $\Rightarrow$ 

$$-x_0\omega^2 + jx_0\gamma\omega + x_0\omega_0^2 = \frac{QE_0}{m} \Longrightarrow$$
$$x_0 = \frac{QE_0/m}{\omega_0^2 - \omega^2 + j\gamma\omega} \text{ with } \gamma = D/m \text{ and } \omega_0^2 = S/m$$

### **Calculating Permittivity & Susceptibility**

• Recall  $x = x_0 e^{j\omega t} = \frac{QE_0 e^{j\omega t} / m}{\omega_0^2 - \omega^2 + j\gamma\omega} = \frac{QE / m}{\omega_0^2 - \omega^2 + j\gamma\omega}$ , where  $E = E_0 e^{j\omega t}$ 

I) Assume that **dipoles are identical** 

II) Assume no coupling between dipoles

III) There are N dipoles per unit volume. In other words, N is the number of dipoles per unit volume.

• **Polarization** P(t) is given by P(t) = NQx where Q is charge associated with dipole [C]. NQx has dimension of:  $\left[\frac{1}{m^3} \cdot C \cdot m = \frac{C}{m^2}\right]$ 

• Using 
$$P(t) = QNx$$
 we have  $P(t) = \frac{Q^2 NE / m}{\omega_0^2 - \omega^2 + j\gamma\omega} \Rightarrow$ 

• We calculate the ratio 
$$\frac{P}{E} = \frac{Q^2 N / m}{\omega_0^2 - \omega^2 + j\gamma\omega}$$

• Recall 
$$P = \varepsilon_0 \chi_e E \Rightarrow \chi_e = \frac{P}{\varepsilon_0 E} \Rightarrow$$
  
 $\chi_e = \frac{Q^2 N / m \varepsilon_0}{\omega_0^2 - \omega^2 + j \gamma \omega}$ 

• We define 
$$\frac{Q^2 N}{m\varepsilon_0} = \omega_p^2$$
 where  $\omega_p^2$  has the dimension of:  $\left[\frac{1}{s^2}\right]$ 

Then

$$\chi_e = \frac{\omega_p^2}{\omega_0^2 - \omega^2 + j\gamma\omega} \qquad \Rightarrow \qquad \varepsilon_r = 1 + \chi_e = 1 + \frac{\omega_p^2}{\omega_0^2 - \omega^2 + j\gamma\omega}$$

• Compare  $\varepsilon_r$  above with **Jackson** (**3<sup>rd</sup> Edition**) Equation 107

$$\frac{\varepsilon}{\varepsilon_0} = 1 + \frac{\omega_p^2}{\omega_0^2 - \omega^2 - i\gamma\omega}$$

• Real and imaginary parts of  $\varepsilon_r (\varepsilon_r = \varepsilon'_r - j\varepsilon''_r)$  are given by  $\operatorname{Re}[\varepsilon_r] = \varepsilon'_r = \frac{\omega_p^2 (\omega_0^2 - \omega^2)}{(\omega_0^2 - \omega^2)^2 + (\omega\gamma)^2} + 1$   $\operatorname{Im}[\varepsilon_r] = \varepsilon''_r = \frac{\omega_p^2 \omega \gamma}{(\omega_0^2 - \omega^2)^2 + (\omega\gamma)^2}$ 

• Recall that the **displacement of electrons subject to the force**  $QE_0e^{j\omega t}$  was given by  $x = x_0e^{j\omega t} = \frac{QE_0e^{j\omega t} / m}{\omega_0^2 - \omega^2 + j\gamma\omega}$ . Note that the **displacement of electrons from** 

equilibrium is sinusoidal with time at the frequency of the source

• If there is **no damping** (no friction in our mechanical model), i.e.,  $D = 0 \Rightarrow \gamma = 0$  then

$$x = \frac{QE_0 / m}{\omega_0^2 - \omega^2} e^{j\omega t}, \text{ and } \mathcal{E}_r = \frac{\mathcal{E}}{\mathcal{E}_0} = 1 + \frac{\omega_p^2}{\omega_0^2 - \omega^2}$$
(1)

• Note as  $\omega \to \omega_0, x \to \infty$ . The frequency  $\omega = \omega_0$  is called the resonance frequency of the system. This model predicts a catastrophic response at  $\omega = \omega_0$ 

- Note that if there is **no damping** ( $\gamma = 0$ ),  $\varepsilon_r = \varepsilon'_r = 1 + \frac{\omega_p^2}{\omega_0^2 \omega^2}$  and  $\varepsilon''_r = 0$ .
- If resonance frequency is also zero ( $\omega_0 = 0$ , the case of free charges), then

$$\varepsilon_r = \varepsilon'_r = 1 - \frac{\omega_p^2}{\omega^2}$$
, which is **negative** for  $\omega_p > \omega$ .

• While above considerations do not predict losses in the case of free charges ( $\omega_0 = 0$ ), there is in fact conduction losses associated with the free charges. Recall the discussion of static conductivity and its origin.

• When damping is present, the resonance frequency is the root of the characteristic

equation of the homogeneous differential equation  $\frac{d^2x}{dt^2} + \gamma \frac{dx}{dt} + \omega_0^2 x = 0$ , for real frequencies.

• **Resonance frequency** is then given by  $\omega_r = \sqrt{\omega_0^2 - (\gamma/2)^2} = \sqrt{\omega_0^2 - \alpha^2}$  where  $\alpha = \frac{\gamma}{2} = \frac{1}{2} \frac{D}{m}$  and  $\omega_0^2 > \alpha^2$  (case of underdamped) Note: if  $\gamma = 0 \Rightarrow \alpha = 0 \Rightarrow \omega_r = \omega_0$ 

### The case of multiple resonances

• Now, suppose there are *N* molecules per unit volume and each molecule has *Z* electron, and there are  $f_i$  electrons per molecule that have the binding frequency (resonance frequency)  $\omega_i$  and damping constant  $\gamma_i$  then

$$\varepsilon_r = 1 + \frac{Q^2 N}{m\varepsilon_0} \sum \frac{f_i}{\omega_i^2 - \omega^2 + j\gamma_i \omega}, \text{ where}$$
  
$$f_i \equiv \text{Oscillator strength and } \sum f_i = Z$$

## **Wave Equation**

• In the following the **field quantities are instantaneous.** For the moment we assume  $\varepsilon$  and  $\mu$  are constant (WRT frequency).

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} - \vec{\mathcal{M}}_i = -\mu \frac{\partial}{\partial t} \vec{\mathcal{H}} - \vec{\mathcal{M}}_i \tag{1}$$

$$\nabla \times \vec{\mathcal{H}} = \vec{\mathcal{I}}_i + \frac{\partial}{\partial t}\vec{\mathcal{D}} + \vec{\mathcal{I}}_c = \vec{\mathcal{I}}_i + \varepsilon \frac{\partial \vec{\mathcal{E}}}{\partial t} + \sigma_s \vec{\mathcal{E}}$$
(2)

From (1) we have 
$$\nabla \times \nabla \times \vec{E} = -\nabla \times \left(\mu \frac{\partial}{\partial t} \vec{\mathcal{H}}\right) - \nabla \times \vec{\mathcal{M}}_i$$
 (3)

From (2) we have 
$$\nabla \times \nabla \times \vec{\mathcal{H}} = \nabla \times \vec{\mathcal{I}}_i + \nabla \times \varepsilon \frac{\partial}{\partial t} \vec{\mathcal{E}} + \nabla \times \sigma_s \vec{\mathcal{E}}$$
 (4)

- Note that  $\nabla \times \nabla \times \vec{\mathcal{A}} = \nabla (\nabla \cdot \vec{\mathcal{A}}) \nabla^2 \vec{\mathcal{A}}$  where  $\nabla^2 \vec{\mathcal{A}} = \nabla^2 \mathcal{A}_x \hat{a}_x + \nabla^2 \mathcal{A}_y \hat{a}_y + \nabla^2 \mathcal{A}_z \hat{a}_z$  and  $\nabla^2 \mathcal{A}_x = \nabla \cdot (\nabla \mathcal{A}_x)$ . Laplacian is the divergence of gradient
- Then (3) can be written as

$$\nabla \left(\nabla \cdot \vec{E}\right) - \nabla^2 \vec{E} = -\nabla \times \mu \left(\frac{\partial}{\partial t} \vec{\mathcal{H}}\right) - \nabla \times \vec{\mathcal{M}}_i \tag{5}$$

• Suppose that medium is **magnetically homogenous** ( $\mu$  is independent of  $\vec{r}$ ) then  $\nabla \times \mu \left(\frac{\partial}{\partial t} \vec{\mathcal{H}}\right) = \mu \frac{\partial}{\partial t} \nabla \times \vec{\mathcal{H}}$ 

• Use **Ampere Law** [Eq. (2)] for  $\nabla \times \hat{\mathcal{H}}$  in Eq. (5) We have

$$\nabla \left(\nabla \cdot \vec{\mathcal{E}}\right) - \nabla^2 \vec{\mathcal{E}} = -\mu \,\nabla \times \left(\frac{\partial}{\partial t} \vec{\mathcal{H}}\right) - \nabla \times \vec{\mathcal{M}}_i = -\mu \frac{\partial}{\partial t} \left[\vec{\mathcal{I}}_i + \varepsilon \frac{\partial \vec{\mathcal{E}}}{\partial t} + \sigma_s \vec{\mathcal{E}}\right] - \nabla \times \vec{\mathcal{M}}_i$$

Or

$$\nabla^{2} \vec{\mathcal{E}} = \nabla \left( \nabla \cdot \vec{\mathcal{E}} \right) + \mu \frac{\partial}{\partial t} \vec{\mathcal{I}}_{i} + \mu \mathcal{E} \frac{\partial^{2}}{\partial t^{2}} \vec{\mathcal{E}} + \mu \sigma_{s} \frac{\partial}{\partial t} \vec{\mathcal{E}} + \nabla \times \vec{\mathcal{M}}_{i}$$

• From Gauss Law recall  $\nabla \cdot \vec{\mathcal{E}} = \rho_{ev} / \varepsilon$  then

### Wave equation for electric field:

$$\nabla^{2}\vec{E} = \mu \frac{\partial}{\partial t}\vec{J}_{i} + \nabla \times \vec{M}_{i} + \varepsilon \mu \frac{\partial^{2}}{\partial t^{2}}\vec{E} + \mu \sigma_{s}\frac{\partial}{\partial t}\vec{E} + \nabla \left(\frac{\rho_{ev}}{\varepsilon}\right)$$
(6)

• Wave equation for magnetic field:

$$\nabla^{2}\vec{\mathcal{H}} = \varepsilon \frac{\partial}{\partial t}\vec{\mathcal{M}}_{i} + \sigma_{s}\vec{\mathcal{M}}_{i} - \nabla \times \vec{\mathcal{I}}_{i} + \varepsilon \mu \frac{\partial^{2}}{\partial t^{2}}\vec{\mathcal{H}} + \mu\sigma_{s}\frac{\partial\vec{\mathcal{H}}}{\partial t} + \nabla \left(\frac{\rho_{m\nu}}{\mu}\right)$$
(7)

• For source free region  $\vec{\mathcal{M}}_i = \vec{\mathcal{I}}_i = \rho_{ev} = 0$  we have

$$\nabla^2 \vec{E} = \mu \varepsilon \frac{\partial^2}{\partial t^2} \vec{E} + \mu \sigma_s \frac{\partial \vec{E}}{\partial t}$$
(1)

• If conductivity is also zero ( $\sigma_s = 0$ ) then

$$\nabla^2 \vec{\mathcal{E}} = \mu \varepsilon \frac{\partial^2}{\partial t^2} \vec{\mathcal{E}}$$

### • Time harmonic wave equations:

$$\nabla^{2}\vec{E} = j\omega\mu\,\vec{J}_{i} + \nabla \times \vec{M}_{i} - \omega^{2}\varepsilon\mu\vec{E} + j\omega\mu\sigma_{s}\vec{E} + \nabla\left(\frac{\rho_{\rm ev}}{\varepsilon}\right)$$
(2)

$$\nabla^2 \vec{H} = j\omega \varepsilon \vec{M}_i + \sigma_s \vec{M}_i - \nabla \times \vec{J}_i - \omega^2 \varepsilon \mu \vec{H} + j\omega \mu \sigma_s \vec{H} + \nabla \left(\frac{\rho_{\rm mv}}{\mu}\right)$$
(3)

• In the case of **time harmonic fields for source free but lossy medium**, we have  

$$\nabla^{2}\vec{E} = -\mu\varepsilon\omega^{2}\vec{E} + j\omega\mu\sigma_{s}\vec{E} = -\mu(\varepsilon' - j\varepsilon'')\omega^{2}\vec{E} + j\omega\mu\sigma_{s}\vec{E} =$$

$$[-\mu\varepsilon'\omega^{2} + j\omega\mu(\sigma_{s} + \omega\varepsilon'')]\vec{E} = [-\mu\varepsilon'\omega^{2} + j\omega\mu\sigma_{e}]\vec{E}$$
where  $\sigma_{s} + \omega\varepsilon'' = \sigma_{s} + \sigma_{a} = \sigma_{e}$  is the effective conductivity.
(4)

• **Define:**  $\gamma^2 = (\alpha + j\beta)^2 = -\mu\varepsilon'\omega^2 + j\omega\mu\sigma_e$  with  $\alpha$  and  $\beta$  designating the real and imaginary parts of the  $\gamma$ ,  $\gamma = \alpha + j\beta$ , where  $\alpha = \text{Attenuation constant [Np/m]}$  $\beta = \text{Phase constant [rad/m]}$  $\gamma = \text{Propagation constant [1/m]}$  then

 $\nabla^2 \vec{E} = \left[-\mu \varepsilon' \omega^2 + j \omega \mu \sigma_e\right] \vec{E} \quad \Rightarrow \nabla^2 \vec{E} = \gamma^2 \vec{E}$ 

• For lossless case ( $\sigma_e = 0$ ) from Eq. (4) we have

$$\nabla^2 \vec{E} = -\omega^2 \mu \varepsilon' \, \vec{E}$$

• Note for lossless case  $\gamma^2 = (\alpha + j\beta)^2 = j\omega\mu\sigma_e - \mu\epsilon'\omega^2 = -\mu\epsilon'\omega^2$ . Then  $\gamma = \alpha + j\beta = \sqrt{-\mu\epsilon'\omega^2} = j\omega\sqrt{\mu\epsilon'} \rightarrow \alpha = 0$  and  $\beta = \omega\sqrt{\mu\epsilon'}$  in the case of lossless medium.

• Then 
$$\nabla^2 \overline{E} = -\omega^2 \mu \varepsilon' \overline{E} = -\beta^2 \overline{E}$$
 where  
 $\beta^2 = \omega^2 \mu \varepsilon' = \omega^2 \mu_0 \varepsilon_0 \mu_r \varepsilon'_r = \frac{\omega^2}{c} \mu_r \varepsilon'_r = \frac{\omega^2}{c^2} (\sqrt{\mu_r \varepsilon'_r})^2 = \frac{\omega^2}{c^2} n'^2$ , or  $\beta = \frac{\omega}{c} n'$ 

# Solutions to Wave Equation in rectangular Coordinate System

• Wave equation for scalar components of  $\vec{E}$ 

$$\nabla^{2}\vec{E} = -\beta^{2}\vec{E} \Longrightarrow \nabla^{2}E_{x}\hat{a}_{x} + \nabla^{2}E_{y}\hat{a}_{y} + \nabla^{2}E_{z}\hat{a}_{z} = -\beta^{2}\left[E_{x}\hat{a}_{x} + E_{y}\hat{a}_{y} + E_{z}\hat{a}_{z}\right] \Longrightarrow$$

$$\nabla^{2}E_{x} = -\beta^{2}E_{x}$$

$$\nabla^{2}E_{y} = -\beta^{2}E_{y}$$

$$\Rightarrow \text{ with } E_{y} = E_{y}(x, y, z)$$

$$E_{z} = E_{z}(x, y, z)$$

• As an **example the** *x***-components of the electric filed** must satisfy the following:  $\nabla^{2}E_{x}(x, y, z) = -\beta^{2}E_{x}(x, y, z) \Rightarrow$   $\frac{\partial^{2}}{\partial x^{2}}E_{x}(x, y, z) + \frac{\partial^{2}}{\partial y^{2}}E_{x}(x, y, z) + \frac{\partial^{2}}{\partial z^{2}}E_{x}(x, y, z) = -\beta^{2}E_{x}(x, y, z)$ 

The differential equations for other components of the field are similar

• To find the solutions for  $E_x$  we assume  $E_x(x, y, z) = f(x)g(y)h(z)$  and use the separation of variables technique to get

$$\frac{1}{f} \frac{d^2 f(x)}{dx^2} + \frac{1}{g} \frac{d^2 g(y)}{dy^2} + \frac{1}{h} \frac{d^2 h(z)}{dz^2} + \beta^2 = 0 \Rightarrow$$

$$\frac{d^2 f(x)}{dx^2} = -\beta_x^2 f(x),$$

$$\frac{d^2 g(y)}{dy^2} = -\beta_y^2 g(y),$$

$$\frac{d^2 h(z)}{dz^2} = -\beta_z^2 h(z),$$

With  $\beta_x^2 + \beta_y^2 + \beta_z^2 = \beta^2 = \omega^2 \mu \varepsilon' = \frac{\omega^2}{c^2} n'^2$ , which sometime is called the **constraint** equation.

Solutions are

$$\frac{d^2 f(x)}{dx^2} = -\beta_x^2 f(x) \Leftrightarrow \qquad f_1(x) = A_1 e^{-j\beta_x x} + B_1 e^{+j\beta_x x}$$
$$f_2(x) = C_1 \cos(\beta_x x) + D_1 \sin(\beta_x x)$$

$$\frac{d^2g(y)}{dy^2} = -\beta_y^2 g(y) \Leftrightarrow g_1(y) = A_2 e^{-j\beta_y y} + B_2 e^{+j\beta_y y}$$
$$g_2(y) = C_2 \cos(\beta_y y) + D_2 \sin(\beta_y y)$$
$$\frac{d^2h(z)}{dz^2} = -\beta_z^2 h \Leftrightarrow h_1(z) = A_3 e^{-j\beta_z z} + B_3 e^{+j\beta_z z}$$
$$h_2(z) = C_3 \cos(\beta_z z) + D_3 \sin(\beta_z z)$$

- e<sup>±jβ<sub>x</sub>x</sup> are called traveling wave solutions
  cos(β<sub>x</sub>x) or sin(β<sub>x</sub>x) are called standing wave solutions
- The type of **solution chosen** depends on the **problem and the boundary condition**.

• For example, for waves **confined in the** *x*-**and** *y*-**directions** and **traveling a long the** *z*-**direction** we have:

$$E_x(x, y, z) = f(x)g(y)h(z) = [C_1 \cos(\beta_x x) + D_1 \sin(\beta_x x)]. [C_2 \cos(\beta_y y) + D_2 \sin(\beta_y y)]. A_3 e^{-j\beta_z z} + B_3 e^{+j\beta_z z}$$



•  $e^{-j\beta_z z}$  is the **positively traveling** wave and  $e^{+j\beta_z z}$  is the **negatively traveling** wave (for time dependency of  $e^{+j\omega t}$ )

• To see this note the following  $E = \operatorname{Re}\left[E_{x}(x, y, z)e^{j\omega t}\right] = \left[C_{1}\cos(\beta_{x}x) + D_{1}\sin(\beta_{x}x)\right] \cdot \left[C_{2}\cos(\beta_{y}y) + D_{2}\sin(\beta_{y}y)\right]A_{3}\cos(\omega t - \beta_{z}z)$ For our choice of  $e^{-j\beta_{z}z}e^{j\omega t}$ 

• Let's plot  $\cos(\omega t - \beta_z z)$  for different times

• To follow the point  $Z_p$  at different times we must keep  $A_3 \cos(\omega t - \beta_z Z_p)$  constant



 $\Rightarrow$  We must keep the phase  $\omega t - \beta_z Z_p$  constant with time  $\Rightarrow \omega t - \beta_z Z_p$  = constant  $\Rightarrow$ 

$$\frac{d}{dt}(\omega t - \beta_z Z_p) = 0 \Longrightarrow \omega - \beta_z \frac{dZ_p}{dt} = 0 \Longrightarrow \frac{dZ_p}{dt} = \frac{\omega}{\beta_z} = V_p$$

• $V_p = \frac{\omega}{\beta_z}$  is called **phase velocity** 

### Solution to Wave Equation in Source Free but Lossy Medium

• Recall wave equation for lossy medium was given by  

$$\nabla^{2}\vec{E} = \left[-\omega^{2}\varepsilon'\mu + j\omega\mu\sigma_{e}\right]\vec{E} = \gamma^{2}\vec{E}$$
(1)  
where  $\gamma^{2} = -\omega^{2}\varepsilon'\mu + j\omega\mu\sigma_{e} = (\alpha + j\beta)^{2}$ 

• Once again Eq. (1)  $\Rightarrow$   $\nabla^2 E_x(x, y, z) \hat{a}_x + \nabla^2 E_y(x, y, z) \hat{a}_y + \nabla^2 E_z(x, y, z) =$  $\gamma^2 (E_x \hat{a}_x + E_y \hat{a}_y + E_z \hat{a}_z) \Rightarrow \nabla^2 E_x(x, y, z) = \gamma^2 E_x(x, y, z)$  and so forth for  $E_y$  and  $E_z$  • Once again we propose a solution of the form  $E_x(x, y, z) = f(x)g(y)h(z)$  and use separation of variables to show

$$\frac{d^2 f(x)}{dx^2} = +\gamma_x^2 f(x),$$
  

$$\frac{d^2 g(y)}{dy^2} = +\gamma_y^2 g(y),$$
  

$$\frac{d^2 h(z)}{dz^2} = +\gamma_z^2 h(z),$$
  
With  $\gamma_x^2 + \gamma_y^2 + \gamma_z^2 = \gamma^2$  constrained equation

• Then 
$$E_x(x, y, z) = f(x)g(y)h(z)$$
 is given by  
 $f_1(x) = A_1 e^{-\gamma_x x} + B_1 e^{\gamma_x x}$   
 $f_2(x) = C_1 \cosh(\gamma_x x) + D_1 \sinh(\gamma_x x)$   
 $g_1(y) = A_2 e^{-\gamma_y y} + B_2 e^{\gamma_y y}$   
 $g_2(y) = C_1 \cosh(\gamma_y y) + D_2 \sinh(\gamma_y y)$   
 $h_1(z) = A_3 e^{-\gamma_z z} + B_3 e^{\gamma_z z}$   
 $h_2(z) = C_3 \cosh(\gamma_z z) + D_3 \sinh(\gamma_z z)$ 

• Exponential functions represent **attenuated traveling waves** and hyperbolic cosine and sine represent **attenuated standing waves** 

### • Choices for the sign of γ

• Recall we had  $\gamma^2 = (\alpha + j\beta)^2 \Rightarrow \gamma = \pm(\alpha + j\beta)$ . We could have equally defined  $\gamma^2 = (\alpha - j\beta)^2 \Rightarrow \gamma = \pm(\alpha - j\beta)$  then we have **four choice**s:

 $\begin{array}{l} \gamma = \alpha + j\beta \\ \gamma = -\alpha - j\beta \\ \gamma = \alpha - j\beta \\ \gamma = -\alpha + j\beta \end{array}$  which one should we choose

$$\begin{split} \gamma_z &= \alpha_z + j\beta_z \Longrightarrow e^{-\gamma_z z} = e^{-\alpha_z z} e^{-j\beta_z z} \text{ travels along +z-axis, decays along +z-axis} \\ \gamma_z &= -\alpha_z - j\beta_z \Longrightarrow e^{-\gamma_z z} = e^{+\alpha_z z} e^{j\beta_z z} \text{ travels along -z-axis, decays along -z-axis} \\ \gamma_z &= -\alpha_z + j\beta_z \Longrightarrow e^{-\gamma_z z} = e^{+\alpha_z z} e^{-j\beta_z z} \text{ travels along +z-axis, grows along +z-axis} \\ \gamma_z &= \alpha_z - j\beta_z \Longrightarrow e^{-\gamma_z z} = e^{-\alpha_z z} e^{+j\beta_z z} \text{ travels along -z-axis, grows along -z-axis} \end{split}$$

• For a **positively traveling wave** (+z-axis) in a **passive media** (media with no gain or external source of energy), we must have a **wave that decays as it moves further in the media**. Hence, the correct sign for a positively traveling wave in a passive media is

 $\gamma_z = \alpha_z + j\beta_z$  $e^{-\gamma_z z} = e^{-\alpha_z z} e^{-j\beta_z z}$ 

with our choice of time dependency of  $e^{+j\omega t}$ 

### Summary

- **Traveling waves**  $\frac{e^{-j\beta_z z}}{e^{+j\beta_z z}}$  for positive *z* traveling *e*<sup>+j\beta\_z z</sup> for negative *z* traveling
- Standing waves  $\frac{\cos(\beta_z z)$  for positive or negative  $z}{\sin(\beta_x z)}$  for positive or negative z

• Evanescent waves  $e^{-\alpha_z z}$  for positive z  $e^{\alpha_z z}$  for negative z

• Attenuated traveling waves  $e^{-\gamma_z z} = e^{-\alpha_z z} e^{-j\beta_z z} \text{ for positive } z \text{ traveling}$   $e^{\gamma_z z} = e^{\alpha_z z} e^{j\beta_z z} \text{ for negative } z \text{ traveling}$ 

• Attenuated standing waves  $\cos(\gamma_z z) = \cos(\alpha_z z) \cosh(\beta_z z) - j \sin(\alpha_z z) \sinh(\beta_z z)$  for positive and negative z $\sin(\gamma_z z) = \sin(\alpha_z z) \cosh(\beta_z z) + j \cos(\alpha_z z) \sinh(\beta_z z)$  for positive and negative z

• Note that: 
$$\frac{\cos(\gamma_z z) = \cos(\alpha_z z + j\beta_z z) = \cos(\alpha_z z)\cos(j\beta_z z) - \sin(\alpha_z z)\sin(j\beta_z z)}{= \cos(\alpha_z z)\cosh(\beta_z z) - j\sin(\alpha_z z)\sinh(\beta_z z)}$$

### **Wave Equation in Cylindrical Coordinates**

• Previously we solved the wave equation  $\nabla^2 \vec{E} = -\beta^2 \vec{E}$  in rectangular coordinate system for lossless and source free region

• Suppose that **boundary condition** (**the geometrical consideration**) of the problem requires us to solve the wave equation in **cylindrical coordinates**. How do we go about this?

• In cylindrical coordinates  

$$\vec{E} = E_{\rho}(\rho, \phi, z)\hat{a}_{\rho} + E_{\phi}(\rho, \phi, z)\hat{a}_{\phi} + E_{z}(\rho, \phi, z)\hat{a}_{z}$$
• Then  $\nabla^{2}\vec{E} = -\beta^{2}\vec{E} \implies \nabla^{2}\left[E_{\rho}\hat{a}_{\rho} + E_{\phi}\hat{a}_{\phi} + E_{z}\hat{a}_{z}\right] = -\beta^{2}\left(E_{\rho}\hat{a}_{\rho} + E_{\phi}\hat{a}_{\phi} + E_{z}\hat{a}_{z}\right)$ 
• But  
 $\nabla^{2}\left(E_{\rho}\hat{a}_{\rho}\right) \neq \hat{a}_{\rho}\nabla^{2}E_{\rho}$  and  
 $\nabla^{2}\left(E_{z}\hat{a}_{z}\right) = \hat{a}_{z}\nabla^{2}E_{z}$   
• Then how do we solve  $\nabla^{2}\vec{E} = -\beta^{2}\vec{E}$  for  
 $\vec{E} = E_{\rho}\hat{a}_{\rho} + E_{\phi}\hat{a}_{\phi} + E_{z}\hat{a}_{z}$ ? In other words, what is  
 $\nabla^{2}\vec{E}$ ?

*x* ×

• Note that  $\nabla^2 \vec{E} = -\beta^2 \vec{E}$  was obtained by using  $\nabla^2 \vec{E} = \nabla \left( \nabla \cdot \vec{E} \right) - \nabla \times \nabla \times \vec{E}$ 

• Using above in  $\nabla^2 \vec{E} = -\beta^2 \vec{E}$  we have  $\nabla (\nabla \cdot \vec{E}) - \nabla \times \nabla \times \vec{E} = -\beta^2 \vec{E}$  (Wave equation in lossless source free region) Where  $\beta = \omega \sqrt{\mu \varepsilon'} = \frac{\omega}{c} n'$  is a constant

• In cylindrical coordinates

and

$$\nabla \psi (\rho, \phi, z) = \hat{a}_{\rho} \frac{\partial \psi}{\partial \rho} + \hat{a}_{\phi} \frac{1}{\rho} \frac{\partial \psi}{\partial \phi} + \hat{a}_{z} \frac{\partial \psi}{\partial z}$$

 $\nabla \cdot \vec{E} = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left( \rho E_p \right) + \frac{1}{\rho} \frac{\partial}{\partial \phi} E_{\phi} + \frac{\partial}{\partial z} E_z$ 

and

$$\nabla \times \vec{E} = \hat{a}_{\rho} \left[ \frac{1}{\rho} \frac{\partial E_{z}}{\partial \phi} - \frac{\partial E_{\phi}}{\partial z} \right] + \hat{a}_{\phi} \left[ \frac{\partial}{\partial z} E_{\rho} - \frac{\partial}{\partial \rho} E_{z} \right] + \hat{a}_{z} \left[ \frac{1}{\rho} \frac{\partial}{\partial \rho} \left( \rho E_{\phi} \right) - \frac{1}{\rho} \frac{\partial E_{\rho}}{\partial \phi} \right]$$

• The use of  $\nabla \cdot$ ,  $\nabla$  and  $\nabla \times$  in cylindrical coordinate in  $\nabla (\nabla \cdot \vec{E}) - \nabla \times \nabla \times \vec{E} = -\beta^2 \vec{E}$ will result in three partial differential equations:

$$\nabla^2 E_{\rho} + \left( -\frac{E_{\rho}}{\rho^2} - \frac{2}{\rho^2} \frac{\partial E_{\phi}}{\partial \phi} \right) = -\beta^2 E_{\rho}$$

y

$$\nabla^{2} E_{\phi} + \left( -\frac{E_{\phi}}{\rho^{2}} + \frac{2}{\rho^{2}} \frac{\partial E_{\rho}}{\partial \phi} \right) = -\beta^{2} E_{\phi}$$

$$\nabla^{2} E_{z} = -\beta^{2} E_{z}$$
where,
$$\nabla^{2} \psi = \frac{\partial^{2} \psi}{\partial \rho^{2}} + \frac{1}{\rho} \frac{\partial \psi}{\partial \rho} + \frac{1}{\rho^{2}} \frac{\partial^{2} \psi}{\partial \phi^{2}} + \frac{\partial^{2} \psi}{\partial z^{2}}$$
with  $\psi(\rho, \phi, z) \equiv E_{\rho}$ ,  $E_{\phi}$ , or  $E_{z}$ 

• Note that differential equations for  $E_{\rho}$  and  $E_{\phi}$  are coupled partial differential equations while the differential equation for  $E_z$  is not coupled

• The solutions of  $\nabla^2 E_z = -\beta^2 E_z$  are most useful in **constructing TE<sup>z</sup> and TM<sup>z</sup> modes** (TE and TM with respect to WRT *z*-direction) boundary value problems and will be considered here.

• From  $\nabla^2 E_z = -\beta^2 E_z$  and the expression for  $\nabla^2 \psi$  ( $\psi \equiv E_z$ ) we have

$$\frac{\partial^2 \psi}{\partial \rho^2} + \frac{1}{\rho} \frac{\partial \psi}{\partial \rho} + \frac{1}{\rho^2} \frac{\partial^2 \psi}{\partial \phi^2} + \frac{\partial^2 \psi}{\partial z^2} = -\beta^2 \psi \text{ where}$$
(1)  
$$\psi = \psi(\rho, \phi, z)$$
(2)

• Let  $\psi(\rho, \phi, z) = f(\rho)g(\phi)h(z)$ . Substitute (2) in (1) and we have:

$$g(\phi)h(z)\frac{d^{2}}{d\rho^{2}}f(\rho) + \frac{g(\phi)h(z)}{\rho}\frac{d}{d\rho}f(\rho) + \frac{f(\rho)h(z)}{\rho^{2}}\frac{d^{2}g(\phi)}{d\phi^{2}} + f(\rho)g(\phi)\frac{d^{2}h(z)}{dz^{2}} = -\beta f(\rho)g(\phi)h(z)$$

• **Divide both sides by** *fgh* and we get:

$$\frac{1}{f(\rho)}\frac{d^2}{d\rho^2}f(\rho) + \frac{1}{\rho f(\rho)}\frac{df(\rho)}{d\rho} + \frac{1}{\rho^2 g(\phi)}\frac{d^2}{d\phi^2}g(\phi) + \frac{1}{h(z)}\frac{d^2}{dz^2}h(z) = -\beta^2$$
(4)

Where  $\beta^2$  is a constant

• Since  $\frac{1}{h(z)}\frac{d^2}{dz^2}h(z)$ , which is only a function of z, **added to other terms** (which are

functions of  $\rho$  and  $\phi$ ) must equal to a constant  $(-\beta^2)$  for all values of z, we must have

$$\frac{1}{h(z)}\frac{d^2h(z)}{dz^2} = -\beta_z^2, \text{ where } \beta_z^2 \text{ is another constant}$$

• Then, Eq. (4) can be written as

$$\frac{\rho^2}{f(\rho)}\frac{d^2}{d\rho^2}f(\rho) + \frac{\rho}{f(\rho)}\frac{d}{d\rho}f(\rho) + \frac{1}{g(\phi)}\frac{d^2}{d\phi^2}g(\phi) + (\beta^2 - \beta_z^2)\rho^2 = 0$$

• Note that in the above,  $\frac{1}{g(\phi)} \frac{d^2 g(\phi)}{d\phi^2}$ , which is only a function of  $\phi$ , added to other

terms must equal to a constant (0 here), then similar to the previous case we say

$$\frac{1}{g(\phi)} \frac{d^2 g(\phi)}{d\phi^2} = -m^2$$
, where  $m^2$  is a constant

• using the constraint equation we see

$$\frac{\rho^2}{f(\rho)}\frac{d^2}{d\rho^2}f(\rho) + \frac{\rho}{f(\rho)}\frac{d}{d\rho}f(\rho) - m^2 + \left(\beta^2 - \beta_z^2\right)\rho^2 = 0 \quad \Rightarrow$$

• Let us also **define**  $\beta^2 - \beta_z^2 = \beta_{\rho}^2$  (constraint equation for wave equation in cylindrical coordinates)

$$\rho^{2} \frac{d^{2} f(\rho)}{d\rho^{2}} + \rho \frac{d f(\rho)}{d\rho} - m^{2} f(\rho) + \beta_{\rho}^{2} \rho^{2} f(\rho) = 0$$

Where  $\beta_{\rho}^{2}$  and  $m^{2}$  are constant. Above is the classical Bessel Differential Equation.  $\rho^{2} \frac{d^{2} f(\rho)}{d\rho^{2}} + \rho \frac{df(\rho)}{d\rho} + (\beta_{\rho}^{2} \rho^{2} - m^{2})f(\rho) = 0$ 

### Summary

• The solution to  $\nabla^2 \psi = -\beta^2 \psi$  where  $\psi(\rho, \phi, z) \equiv E_z(\rho, \phi, z)$  is given by  $\psi = f(\rho)g(\phi)h(z)$  where  $f(\rho)$ ,  $g(\phi)$ , and h(z) are themselves solutions to

$$\frac{1}{h(z)}\frac{d^2}{dz^2}h(z) = -\beta_z^2 \Leftrightarrow \frac{d^2h(z)}{dz^2} = -\beta_z^2h(z)$$
(1)

$$\frac{1}{g(\phi)}\frac{d^2}{d\phi^2}g(\phi) = -m^2 \Leftrightarrow \frac{d^2g(\phi)}{d\phi^2} = -m^2g(\phi)$$
(2)

$$\rho^{2} \frac{df(\rho)}{d\rho^{2}} + \rho \frac{df(\rho)}{d\rho} + \left(\beta_{\rho}^{2} \rho^{2} - m^{2}\right) f(\rho) = 0$$
(3)

With constraint equation  $\beta_z^2 + \beta_\rho^2 = \beta^2 = \omega^2 \mu \varepsilon$ 

• Solutions to  $\frac{1}{h(z)} \frac{d^2}{dz^2} h(z) = -\beta_z^2 \Leftrightarrow \frac{d^2 h(z)}{dz^2} = -\beta_z^2 h(z)$  are given by Standing wave  $\leftarrow \frac{h_1(z) = A_1 \cos(\beta_z z) + B_1 \sin(\beta_z z)}{B_1 \sin(\beta_z z)}$ or Traveling wave  $\leftarrow \frac{h_2(z) = C_1 e^{-j\beta_z z} + D_1 e^{+j\beta_z z}}{D_1 e^{+j\beta_z z}}$ • Solution to  $\frac{1}{g(\phi)} \frac{d^2}{dz^2} g(\phi) = -m^2 \Leftrightarrow \frac{d^2 g(\phi)}{d\phi^2} = -m^2 g(\phi)$  are given by Standing wave  $\leftarrow g_1(\phi) = A_2 \cos(m\phi) + B_2 \sin(m\phi)$ or Traveling wave  $\leftarrow g_2(\phi) = C_2 e^{-jm\phi} + D_2 e^{+jm\phi}$ • Solution to  $\rho^2 \frac{df(\rho)}{d\rho^2} + \rho \frac{df(\rho)}{d\rho} + (\beta_{\rho}^2 \rho^2 - m^2)f(\rho) = 0$  (Bessel Diff. Eq.) is given by **Traveling wave**  $\leftarrow f_1(\rho) = A_3 H_m^{(1)}(\beta_0 \rho) + B_3 H_m^{(2)}(\beta_0 \rho)$ or Standing wave  $\leftarrow f_2(\rho) = C_3 J_m(\beta_o \rho) + D_3 Y_m(\beta_o \rho)$  $H_m^{(1)}(\beta_{\rho}\rho) \equiv$  Hankel function of the first kind у  $H_m^{(2)}(\beta_{\rho}\rho) \equiv$  Hankel function of the second kind  $J_m(\beta_{\rho}\rho) =$  Bessel function of the first kind  $Y_m(\beta_o \rho) \equiv$  Bessel function of the second kind ø

• The functions  $e^{\pm j \dots}$ ,  $\cos(\dots)$ ,  $\sin(\dots)$ ,  $J_m$ ,  $Y_m$ ,  $H_m^{(1)}$ ,  $H_m^{(2)}$  are all valid solutions. Which one is used in a given problem, depends on the problems at hand (particularly the boundary conditions).



• As an example **consider a metallic cylindrical waveguide.** The solution inside of the guide,  $0 \le \rho < a$  is given by:

$$\psi_{in}(\rho,\phi,z) = f(\rho)g(\phi)h(z)$$
  
=  $[C_3J_m(\beta_\rho\rho) + D_3Y_m(\beta_\rho\rho)] \cdot [A_2\cos(m\phi) + B_2\sin(m\phi)] \cdot [C_1e^{-j\beta_z z} + D_1e^{+j\beta_z z}]$ 

• Note that **inside the guide** the **solution in**  $\rho$  **must be standing waves**, the solution in  $\phi$  must be periodic, and solution in z must be traveling waves.

• Furthermore, since  $Y_m(\beta_\rho \rho)$  is singular at  $\rho = 0$ , then  $D_3 = 0 \Rightarrow \psi_{in} = C_3 J_m(\beta_\rho \rho) [A_2 \cos(m\phi) + B_2 \sin(m\phi)] [C_1 e^{-j\beta_z z} + D_1 e^{+j\beta_z z}]$ 

• If propagating fields outside the guide region ( $\rho > a$ ) are allowed then fields will be **traveling in** z and  $\rho$  and periodic in  $\phi$ :  $\psi_{out}(\rho,\phi,z) = B_3 H_m^{(2)}(\beta_{\rho}\rho) [A_2 \cos(m\phi) + B_2 \sin(m\phi)] [C_1 e^{-j\beta_z z} + D_1 e^{j\beta_z z}]$ Where  $H_m^{(2)}(\beta_{\rho}\rho)$  is **positively traveling wave** 

• Note the following relations for Hankel functions of the first and second kind.

$$H_{m}^{(1)}(\beta_{\rho}\rho) = \sqrt{\frac{2}{\pi\beta_{\rho}\rho}} e^{j\left[\frac{\beta_{\rho}\rho - m\left(\frac{\pi}{2}\right) - \frac{\pi}{4}\right]}{\beta_{\rho}\rho \to \infty}}$$
$$H_{m}^{(2)}(\beta_{\rho}\rho) = \sqrt{\frac{2}{\pi\beta_{\rho}\rho}} e^{-j\left[\frac{\beta_{\rho}\rho - m\left(\frac{\pi}{2}\right) - \frac{\pi}{4}\right]}{\beta_{\rho}\rho \to \infty}}$$

# Fields, Modes, TEM, Plane wave, and Uniform plane waves

• Field is a modification of space-time

• Mode is a particular field configuration for a given boundary value problem. Many field configurations can satisfy Maxwell equations (wave equation). These usually are referred to as modes. Mode is a self-consistent field distribution.

• In **TEM mode**,  $\vec{E}$  and  $\vec{H}$  at every point in space are constrained in a local plane, independent of time. This plane is called equiphase Plane. In general equiphase planes are not parallel at two different points along the trajectory of the wave

• If equiphase planes are parallel (i.e. the space orientation of the planes for TEM mode



Phase Front of TEM wave

are the same), then we say we have a plane wave. In other words, the equiphase surfaces are parallel planar surfaces

• If in addition to parallel planar equiphase surfaces, the field has equiamplitude planar surfaces (the amplitude is the same over each plane), we say we have a uniform plane wave. In this case field is not a function of the coordinates that make up equiamplitude and equiphase planes

<sup>•</sup> We mentioned wave trajectory, what do we mean by wave trajectory



• Consider the following **plane wave**:  $\vec{E} = \vec{E}_0 e^{-j\vec{k}\cdot\vec{r}+j\omega t}$  when  $\vec{E}_0$  is a constant and  $\vec{k} = \vec{\beta}$ 

• Since  $\nabla \cdot \vec{D} = 0$  for source free region  $\Rightarrow \nabla \cdot \vec{E} = 0$  then  $\nabla \cdot \vec{E} = \nabla \cdot \left(\vec{E}_0 e^{-j\vec{k}\cdot\vec{r}+j\omega t}\right) = 0$ Recall  $\nabla \cdot \left(f \ \vec{F}\right) = f \ \nabla \cdot \vec{F} + \vec{F} \cdot \nabla f$ Then  $\nabla \cdot \vec{E} = e^{-j\vec{k}\cdot\vec{r}+j\omega t} \nabla \cdot \vec{E}_0 + \vec{E}_0 \cdot \nabla \left[e^{-j\vec{k}\cdot\vec{r}+j\omega t}\right] = 0$ , but  $\nabla \cdot \vec{E}_0 = 0$  $-j\vec{k} \cdot \vec{E}_0 e^{-j\vec{k}\cdot\vec{r}+j\omega t} = 0 \Rightarrow \vec{k} \cdot \vec{E} = 0$ 

• Using  $\nabla \cdot \vec{H} = 0$  we can also show  $\vec{k} \cdot \vec{H} = 0$ 

• It can also be shown (HW)  $\vec{k} \times \vec{E} = \omega \mu \vec{H}$  and  $\vec{k} \times \vec{H} = -\varepsilon \omega \vec{E}$ 



• Let's assume there are situations for which  $\varepsilon$  and  $\mu$  are both negative  $\varepsilon \rightarrow -|\varepsilon|$  and  $\mu \rightarrow -|\mu|$  then  $\vec{k} \cdot \vec{E} = 0$   $\vec{k} \cdot \vec{H} = 0$   $\vec{k} \times \vec{E} = -\omega |\mu| \vec{H}$   $\vec{k} \times \vec{H} = +|\varepsilon| \omega \vec{E}$   $\langle \vec{s} \rangle \propto \vec{E} \times \vec{H}$   $\vec{H}$   $\vec{K} \leftarrow \vec{H} = 0$   $\vec{k} \leftarrow \vec{F} = -\omega |\mu| \vec{H}$   $\vec{k} \leftarrow \vec{F} = -\omega |\mu| \vec{H}$  $\vec{H}$ 

## Relation between $\vec{E}$ and $\vec{H}$ for plane waves

• From 
$$\vec{k} \times \vec{E} = \omega \mu \ \vec{H} \Longrightarrow k \ \hat{a}_k \times \vec{E} = \omega \mu \ \vec{H} \Longrightarrow \vec{H} = \frac{k}{\omega \mu} \hat{a}_k \times \vec{E}$$

where  $\hat{a}_k$  is the **unit vector along**  $\vec{k}$ .

• With  $k = \frac{\omega}{c}n = \omega\sqrt{\mu_0\varepsilon_0}\sqrt{\mu_r}\sqrt{\varepsilon_r}$  Expression for  $\vec{H}$  can be written as  $\vec{H} = \frac{\omega\sqrt{\mu_0\varepsilon_0}\sqrt{\mu_r\varepsilon_r}}{\omega\mu_r\mu_0}\hat{a}_k \times \vec{E} \Rightarrow \vec{H} = \frac{\sqrt{\varepsilon_0\varepsilon_r}}{\sqrt{\mu_0\mu_r}}\hat{a}_k \times \vec{E} = \frac{\hat{a}_k \times \vec{E}}{\sqrt{\mu/\varepsilon}} = \frac{\hat{a}_k \times \vec{E}}{\eta}$  where  $\eta = \sqrt{\mu/\varepsilon}$  is the medium intrinsic impedance and we can define

 $\eta_0 = \sqrt{\mu_0 / \varepsilon_0} = 120\pi = 377 [\Omega]$  as the free space intrinsic impedance.

• Similar expression for  $\vec{E}$  in terms of  $\vec{H}$  can be found to be  $\vec{E} = -\eta \ \hat{a}_k \times \vec{H}$ 



### **Fresnel Reflection & Transmission Coefficients**

- The case of  $\vec{E}$  **Perpendicular Polarization:**
- The interface is in *xy* plane
- Plane of incidence is *xz* plane
- Incident waves are  $\vec{E}_i, \vec{H}_i, \vec{K}_1$
- Reflected waves are  $\vec{E}_r, \vec{H}_r, \vec{K}_1'$
- Transmitted waves are  $\vec{E}_t, \vec{H}_t, \vec{K}_2$
- $\theta_1 \equiv$  Angle of incidence,  $\theta'_1 \equiv$  Reflection angle  $\theta_2 \equiv$  Transmitted angle

• As stated earlier this geometry is for  $E \perp (\bar{E}$  perpendicular to the plane of incidence). This configuration sometimes is called TE or  $\sigma$  polarization



• 
$$\vec{E}_i = E_0 e^{-j\vec{k}_1 \cdot \vec{r}} e^{+j\omega t} \hat{a}_y$$
 where  $\vec{k}_1 = k_{1x} \hat{a}_x + k_{1z} \hat{a}_z$  with  
 $k_{1x} = k_1 \sin \theta_1 = \frac{\omega}{c} n_1 \sin \theta_1$  and  $k_{1z} = k_1 \cos \theta_1 = \frac{\omega}{c} n_1 \cos \theta_1$  and  $k_1 = \frac{\omega}{c} n_1 = \frac{\omega}{c} \sqrt{\mu_1 \varepsilon_1}$ .  
Then  $\vec{k}_1 = k_1 (\sin \theta_1 \hat{a}_x + \cos \theta_1 \hat{a}_z)$  and we have  $\vec{E}_i = E_0 e^{-jk_1 (\sin \theta_1 x + \cos \theta_1 z)} e^{j\omega t} \hat{a}_y$ 

Note also that

$$k_{1x}^{2} + k_{1z}^{2} = k_{1}^{2} \Longrightarrow k_{1z} = \sqrt{k_{1}^{2} - k_{1x}^{2}} = \sqrt{\frac{\omega^{2}}{c^{2}}} n_{1}^{2} - \frac{\omega^{2}}{c^{2}} n_{1}^{2} \sin \theta_{1}^{2} = \frac{\omega}{c} n_{1} \sqrt{1 - \sin^{2} \theta_{1}} = \frac{\omega}{c} n_{1} \cos \theta_{1}$$

• From 
$$\vec{H}_i = \frac{\hat{a}_{ki} \times \vec{E}_i}{\eta_1}$$
 we have  $\vec{H}_i = \frac{E_0}{\eta_1} \left( -\hat{a}_x \cos \theta_1 + \sin \theta_1 \hat{a}_z \right) e^{-jk_1 (\sin \theta_1 x + \cos \theta_1 z)} e^{j\omega_1 x + \cos \theta_1 z}$ 

#### • For Reflected wave we have

$$\vec{E}_{r} = rE_{0}e^{-jk_{1}'\vec{r}}e^{j\omega t}\hat{a}_{y} \text{ with } |\vec{k}_{1}'| = k_{1}' = \frac{\omega}{c}\sqrt{\mu_{1}\varepsilon_{1}} = \frac{\omega}{c}n = |\vec{k}_{1}| = k_{1} \Rightarrow k_{1}' = k_{1}$$

$$k_{1}' = -k_{1}'\cos\theta_{1}'\hat{a}_{z} + k_{1}'\sin\theta_{1}'\hat{a}_{x} \text{ since } k_{1}' = k_{1} \text{ then } k_{1}' = -k_{1}\cos\theta_{1}'\hat{a}_{z} + k_{1}\sin\theta_{1}'\hat{a}_{x}$$
The reflected  $\vec{E}$  and  $\vec{H}$  are then
$$\vec{E}_{r} = rE_{0}\exp\left[-jk_{1}(\sin\theta_{1}'x - \cos\theta_{1}'z)\right]\exp\left[j\omega t\right]\hat{a}_{y}$$

$$\vec{H}_{r} = \frac{rE_{0}}{\eta_{1}}\left[\cos\theta_{1}'\hat{a}_{x} + \sin\theta_{1}'\hat{a}_{z}\right]\exp\left[-jk_{1}(\sin\theta_{1}'x - \cos\theta_{1}'z)\right]\exp\left[j\omega t\right]$$



• We now apply the B.C. at xy plane and z = 0, requiring tangential  $\vec{E}$  and  $\vec{H}$  to be continuous (two good dielectric)

$$(E_i + E_r)_{\text{tangential}} = (E_t)_{\text{tangential}} (H_i + H_r)_{\text{tangential}} = (H_t)_{\text{tangential}}$$

• Note that **tangential components are along** x and y  $E_0 e^{-jk_1 \sin \theta_1 x} + rE_0 e^{-jk_1 \sin \theta_1' x} = tE_0 e^{-jk_2 \sin \theta_2 x}$   $-\frac{E_0}{\eta_1} \cos \theta_1 e^{-jk_1 \sin \theta_1 x} + \frac{rE_0}{\eta_1} \cos \theta_1' e^{-jk_1 \sin \theta_1' x} = -\frac{tE_0}{\eta_2} \cos \theta_2 e^{-jk_2 \sin \theta_2 x}$  Ζ.

• The above two equations must be valid for any *x* then

$$\theta_1 = \theta_1'$$
  
$$k_1 \sin \theta_1 = k_2 \sin \theta_2$$

•  $\theta_1 = \theta_1'$  is the first Snell's law of refraction (i.e. the incident & reflected angles are equal)

Second Snell's Law of Refraction

 $k_1 \sin \theta_1 = k_2 \sin \theta_2 \Leftrightarrow k_{1x} = k_{2x} \Leftrightarrow \frac{\omega}{c} n_1 \sin \theta_1 = \frac{\omega}{c} n_2 \sin \theta_2 \Longrightarrow n_1 \sin \theta_1 = n_2 \sin \theta_2$ 

This says that **tangential component of the propagation vector across the interface is continuous.** 



• Using 
$$\eta = \sqrt{\mu/\varepsilon}$$
 and **multiplying top and bottom** by  $\sqrt{\varepsilon_1 \varepsilon_2 \mu_1 \mu_2}$  we have  

$$r = \frac{\sqrt{\mu_2/\varepsilon_2} \cos\theta_1 - \sqrt{\mu_1/\varepsilon_1} \cos\theta_2}{\sqrt{\mu_2/\varepsilon_2} \cos\theta_1 + \sqrt{\mu_1/\varepsilon_1} \cos\theta_2} = \frac{\sqrt{\varepsilon_1 \mu_1} \mu_2 \cos\theta_1 - \sqrt{\mu_2 \varepsilon_2} \mu_1 \cos\theta_2}{\sqrt{\varepsilon_1 \mu_1} \mu_2 \cos\theta_1 + \sqrt{\mu_2 \varepsilon_2} \mu_1 \cos\theta_2}$$

$$= \frac{\frac{\omega}{c} \sqrt{\varepsilon_1 \mu_1} \mu_2 \cos\theta_1 - \frac{\omega}{c} \sqrt{\varepsilon_2 \mu_2} \mu_1 \cos\theta_2}{\frac{\omega}{c} \sqrt{\varepsilon_1 \mu_1} \mu_2 \cos\theta_1 + \frac{\omega}{c} \sqrt{\varepsilon_2 \mu_2} \mu_1 \cos\theta_2}$$
• Recall

$$k_{1z} = k_1 \cos \theta_1 = \frac{\omega}{c} n_1 \cos \theta_1 = \frac{\omega}{c} \sqrt{\mu_1 \varepsilon_1} \cos \theta_1$$
$$k_{2z} = k_2 \cos \theta_2 = \frac{\omega}{c} n_2 \cos \theta_2 = \frac{\omega}{c} \sqrt{\mu_2 \varepsilon_2} \cos \theta_2$$

• Hence  

$$r = \frac{\mu_2 k_{1z} - \mu_1 k_{2z}}{\mu_2 k_{1z} + \mu_1 k_{2z}}$$
(1)  
and similarly  

$$t = \frac{2\mu_2 k_{1z}}{\mu_2 k_{1z} + \mu_1 k_{2z}}$$
(2)

• Note that (1) and (2) are reflection and transmission coefficient (Fresnel field coefficients) for TE or  $\vec{E}_{\perp}$  polarization.

## **Two Interface Problem**

• We consider **TE** or  $\vec{E}$  perpendicular polarization. The Fresnel reflection coefficients at each interface can be written as:

$$r_{12} = \frac{\mu_2 k_{1z} - \mu_1 k_{2z}}{\mu_2 k_{1z} + \mu_1 k_{2z}}$$

$$t_{12} = \frac{2\mu_2 k_{1z}}{\mu_2 k_{1z} + \mu_1 k_{2z}}$$

$$r_{23} = \frac{\mu_3 k_{2z} - \mu_2 k_{3z}}{\mu_3 k_{2z} + \mu_2 k_{3z}} \qquad 1 \to 2$$

$$r_{21} = \frac{\mu_1 k_{2z} - \mu_2 k_{1z}}{\mu_1 k_{2z} + \mu_2 k_{1z}} = -r_{12} \qquad 2 \to 3$$

$$t_{23} = \frac{2\mu_3 k_{2z}}{\mu_3 k_{2z} + \mu_2 k_{3z}} \qquad 1 \to 2$$

$$2 \to 3$$

• At 
$$z = 0$$
  
(1)  $rA = r_{12}A + t_{21}D$   
(2)  $C = t_{12}A + r_{21}D$ 

• At 
$$z = d$$
 (slab thickness is  $d$ )  
(3)  $At = t_{23}Ce^{-jk_{2z}d}$   
(4)  $De^{jk_{2z}d} = r_{23}Ce^{-jk_{2z}d} \Rightarrow$   
(5)  $D = r_{23}Ce^{-2jk_{2z}d} = r_{23}Ce^{+2j\phi}$  where  
(6)  $\phi = -k_{2z}d = -\frac{\omega}{c}n_2\cos\theta_2d$ 

3 (1)(2) $\mu_1, \mathcal{E}_1$  $\mu_2, \varepsilon_2$  $\mu_3, \varepsilon_3$  $k_{3z}$  $k_{2z}$  $k_{1z}$ **▶** Z  $\odot_y$ х • y Z. (2)(3)(1) $\mu_1, \mathcal{E}_1$  $\mu_2, \mathcal{E}_2$  $\mu_3, \varepsilon_3$  $k_{17}$  $k_{2z}$  $k_{3z}$  $\xrightarrow{Ate^{-jk_{3z}(z-d)}}$ z = d

• Use (5) in (2) then

(1) 
$$C = t_{12}A + r_{21}r_{23}Ce^{+2j\phi} \Longrightarrow$$
  
(2)  $C = \frac{t_{12}}{1 - r_{21}r_{23}e^{+2j\phi}}A$ 

• Using (2) in  $At = t_{23}Ce^{-jk_{22}d} = t_{23}Ce^{j\phi}$  (Eq. 3-page 55), we have

$$At = t_{23}e^{+j\phi}\frac{t_{12}}{1 - r_{21}r_{23}e^{+2j\phi}}A \implies t^{\text{TE}} = t = \frac{t_{12}t_{23}e^{+j\phi}}{1 - r_{21}r_{23}e^{+2j\phi}}$$
(1)

• In a similar manner (HW) we can show

$$r^{\rm TE} = r = r_{12} + \frac{t_{12}t_{21}r_{23}e^{+2j\phi}}{1 - r_{21}r_{23}e^{+2j\phi}}$$
(2)

• Note if medium 1 and 3 are the same then  $r_{21} = r_{23} = \frac{\mu_1 k_{2z} - \mu_2 k_{1z}}{\mu_1 k_{2z} - \mu_2 k_{1z}} = -r_{12}$  and

$$\mu_1 \kappa_{2z} + \mu_2 \kappa_{1z}$$

Then (1) and (2) can be written as

Then 
$$t^{\text{TE}} = \frac{t_{12}t_{21}e^{+j\psi}}{1 - (r_{21})^2 e^{+2j\psi}}$$
  
 $r^{\text{TE}} = r_{12} + \frac{t_{12}t_{21}r_{21}e^{+2j\psi}}{1 - (r_{21})^2 e^{+2j\psi}}$   
 $\phi = -k_{2z}d = -\frac{\omega}{c}n_2\cos\theta_2d$ 

• From the expression for  $r^{\text{TE}}$  we see that if  $r_{12} = r_{21} = 0$ , then  $r^{\text{TE}} = 0$ ; i.e. there is no reflection from the slab. This is called the matched condition.

• Recall 
$$r_{21} = \frac{\mu_1 k_{2z} - \mu_2 k_{1z}}{\mu_1 k_{2z} + \mu_2 k_{1z}} = -r_{12}$$
, then  $r_{12} = r_{21} = 0$  if  
 $\mu_1 k_{2z} = \mu_2 k_{1z} \Longrightarrow \mu_1 \frac{\omega}{c} n_2 \cos \theta_2 = \mu_2 \frac{\omega}{c} n_1 \cos \theta_1 \Longrightarrow$   
 $\mu_1 \sqrt{\mu_2 \varepsilon_2} \cos \theta_2 = \mu_2 \sqrt{\mu_1 \varepsilon_1} \cos \theta_1 \Longrightarrow \eta_1 \cos \theta_2 = \eta_2 \cos \theta_1$ 

• What happens to  $t^{\text{TE}}$  (transmission coefficient) under matched condition.



• Note that with  $r_{12} = r_{21} = 0 \Longrightarrow t^{\text{TE}} = \frac{t_{12}t_{21}e^{+j\phi}}{1 - (r_{21})^2e^{+2j\phi}} = t_{12}t_{21}e^{+j\phi}$ . Recall that

 $t_{12} = \frac{2\mu_2 k_{1z}}{\mu_2 k_{1z} + \mu_1 k_{2z}}$  and  $t_{21} = \frac{2\mu_1 k_{2z}}{\mu_1 k_{2z} + \mu_2 k_{1z}}$ . Hence under matched condition (  $\mu_1 k_{2z} = \mu_2 k_{1z}$ ) we have  $t_{12} = t_{21} = 1$ , which then implies  $t^{\text{TE}} = t_{12} t_{21} e^{+j\phi} = e^{+j\phi} = e^{-jk_2z^d}$  and  $r^{\text{TE}} = 0$ . This says that under matched condition the slab only inserts a phase on the traveling wave.

• At normal incidence  $\theta_1 = \theta_2 = 0$ , the matching condition (no reflection from the slab) given by  $\eta_1 \cos \theta_2 = \eta_2 \cos \theta_1$  will simplify to  $\eta_1 = \eta_2$ .

• Note that **under matched condition with**  $t^{\text{TE}} = e^{+j\phi} = e^{-jk_{2z}d}$  we can write  $-\frac{\partial\phi}{\partial\omega} = \frac{\partial}{\partial\omega} [k_{2z}d] = d\frac{\partial k_{2z}}{\partial\omega} = \frac{d}{\partial\omega/\partial k_{2z}} = \frac{d}{v_g} \Rightarrow v_g = \frac{d}{-\partial\phi/\partial\omega}$ , where we will later see

 $-\partial \phi / \partial \omega$  is called the group delay.

## • Final Remarks: you should study (self study) topics such as critical and Brewster angles.