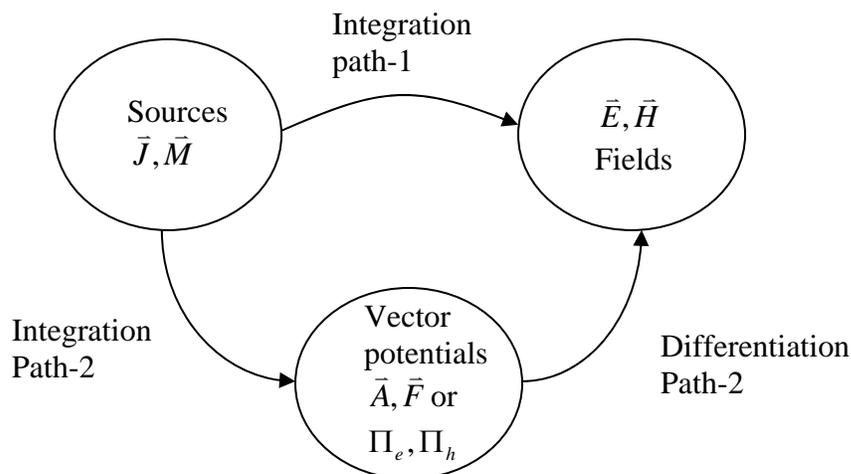


## Auxiliary Vector Potential

### Constructing solutions using auxiliary vector potentials

- The objective of EM theory is to **find possible EM field configurations (modes) for a given boundary value problem involving wave propagation, radiation, scattering, or absorption.**
- This can be done by **finding the electric and magnetic fields ( $\vec{E}$  and  $\vec{H}$ ) or equally obtaining the auxiliary vector potentials ( $\vec{A}$  and  $\vec{F}$ )**
- **In addition to auxiliary vector potentials  $\vec{A}$  and  $\vec{F}$  there are other possible set. For example, Hertz vector potentials ( $\Pi_e$  and  $\Pi_h$ ).** Here, we only concentrate on  $\vec{A}$  and  $\vec{F}$
- The **path for solving EM field configuration** is then as follows



- Depending on the problem at hand, **path-2 maybe easier than path-1**
- Traditionally  $\vec{E}$  and  $\vec{B}$  are viewed as **physical field quantities**, whereas **vector potential ( $\vec{A}$ ) and its scalar counter part ( $\phi_e$ ) are considered as mathematical constructs.** However, there are diverging views on this point!!!
- It is interesting to note that **Maxwell himself derived many of his results by using the concept of vector potential ( $\vec{A}$ ) which he called “electromagnetic momentum.”** However this approach was later criticized by other practitioners such as Hertz and Heaviside.

The question of the propagation of, not merely the electric potential  $\Psi$  but the vector potential  $\vec{A}$  ... when brought forward, **prove to be one of a metaphysical nature ... the electric force  $\vec{E}$  and the magnetic force  $\vec{H}$  ... actually represent the state of the medium everywhere.** Heaviside, *Philosophical Magazine*, 1889.

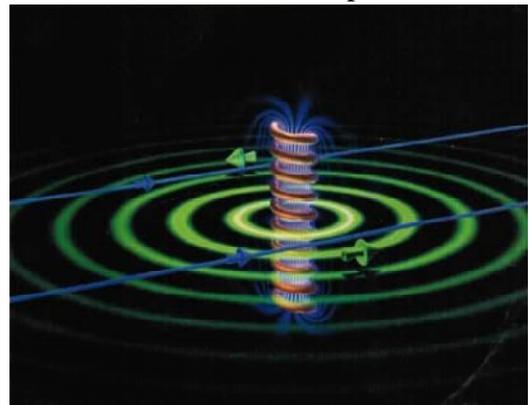
- Here is what **Hertz says about Maxwell's approach:**

I may mention the predominance of the vector potential in [Maxwell's] fundamental equations. **In the construction of new theory the potential served as a scaffolding ... it does not appear to me that any ... advantage is attained by the introduction of the vector potential in the fundamental equations.** C. A. Mead, *Collective electrodynamics*, 2000.

- Here is different (more modern) point of view:

... the **vector potential** which appears in quantum mechanics in an explicit form **produces a classical force which depends only on its derivatives.** In quantum mechanics what matters is the interference between nearby paths; it always turns out that the **effects depend only on how much the field  $\vec{A}$  changes from point to point, and therefore only on the derivatives of  $\vec{A}$  and not on the value itself.** Nevertheless, the vector potential  $\vec{A}$  (together with the scalar potential  $\phi$  that goes with it) **appears to give the most direct description of the physics.** This becomes more and more apparent the more deeply we go into the quantum theory. In the general theory of **quantum electrodynamics**, one takes the **vector and scalar potentials as the fundamental quantities in a set of equations that replace the Maxwell equations:  $\vec{E}$  and  $\vec{B}$  are slowly disappearing from the modern expression of physical laws, they are being replaced by  $\vec{A}$  and  $\phi$ .** Feynman, Leighton, and Sands, *Lectures on Physics, Vol. II*, 1984.

- **Aharonov-Bohm Effects:** What happens to an electron as it passes by an infinitely long solenoid. The  $\vec{E}$  and  $\vec{B}$  are zero outside the solenoid's core but  $\vec{A} \neq 0$ . Despite the fact that there are no EM forces outside of the solenoid, electron will experience the presence of  $\vec{A}$  and its phase will be modified. For the figure shown,  $\vec{A}$  will introduce a phase shift in the electrons' wave functions which can be detected by interfering the electrons.



## Equations governing vector potential $\vec{A}$

• Since  $\nabla \cdot \vec{B} = 0 \Rightarrow$  (1)

$$\vec{B}_A = \nabla \times \vec{A} \quad \text{and} \quad (2)$$

$$\vec{H}_A = \frac{1}{\mu} \nabla \times \vec{A} \quad (3)$$

**Subscript A** is to remind us that  $\vec{B}_A$  and  $\vec{H}_A$  are due to vector potential A

• For  $\vec{M} = 0$  (no magnetic source)

$$\nabla \times \vec{E}_A = -j\omega\mu \vec{H}_A \quad (\text{Faraday's Law}) \quad (4)$$

• Use (3) in (4)  $\Rightarrow$

$$\nabla \times \vec{E}_A = -j\omega\mu \left( \frac{1}{\mu} \nabla \times \vec{A} \right) \Rightarrow \nabla \times (\vec{E}_A + j\omega \vec{A}) = 0 \quad (5)$$

• Since **curl of gradient of any scalar is zero**, i.e.,  $\nabla \times (-\nabla \phi_e) = 0$ , then **from (5)** we have  $\vec{E}_A + j\omega \vec{A} = -\nabla \phi_e \Rightarrow \vec{E}_A = -j\omega \vec{A} - \nabla \phi_e$  where (6)

$\phi_e \equiv$  **Scalar potential**

$\vec{A} \equiv$  **Vector potential**

• **Equations (6) and (3) are the expression for  $\vec{E}$  and  $\vec{H}$  in terms of  $\vec{A}$  and  $\phi_e$**

• **We now want to find differential equations governing the behaviors of  $\vec{A}$  and  $\phi_e$**

• We note that **from  $\vec{H}_A = \frac{1}{\mu} \nabla \times \vec{A}$ , for a homogeneous medium we can write**

$$\mu \nabla \times \vec{H}_A = \nabla \times \nabla \times \vec{A} \Rightarrow \mu \nabla \times \vec{H}_A = \nabla(\nabla \cdot \vec{A}) - \nabla^2 \vec{A} \quad (7)$$

• **Using Ampere's Law  $\nabla \times \vec{H}_A = \vec{J} + j\omega\epsilon \vec{E}_A$  in (7) we have**

$$\mu \vec{J} + j\omega\epsilon\mu \vec{E}_A = \nabla(\nabla \cdot \vec{A}) - \nabla^2 \vec{A} \quad (8)$$

• **Previously we found the expression for  $\vec{E}_A$  to be  $\vec{E}_A = -j\omega \vec{A} - \nabla \phi_e$ . Using this in (8) we have**

$$\mu \vec{J} + j\omega\epsilon\mu [-j\omega \vec{A} - \nabla \phi_e] = \nabla(\nabla \cdot \vec{A}) - \nabla^2 \vec{A} \quad (9)$$

• Recall that  $\omega^2 \mu\epsilon = \beta^2$  then (9) can be written as

$$\nabla^2 \vec{A} + \beta^2 \vec{A} = \nabla(\nabla \cdot \vec{A} + j\omega\epsilon\mu \phi_e) - \mu \vec{J}$$

• **We have defined the curl of  $\vec{A}$  as  $\vec{B}_A = \nabla \times \vec{A}$ , we are at liberty to define the  $\nabla \cdot \vec{A}$ .**

• In light of  $\nabla^2 \bar{A} + \beta^2 \bar{A} = \nabla(\nabla \cdot \bar{A} + j\omega\epsilon\mu\phi_e) - \mu\bar{J}$  (1)

let us define the divergence of  $\bar{A}$  to be

$$\nabla \cdot \bar{A} = -j\omega\epsilon\mu\phi_e \quad (2)$$

• Using (2) in (1) we have

$$\nabla^2 \bar{A} + \beta^2 \bar{A} = -\mu\bar{J} \quad \text{and} \quad (3)$$

$$\phi_e = -\frac{1}{j\omega\epsilon\mu} \nabla \cdot \bar{A} \quad (4)$$

• Finally, our expressions for  $\bar{E}_A$  and  $\bar{H}_A$  in the last page [Eqs. (6) and (3)] can be written as

$$\bar{E}_A = -\nabla\phi_e - j\omega\bar{A} = \frac{-j}{\omega\mu\epsilon} \nabla(\nabla \cdot \bar{A}) - j\omega\bar{A} \quad (5)$$

$$\bar{H}_A = \frac{1}{\mu} \nabla \times \bar{A} \quad (6)$$

• Now, equations (5) and (6) are expressions for  $\bar{E}_A$  and  $\bar{H}_A$  in terms of  $\bar{A}$  only subject to Lorentz gauge.

## Equations governing the vector potential $\bar{F}$

• Consider a region of space free of charges, i.e.  $q_{\text{ave}} = 0$ , then

$$\nabla \cdot \bar{D} = 0 \Rightarrow \quad (1)$$

$$\bar{D}_F = -\nabla \times \bar{F} \Rightarrow \quad (2)$$

$$\bar{E}_F = -\frac{1}{\epsilon} \nabla \times \bar{F} \quad (3)$$

Subscript  $F$  is to remind us  $\bar{D}_F$  is due to vector potential  $\bar{F}$

• Recall that Ampere's Law with  $\bar{J} = 0$ , is given by

$$\nabla \times \bar{H}_F = j\omega\epsilon\bar{E}_F \Rightarrow \frac{1}{j\omega\epsilon} \nabla \times \bar{H}_F = \bar{E}_F \quad (4)$$

• Use (4) in (3) and we have

$$\frac{1}{j\omega\epsilon} \nabla \times \bar{H}_F = -\frac{1}{\epsilon} \nabla \times \bar{F} \Rightarrow \nabla \times \bar{H}_F = -j\omega \nabla \times \bar{F} \Rightarrow \nabla \times (\bar{H}_F + j\omega\bar{F}) = 0 \quad (5)$$

• Compare  $\nabla \times (\bar{H}_F + j\omega\bar{F}) = 0$  with null identity  $\nabla \times (-\nabla\phi_m) = 0$ , then it is clear that

$$\begin{aligned}\vec{H}_F + j\omega\vec{F} &= -\nabla\phi_m \Rightarrow \\ \vec{H}_F &= -j\omega\vec{F} - \nabla\phi_m\end{aligned}\quad (1)$$

• **For homogenous media, from**  $\vec{E}_F = -\frac{1}{\varepsilon}\nabla\times\vec{F}$  **we have**  $\nabla\times\vec{E}_F = -\frac{1}{\varepsilon}\nabla\times\nabla\times\vec{F} \Rightarrow$

$$\nabla\times\vec{E}_F = -\frac{1}{\varepsilon}\nabla(\nabla\cdot\vec{F}) + \frac{1}{\varepsilon}\nabla^2\vec{F}\quad (2)$$

• **From Faraday's Law we have**

$$\nabla\times\vec{E}_F = -\vec{M} - j\omega\mu\vec{H}_F, \quad (3)$$

then **substitute (3) in (2)**

$$-\vec{M} - j\omega\mu\vec{H}_F = -\frac{1}{\varepsilon}\nabla(\nabla\cdot\vec{F}) + \frac{1}{\varepsilon}\nabla^2\vec{F}\quad (4)$$

• **But we already found an expression for**  $\vec{H}_F$  **in (1). Use (1) in (4), and we have**

$$\beta^2\vec{F} + \nabla^2\vec{F} = -\varepsilon\vec{M} + \nabla(\nabla\cdot\vec{F} + j\omega\mu\varepsilon\phi_m)\quad (5)$$

Where again  $\beta^2 = \omega^2\mu\varepsilon$

• **Once again curl of**  $\vec{F}$  **is defined by**  $\vec{D}_F = -\nabla\times\vec{F}$ . **We are at liberty to choose the divergence of**  $\vec{F}$ . **Let**

$$\nabla\cdot\vec{F} = -j\omega\mu\varepsilon\phi_m \Rightarrow \quad (6)$$

$$\phi_m = \frac{-1}{j\omega\varepsilon\mu}\nabla\cdot\vec{F}\quad (7)$$

• **Using (6), (5) simplifies to**

$$\nabla^2\vec{F} + \beta^2\vec{F} = -\varepsilon\vec{M}\quad (8)$$

• **Finally, note that**  $\vec{H}_F$  [Eq. (1)] **and**  $\vec{E}_F$  [Eq. (3) of last page] **can be written in terms of**  $\vec{F}$  **according to**

$$\vec{H}_F = -j\omega\vec{F} - \nabla\phi_m = -j\omega\vec{F} - \frac{j}{\omega\varepsilon\mu}\nabla(\nabla\cdot\vec{F})$$

$$\vec{E}_F = -\frac{1}{\varepsilon}\nabla\times\vec{F}$$

## Summary

1. Find  $\vec{A}$  from  $\nabla^2 \vec{A} + \beta^2 \vec{A} = -\mu \vec{J}$ ,  $\beta^2 = \omega^2 \mu \epsilon$  (1)

2. Find  $\vec{H}_A$  from  $\vec{H}_A = \frac{1}{\mu} \nabla \times \vec{A}$  (2)

3. Find  $\vec{E}_A$  from  $\vec{E}_A = -j\omega \vec{A} - j \frac{1}{\omega \mu \epsilon} \nabla(\nabla \cdot \vec{A})$  or  $\vec{E}_A = \frac{1}{j\omega \epsilon} \nabla \times \vec{H}_A$  (3)

4. Find  $\vec{F}$  from  $\nabla^2 \vec{F} + \beta^2 \vec{F} = -\epsilon \vec{M}$  (4)

5. Find  $\vec{E}_F$  from  $\vec{E}_F = -\frac{1}{\epsilon} \nabla \times \vec{F}$  (5)

6. Find  $\vec{H}_F$  from  $\vec{H}_F = -j\omega \vec{F} - j \frac{1}{\omega \mu \epsilon} \nabla(\nabla \cdot \vec{F})$  or  $\vec{H}_F = \frac{-1}{j\omega \mu} \nabla \times \vec{E}_F$  (6)

7. The total  $\vec{E}$  is given by

$$\vec{E} = \vec{E}_A + \vec{E}_F = -j\omega \vec{A} - j \frac{1}{\omega \mu \epsilon} \nabla(\nabla \cdot \vec{A}) - \frac{1}{\epsilon} \nabla \times \vec{F} \quad (7)$$

or

$$\vec{E} = \vec{E}_A + \vec{E}_F = \frac{1}{j\omega \epsilon} \nabla \times \vec{H}_A - \frac{1}{\epsilon} \nabla \times \vec{F} \quad (8)$$

8. The total  $\vec{H}$  is given by

$$\vec{H} = \vec{H}_A + \vec{H}_F = \frac{1}{\mu} \nabla \times \vec{A} - j\omega \vec{F} - j \frac{1}{\omega \mu \epsilon} \nabla(\nabla \cdot \vec{F}) \quad (9)$$

or

$$\vec{H} = \vec{H}_A + \vec{H}_F = \frac{1}{\mu} \nabla \times \vec{A} - \frac{1}{j\omega \mu} \nabla \times \vec{E}_F \quad (10)$$

## Solutions for $\vec{A}$ and $\vec{F}$

- Recall that **governing differential equations for  $\vec{A}$  and  $\vec{F}$  are**

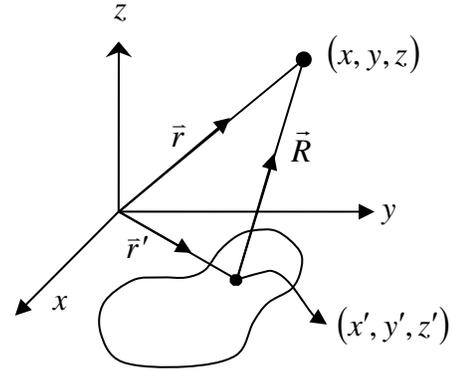
$$\nabla^2 \vec{A} + \beta^2 \vec{A} = -\mu \vec{J} \quad (1)$$

$$\nabla^2 \vec{F} + \beta^2 \vec{F} = -\varepsilon \vec{M} \quad (2)$$

- For **source located at  $(x', y', z')$  and observation point distance  $R$  from the source, the solutions to (1) and (2) are given by**

$$\vec{A}(x, y, z) = \frac{\mu}{4\pi} \iiint_{v'} \vec{J}(x', y', z') \frac{e^{-j\beta R}}{R} dv' \quad (3)$$

$$\vec{F}(x, y, z) = \frac{\varepsilon}{4\pi} \iiint_{v'} \vec{M}(x', y', z') \frac{e^{-j\beta R}}{R} dv' \quad (4)$$



where  $\vec{J}$  and  $\vec{M}$  have **dimensions proportional to  $1/m^2$**

- For  $\vec{J}_s$  and  $\vec{M}_s$  **dimensions proportional to  $1/m$**  we have

$$\vec{A}(x, y, z) = \frac{\mu}{4\pi} \iint_{s'} \vec{J}_s(x', y', z') \frac{e^{-j\beta R}}{R} ds' \quad (5)$$

$$\vec{F}(x, y, z) = \frac{\varepsilon}{4\pi} \iint_{s'} \vec{M}_s(x', y', z') \frac{e^{-j\beta R}}{R} ds' \quad (6)$$

- For **electric and magnetic current densities  $\vec{I}_e$  [Ampere] and  $\vec{I}_m$  [volt]** we have

$$\vec{A}(x, y, z) = \frac{\mu}{4\pi} \int_c \vec{I}_e(x', y', z') \frac{e^{-j\beta R}}{R} dl' \quad (7)$$

$$\vec{F}(x, y, z) = \frac{\varepsilon}{4\pi} \int_c \vec{I}_m(x', y', z') \frac{e^{-j\beta R}}{R} dl' \quad (8)$$

## TEM, TE and TM modes

- The transverse electromagnetic field configuration is a mode for **which electric and magnetic field components are transverse to a given direction**. This direction often, but not always, is the path that wave is traveling.
- For **TE mode the electric field is transverse to a given direction** and for **TM mode the magnetic field is transverse to a given direction**. Again, for TE and TM modes the aforementioned direction is often, but not always, the **direction of propagation**.

## The conditions on auxiliary vector potentials $\vec{A}$ and $\vec{F}$ for TEM, TE and TM modes

- Recall that  $\vec{E}$  and  $\vec{H}$  in terms of  $\vec{A}$  and  $\vec{F}$  were given by

$$\vec{E} = \vec{E}_A + \vec{E}_F = -j\omega\vec{A} - j\frac{1}{\omega\mu\epsilon}\nabla(\nabla\cdot\vec{A}) - \frac{1}{\epsilon}\nabla\times\vec{F} \quad (1)$$

$$\vec{H} = \vec{H}_A + \vec{H}_F = \frac{1}{\mu}\nabla\times\vec{A} - j\omega\vec{F} - j\frac{1}{\omega\mu\epsilon}\nabla(\nabla\cdot\vec{F}) \quad (2)$$

- Let

$$\vec{A} = A_x(x, y, z)\hat{a}_x + A_y(x, y, z)\hat{a}_y + A_z(x, y, z)\hat{a}_z \quad (3)$$

$$\vec{F} = F_x(x, y, z)\hat{a}_x + F_y(x, y, z)\hat{a}_y + F_z(x, y, z)\hat{a}_z \quad (4)$$

- Use (3) and (4) in (1) and (2). We get

$$\begin{aligned} \vec{E} = & \hat{a}_x \left[ -j\omega A_x - j\frac{1}{\omega\mu\epsilon} \left( \frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial x\partial y} + \frac{\partial^2 A_z}{\partial x\partial z} \right) - \frac{1}{\epsilon} \left( \frac{\partial F_z}{\partial y} - \frac{\partial F_y}{\partial z} \right) \right] + \\ & \hat{a}_y \left[ -j\omega A_y - j\frac{1}{\omega\mu\epsilon} \left( \frac{\partial^2 A_x}{\partial x\partial y} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y\partial z} \right) - \frac{1}{\epsilon} \left( \frac{\partial F_x}{\partial z} - \frac{\partial F_z}{\partial x} \right) \right] + \\ & \hat{a}_z \left[ -j\omega A_z - j\frac{1}{\omega\mu\epsilon} \left( \frac{\partial^2 A_x}{\partial x\partial z} + \frac{\partial^2 A_y}{\partial y\partial z} + \frac{\partial^2 A_z}{\partial z^2} \right) - \frac{1}{\epsilon} \left( \frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} \right) \right] \end{aligned}$$

• For  $\vec{H}$  we have

$$\begin{aligned} \vec{H} = & \hat{a}_x \left[ -j\omega F_x - j \frac{1}{\omega\mu\epsilon} \left( \frac{\partial^2 F_x}{\partial x^2} + \frac{\partial^2 F_y}{\partial x\partial y} + \frac{\partial^2 F_z}{\partial x\partial z} \right) + \frac{1}{\mu} \left( \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) \right] + \\ & \hat{a}_y \left[ -j\omega F_y - j \frac{1}{\omega\mu\epsilon} \left( \frac{\partial^2 F_x}{\partial x\partial y} + \frac{\partial^2 F_y}{\partial y^2} + \frac{\partial^2 F_z}{\partial y\partial z} \right) + \frac{1}{\mu} \left( \frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) \right] + \\ & \hat{a}_z \left[ -j\omega F_z - j \frac{1}{\omega\mu\epsilon} \left( \frac{\partial^2 F_x}{\partial x\partial z} + \frac{\partial^2 F_y}{\partial y\partial z} + \frac{\partial^2 F_z}{\partial z^2} \right) + \frac{1}{\mu} \left( \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \right] \end{aligned} \quad (1)$$

• From expression for  $\vec{E}$  and  $\vec{H}$  in terms of  $\vec{A}$  and  $\vec{F}$  we can see there are at least 3 ways for which we can obtain a TEM mode with respect to z-direction, i.e. TEM<sup>z</sup> (HW)

• For example if all the condition listed below are satisfied we have a TEM<sup>z</sup> mode

$$A_x = A_y = A_z = 0, \text{ and } F_x = F_y = 0, \text{ and } \frac{\partial}{\partial x} \neq 0, \text{ and } \frac{\partial}{\partial y} \neq 0, \text{ and}$$

$$F_z = F_z^+(x, y)e^{-j\beta z} + F_z^-(x, y)e^{j\beta z},$$

then

$$E_z = \underbrace{-j\omega A_z}_0 - \frac{j}{\omega\mu\epsilon} \left( \underbrace{\frac{\partial^2 A_x}{\partial x\partial z}}_0 + \underbrace{\frac{\partial^2 A_y}{\partial y\partial z}}_0 + \underbrace{\frac{\partial^2 A_z}{\partial z^2}}_0 \right) - \frac{1}{\epsilon} \left( \underbrace{\frac{\partial F_y}{\partial x}}_0 - \underbrace{\frac{\partial F_x}{\partial y}}_0 \right) = 0 \quad (2)$$

$$\begin{aligned} H_z = & -j\omega F_z - j \frac{1}{\omega\mu\epsilon} \left( \underbrace{\frac{\partial^2 F_x}{\partial x\partial z}}_0 + \underbrace{\frac{\partial^2 F_y}{\partial y\partial z}}_0 + \frac{\partial^2 F_z}{\partial z^2} \right) + \frac{1}{\mu} \left( \underbrace{\frac{\partial A_y}{\partial x}}_0 - \underbrace{\frac{\partial A_x}{\partial y}}_0 \right) = \\ & -j\omega F_z + \frac{j\beta^2}{\omega\mu\epsilon} \left[ F_z^+(x, y)e^{-j\beta z} + F_z^-(x, y)e^{j\beta z} \right] = -j\omega F_z + j\omega F_z = 0 \end{aligned} \quad (3)$$

• Note that from (2) and (3)  $E_z = H_z = 0$ .

• We can further calculate the  $E_x$ ,  $E_y$ ,  $H_x$ , and  $H_y$  to be

$$E_x = \underbrace{-j\omega A_x}_0 - j \frac{1}{\omega\mu\epsilon} \left( \underbrace{\frac{\partial^2 A_x}{\partial x^2}}_0 + \underbrace{\frac{\partial^2 A_y}{\partial x\partial y}}_0 + \underbrace{\frac{\partial^2 A_z}{\partial x\partial z}}_0 \right) - \frac{1}{\epsilon} \left( \frac{\partial F_z}{\partial y} - \underbrace{\frac{\partial F_y}{\partial z}}_0 \right) \Rightarrow$$

$$E_x = -\frac{1}{\epsilon} \frac{\partial}{\partial y} F_z^+(x, y)e^{-j\beta z} - \frac{1}{\epsilon} \frac{\partial}{\partial y} F_z^-(x, y)e^{j\beta z} = E_x^+ + E_x^-$$

$$E_y = \underbrace{-j\omega A_y}_0 - j \frac{1}{\omega\mu\epsilon} \left( \underbrace{\frac{\partial^2 A_x}{\partial x \partial y}}_0 + \underbrace{\frac{\partial^2 A_y}{\partial y^2}}_0 + \underbrace{\frac{\partial^2 A_z}{\partial y \partial z}}_0 \right) - \frac{1}{\epsilon} \left( \underbrace{\frac{\partial F_x}{\partial z}}_0 - \frac{\partial F_z}{\partial x} \right) = \frac{1}{\epsilon} \frac{\partial F_z}{\partial x} \Rightarrow \quad (1)$$

$$E_y = \frac{1}{\epsilon} \frac{\partial}{\partial x} F_z^+(x, y) e^{-j\beta z} + \frac{1}{\epsilon} \frac{\partial}{\partial x} F_z^- e^{j\beta z} = E_y^+ + E_y^- \quad (2)$$

and it can be shown

$$H_x = H_x^+ + H_x^- = -\sqrt{\frac{\epsilon}{\mu}} E_y^+ + \sqrt{\frac{\epsilon}{\mu}} E_y^- \quad (\text{HW}) \quad (3)$$

$$H_y = H_y^+ + H_y^- = \sqrt{\frac{\epsilon}{\mu}} E_x^+ - \sqrt{\frac{\epsilon}{\mu}} E_x^-, \quad (\text{HW}) \quad (4)$$

Where expression for  $E_y^+, E_y^-, E_x^+, E_x^-$  were given previously (e.g.

$$E_x^+ = -\frac{1}{\epsilon} \frac{\partial}{\partial y} F_z^+(x, y) e^{-j\beta z} \text{ and } E_x^- = -\frac{1}{\epsilon} \frac{\partial}{\partial y} F_z^-(x, y) e^{+j\beta z} \quad (5)$$

## Transverse magnetic wave WRT z-direction (TM<sup>z</sup>)

• To ensure that wave is a **transverse magnetic (TM) field WRT z-direction**, it is **sufficient to ensure the auxiliary vector potential  $\vec{A}$  has only z-component and  $\vec{F} = 0$ .**

• **For TM<sup>z</sup>**

$$\vec{A} = \hat{a}_z A_z(x, y, z) \text{ and } \vec{F} = 0 \quad (6)$$

• **The field components are then given by**

$$E_x = -j \frac{1}{\omega\mu\epsilon} \frac{\partial^2 A_z}{\partial x \partial z} \quad (7)$$

$$E_y = -j \frac{1}{\omega\mu\epsilon} \frac{\partial^2 A_z}{\partial y \partial z} \quad (8)$$

$$E_z = -j \frac{1}{\omega\mu\epsilon} \left( \frac{\partial^2}{\partial z^2} + \beta^2 \right) A_z \quad (9)$$

$$H_x = \frac{1}{\mu} \frac{\partial}{\partial y} A_z \quad (10)$$

$$H_y = -\frac{1}{\mu} \frac{\partial A_z}{\partial x} \quad (11)$$

$$H_z = 0 \quad (12)$$

• **All the field components of the TM<sup>z</sup> mode can also be expressed in terms of  $E_z$**

## Transverse electric field WRT z-direction (TE<sup>z</sup>)

- To have TE<sup>z</sup> we require  $\vec{F}$  to have only z-component and  $\vec{A} = 0$ , i.e.,  $\vec{A} = 0$  and  $\vec{F} = \hat{a}_z F_z(x, y, z)$  (1)

- The field components are given by

$$E_x = -\frac{1}{\epsilon} \frac{\partial F_z}{\partial y}$$

$$E_y = \frac{1}{\epsilon} \frac{\partial F_z}{\partial x}$$

$$E_z = 0$$

$$H_x = -j \frac{1}{\omega \mu \epsilon} \frac{\partial^2 F_z}{\partial x \partial z}$$

$$H_y = -j \frac{1}{\omega \mu \epsilon} \frac{\partial^2 F_z}{\partial y \partial z}$$

$$H_z = -j \frac{1}{\omega \mu \epsilon} \left( \frac{\partial^2}{\partial z^2} + \beta^2 \right) F_z$$

- All the field components of the TE<sup>z</sup> mode can also be expressed in terms of  $H_z$

## Rectangular metallic wave guide

- Rectangular metallic waveguides are routinely **used at RF and microwave frequencies**. Their study is not only motivated by their use as RF/microwave components, but will help us **better understand the concept of mode** and guided wave propagation
- In studying the guided wave structures we are usually interested in parameters such as: **field configurations (modes)** that are supported by the structure, the structure **cutoff frequency, guided wavelength, wave impedance, phase constant, attenuation constant**, etc.
- For metallic rectangular waveguide, it can be shown that **although TEM field configuration is the lowest order mode, it does not satisfy the boundary conditions and as such, the waveguide does not support TEM modes**
- However, the **TE and TM modes satisfy the required boundary conditions and as such are supported by the structure**

## Transverse Electric Field TE<sup>z</sup>

- Consider the **metallic waveguide of size  $a \times b$**  as shown. The **waveguide is infinite in the z-direction**

- From our previous discussion we have seen that **TE<sup>z</sup> modes are obtained if**

$\vec{A} = 0$  and  $\vec{F} = \hat{a}_z F_z(x, y, z)$  which implied

$$E_x = -\frac{1}{\epsilon} \frac{\partial F_z}{\partial y}$$

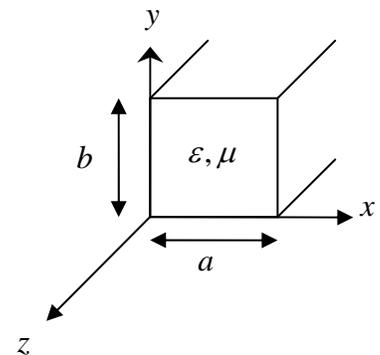
$$H_x = -j \frac{1}{\omega \mu \epsilon} \frac{\partial^2 F_z}{\partial x \partial z}$$

$$E_y = \frac{1}{\epsilon} \frac{\partial F_z}{\partial x}$$

$$H_y = -j \frac{1}{\omega \mu \epsilon} \frac{\partial^2 F_z}{\partial y \partial z}$$

$$E_z = 0$$

$$H_z = -j \frac{1}{\omega \mu \epsilon} \left( \frac{\partial^2}{\partial z^2} + \beta^2 \right) F_z$$



- $\vec{F}$  must satisfy the vector differential equation

$$\nabla^2 \vec{F} + \beta^2 \vec{F} = 0 \Rightarrow \nabla^2 F_z(x, y, z) + \beta^2 F_z(x, y, z) = 0 \Rightarrow$$

$$\frac{\partial^2 F_z}{\partial x^2} + \frac{\partial^2 F_z}{\partial y^2} + \frac{\partial^2 F_z}{\partial z^2} + \beta^2 F_z = 0$$

- Note that  $F_z(x, y, z)$  is a scalar function that can be written as (using separation of variables)

$$F_z(x, y, z) = f(x)g(y)h(z)$$

- Also recall that solutions to  $\nabla^2 F_z + \beta^2 F_z = 0$  are either standing waves (sinusoidal) or traveling waves (exponential with complex argument)

- The particular form (standing wave or traveling wave) is chosen based on the boundary conditions to be satisfied

- In the case of our metallic waveguide solutions in  $x$  and  $y$  must be standing waves and solution in  $z$ -direction (guide is infinite in the  $z$ -direction) must be traveling wave

- Hence

$$F_z(x, y, z) = f(x)g(y)h(z)$$

$$= [C_1 \cos(\beta_x x) + D_1 \sin(\beta_x x)] \cdot [C_2 \cos(\beta_y y) + D_2 \sin(\beta_y y)] \cdot [A_3 e^{-j\beta_z z} + B_3 e^{+j\beta_z z}]$$

with

$$\beta_x^2 + \beta_y^2 + \beta_z^2 = \beta^2 = \omega^2 \mu \epsilon$$

- Recall that for  $e^{j\omega t}$  time dependency,  $e^{-j\beta_z z}$  is a positively traveling wave (wave travels in positive  $z$ -direction) and  $e^{+j\beta_z z}$  is a negatively traveling wave (wave travels in negative  $z$ -direction)

- If source is located such that only positively traveling wave is present, then

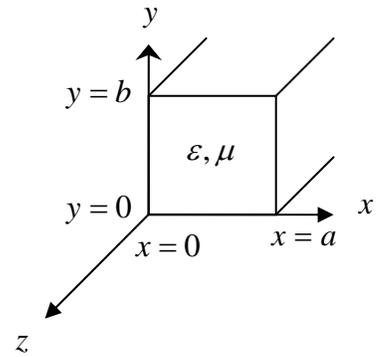
$$B_3 e^{+j\beta_z z} = 0 \Rightarrow B_3 = 0$$

- If source is located such that only negatively traveling wave is present, then

$$A_3 e^{-j\beta_z z} = 0 \Rightarrow A_3 = 0$$

- If both positively and negatively traveling waves are present (a waveguide terminated on a load that is not matched), then both  $A_3 e^{-j\beta_z z}$  and  $B_3 e^{+j\beta_z z}$  must be included

- Here, for simplicity, we assume that only positive traveling wave exist  $\Rightarrow B_3 = 0$



- The  $F_z$  is then given by

$$F_z^+(x, y, z) = [C_1 \cos(\beta_x x) + D_1 \sin(\beta_x x)] \cdot [C_2 \cos(\beta_y y) + D_2 \sin(\beta_y y)] A_3 e^{-j\beta_z z} \quad (1)$$

- We impose the boundary conditions on the top, bottom, left and right walls of the metallic waveguide, assuming a perfect electric conductor (PEC) boundary condition, i.e.  $\vec{E}$  and  $\vec{H}$  tangential are zero on the walls

- The boundary conditions are:

$$E_x(0 \leq x \leq a, y = 0, z) = E_x(0 \leq x \leq a, y = b, z) = 0, \text{ Bottom and top walls for } E_x \quad (2)$$

$$E_z(0 \leq x \leq a, y = 0, z) = E_z(0 \leq x \leq a, y = b, z) = 0, \text{ Bottom and top walls for } E_z \quad (3)$$

$$E_y(x = 0, 0 \leq y \leq b, z) = E_y(x = a, 0 \leq y \leq b, z) = 0, \text{ Left and right walls for } E_y \quad (4)$$

$$E_z(x = 0, 0 \leq y \leq b, z) = E_z(x = a, 0 \leq y \leq b, z) = 0, \text{ Left and right walls for } E_z \quad (5)$$

- Note that the boundary conditions (3) and (5) are not independent and they represent the same boundary conditions as (2) and (4).

- The necessary and sufficient conditions are to satisfy (2) OR (3) ( $E_x$  and  $E_z$  at bottom and top walls) AND (4) or (5) ( $E_y$  and  $E_z$  at the left and right walls)

- Furthermore, note that for  $\text{TE}^z$  modes by definition  $E_z$  is zero. This means that the necessary and sufficient B.C.'s for  $\text{TE}^z$  are (2) and (4) of the last page ( $E_x$  at the bottom and the top and  $E_y$  at the left and right walls)

$$E_x(0 \leq x \leq a, y = 0, z) = E_x(0 \leq x \leq a, y = b, z) = 0$$

$$E_y(x = 0, 0 \leq y \leq b, z) = E_y(x = a, 0 \leq y \leq b, z) = 0$$

- Recall that the vector potential for  $\text{TE}^z$  was given as [Eq. (1), last page]

$$F_z^+(x, y, z) = [C_1 \cos(\beta_x x) + D_1 \sin(\beta_x x)] \cdot [C_2 \cos(\beta_y y) + D_2 \sin(\beta_y y)] A_3 e^{-j\beta_z z}. \text{ We then have}$$

$$E_x = -\frac{1}{\varepsilon} \frac{\partial F_z^+}{\partial y} = -A_3 \frac{\beta_y}{\varepsilon} [C_1 \cos(\beta_x x) + D_1 \sin(\beta_x x)] \cdot [-C_2 \sin(\beta_y y) + D_2 \cos(\beta_y y)] A_3 e^{-j\beta_z z}$$

- From  $E_x(0 \leq x \leq a, y = 0, z) = 0 \Rightarrow D_2 = 0$

- From  $E_x(0 \leq x \leq a, y = b, z) = 0 \Rightarrow \sin(\beta_y b) = 0 \Rightarrow$

$$\beta_y b = n\pi \quad n = 0, 1, 2, 3 \text{ or equally,}$$

$$\beta_y = \frac{n\pi}{b} \quad n = 0, 1, 2, 3$$

- $\beta_y$  is sometimes referred to as eigenvalue

- If we use our newly found results, we have

$$F_z^+(x, y, z) = [C_1 \cos(\beta_x x) + D_1 \sin(\beta_x x)] C_2 \cos\left(\frac{n\pi}{b} y\right) A_3 e^{-j\beta_z z}$$

- The  $E_y$  can be found from

$$E_y = \frac{1}{\varepsilon} \frac{\partial F_z^+}{\partial x} = \frac{\beta_x}{\varepsilon} [-C_1 \sin(\beta_x x) + D_1 \cos(\beta_x x)] C_2 \cos\left(\frac{n\pi}{b} y\right) A_3 e^{-j\beta_z z}$$

- Boundary conditions for  $E_y$  at left wall is

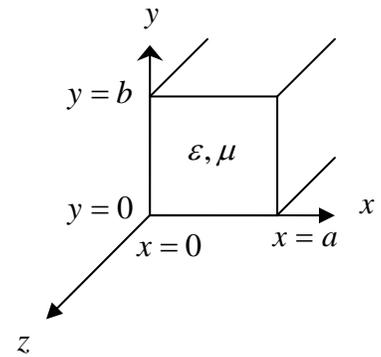
$$E_y(x = 0, 0 \leq y \leq b, z) = 0 \Rightarrow D_1 = 0$$

- Boundary condition for  $E_y$  at right wall is

$$E_y(x = a, 0 \leq y \leq b, z) = 0 \Rightarrow \sin(\beta_x a) = 0 \Rightarrow$$

$$\beta_x a = m\pi \quad m = 0, 1, 2, 3 \text{ or equally}$$

$$\beta_x = \frac{m\pi}{a} \quad m = 0, 1, 2, 3$$



- Putting it all together, the vector potential  $F_z^+$  is given by

$$F_z^+(x, y, z) = C_1 \cos\left(\frac{m\pi}{a}x\right) C_2 \cos\left(\frac{n\pi}{b}y\right) A_3 e^{-j\beta_z z} = A_{mn} \cos\left(\frac{m\pi}{a}x\right) \cos\left(\frac{n\pi}{b}y\right) e^{-j\beta_z z}$$

with  $m = 0, 1, 2, 3$   
 $n = 0, 1, 2, 3$  but  $m = n \neq 0$

$A_{mn}$  is a constant =  $C_1 C_2 A_3$

## Propagation constant (wave numbers) and wavelengths in the $x$ , $y$ and $z$ direction

- From our previous discussion it is clear that propagation constant (or wave number) along  $x$  ( $\beta_x$ ) and along  $y$  ( $\beta_y$ ) can be written as

$$\beta_x = \frac{m\pi}{a} = \frac{2\pi}{\lambda_x} \Rightarrow \lambda_x = \frac{2a}{m}; m = 0, 1, 2 \quad (1)$$

$$\beta_y = \frac{n\pi}{b} = \frac{2\pi}{\lambda_y} \Rightarrow \lambda_y = \frac{2b}{n}; n = 0, 1, 2 \text{ and with } m = n \neq 0, \quad (2)$$

where we have also defined the wavelength along  $x$  to be  $\lambda_x$  and along  $y$  to be  $\lambda_y$

- Recall that  $\beta_x^2 + \beta_y^2 + \beta_z^2 = \beta^2 = \omega^2 \mu \epsilon$  or equally well:

$$\frac{1}{\lambda_x^2} + \frac{1}{\lambda_y^2} + \frac{1}{\lambda_z^2} = \frac{1}{\lambda^2} \text{ where } \lambda \text{ is the wavelength in the medium with } \epsilon \text{ and } \mu$$

(material inside the guide)

- From (1) and (2) note that  $\beta_x$  and  $\beta_y$  are discrete (one can say they are quantized), where as  $\beta_z$  is a continuous parameter.

- Note that in principle there are infinite numbers of possible  $\beta_x$  and  $\beta_y$  (eigenvalues) hence there are infinite number of  $\text{TE}^z$  modes that satisfy the wave equation and the given boundary condition.

- From  $\beta_x = \frac{m\pi}{a}$  and  $\beta_y = \frac{n\pi}{b}$  and  $\beta_x^2 + \beta_y^2 + \beta_z^2 = \beta^2 = \omega^2 \mu \epsilon$  we can see that

$$\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2 + \beta_z^2 = \beta^2 \Rightarrow \beta^2 - \beta_z^2 = \left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2 = \beta_c^2,$$

where by definition:  $\beta_c \equiv$  cutoff propagation constant or cutoff wave number

• Note that  $\beta_c = \beta|_{\beta_z=0} = \omega\sqrt{\mu\varepsilon}|_{\beta_z=0} = \omega_c\sqrt{\mu\varepsilon} = 2\pi f_c\sqrt{\mu\varepsilon} = \sqrt{\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2}$ .

• Hence, the cutoff frequency ( $f_c$ ) is given by

$$(f_c)_{mn} = \frac{1}{2\pi\sqrt{\mu\varepsilon}} \sqrt{\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2} \quad \left. \begin{array}{l} m = 0,1,2,3 \\ n = 0,1,2,3 \end{array} \right\} m = n \neq 0$$

• From the expression  $\beta_c = \beta|_{\beta_z=0}$  we can see why  $\beta_c$  is called the cutoff propagation constant. **For this wave number,  $\beta_z = 0$  and the wave no longer travels along the z-direction.**

• The above can be more clearly seen from

$$\beta_z^2 = \beta^2 - (\beta_x^2 + \beta_y^2) = \beta^2 - \left[ \left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2 \right] = \beta^2 - \beta_c^2. \quad \text{Clearly for}$$

$$\beta = \beta_c \Rightarrow \beta_z = 0$$

• The field components for  $\text{TE}_{mn}^{+z}$  are now given by

$$E_x^+ = A_{mn} \frac{\beta_y}{\varepsilon} \cos(\beta_x x) \sin(\beta_y y) e^{-j\beta_z z}$$

$$E_y^+ = -A_{mn} \frac{\beta_x}{\varepsilon} \sin(\beta_x x) \cos(\beta_y y) e^{-j\beta_z z}$$

$$E_z^+ = 0$$

$$H_x^+ = A_{mn} \frac{\beta_x \beta_z}{\omega\mu\varepsilon} \sin(\beta_x x) \cos(\beta_y y) e^{-j\beta_z z}$$

$$H_y^+ = A_{mn} \frac{\beta_y \beta_z}{\omega\mu\varepsilon} \cos(\beta_x x) \sin(\beta_y y) e^{-j\beta_z z}$$

$$H_z^+ = -jA_{mn} \frac{\beta_c^2}{\omega\mu\varepsilon} \cos(\beta_x x) \cos(\beta_y y) e^{-j\beta_z z}$$

• To appreciate the importance of the cutoff conditions consider the following:

$$\beta_z^2 = \beta^2 - \beta_c^2 = \beta^2 - \left[ \left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2 \right] \Rightarrow$$

$$(\beta_z)_{mn} = \pm\sqrt{\beta^2 - \beta_c^2} = \pm\beta\sqrt{1 - \left(\frac{\beta_c}{\beta}\right)^2}$$

$$= \pm\beta\sqrt{1 - \left(\frac{f_c}{f}\right)^2} = \pm\beta\sqrt{1 - \left(\frac{\lambda}{\lambda_c}\right)^2}$$

for  $\beta > \beta_c \Leftrightarrow f > f_c$

•  $(\beta_z)_{mn} = 0$  for  $\beta = \beta_c \Leftrightarrow f = f_c$

•  $(\beta_z)_{mn} = \pm j\sqrt{\beta_c^2 - \beta^2} = \pm j\beta\sqrt{\left(\frac{\beta_c}{\beta}\right)^2 - 1}$

$= \pm j\beta\sqrt{\left(\frac{f_c}{f}\right)^2 - 1} = \pm j\beta\sqrt{\left(\frac{\lambda}{\lambda_c}\right)^2 - 1}$  for  $\beta_c > \beta \Leftrightarrow f_c > f$

• If we only consider the positively traveling wave we must choose the sign in front of the square root appropriately, i.e.

$(\beta_z)_{mn} = \beta\sqrt{1 - \left(\frac{\beta_c}{\beta}\right)^2} = \beta\sqrt{1 - \left(\frac{f_c}{f}\right)^2} = \beta\sqrt{1 - \left(\frac{\lambda}{\lambda_c}\right)^2}$  for  $\beta > \beta_c \Leftrightarrow f > f_c$

$(\beta_z)_{mn} = 0$  for  $\beta_c = \beta \Leftrightarrow f_c = f$

$(\beta_z)_{mn} = -j\beta\sqrt{\left(\frac{\beta_c}{\beta}\right)^2 - 1} = -j\beta\sqrt{\left(\frac{f_c}{f}\right)^2 - 1} = -j\beta\sqrt{\left(\frac{\lambda}{\lambda_c}\right)^2 - 1}$  for  $\beta_c > \beta \Leftrightarrow f_c > f$

• Since electric and magnetic fields are proportional to  $e^{-j\beta_z z} e^{j\omega t}$  then

$e^{-j\beta\sqrt{1 - \left(\frac{f_c}{f}\right)^2} z} e^{j\omega t}$  represents a propagating wave for  $f > f_c$

$e^{j\omega t} e^{-j0z} = e^0 e^{j\omega t} = 1 e^{j\omega t}$  represents a standing wave for  $f_c = f$

$e^{-j\left[-j\beta\sqrt{\left(\frac{f_c}{f}\right)^2 - 1}\right] z} e^{j\omega t} = e^{-\beta_z\left[\sqrt{\left(\frac{f_c}{f}\right)^2 - 1}\right] z} e^{j\omega t}$  represents an attenuated (evanescent) wave for  $f_c > f$

## TE<sub>10</sub> Field components and Field Patterns

$$E_x(x, y, z, t) = 0$$

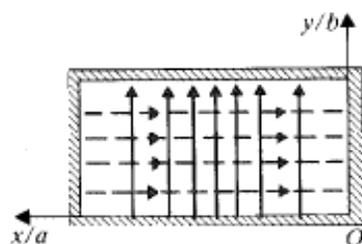
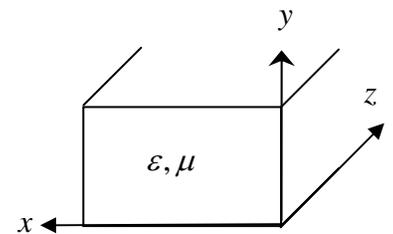
$$E_y(x, y, z, t) = \frac{\omega\mu}{h^2} \left(\frac{\pi}{a}\right) H_0 \sin\left(\frac{\pi}{a}x\right) \sin(\omega t - \beta z),$$

$$E_z(x, y, z, t) = 0,$$

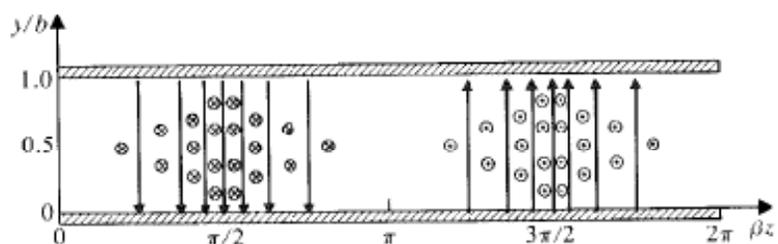
$$H_x(x, y, z, t) = -\frac{\beta}{h^2} \left(\frac{\pi}{a}\right) H_0 \sin\left(\frac{\pi}{a}x\right) \sin(\omega t - \beta z),$$

$$H_y(x, y, z, t) = 0,$$

$$H_z(x, y, z, t) = H_0 \cos\left(\frac{\pi}{a}x\right) \cos(\omega t - \beta z),$$

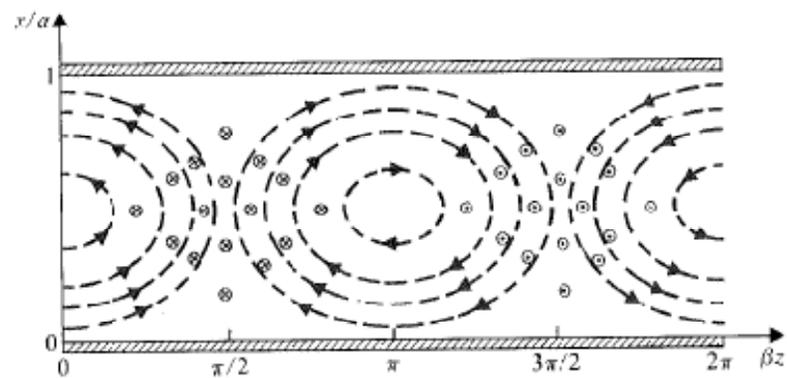


(a)



(b)

—— Electric field lines  
 - - - - Magnetic field lines



(c)