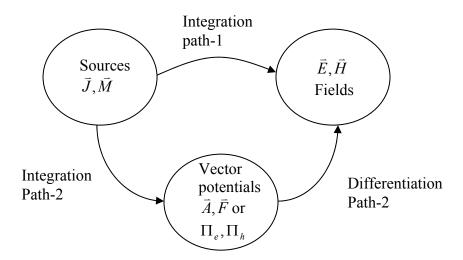
Auxiliary Vector Potential

Constructing solutions using auxiliary vector potentials

- The objective of EM theory is to find the possible EM field configurations (modes) for a given boundary value problem involving wave propagation, radiation, or scattering.
- This can be done by finding the electric and magnetic fields (\vec{E} and \vec{H}) or equally obtaining the auxiliary vector potentials (\vec{A} and \vec{F})
- In addition to auxiliary vector potentials \vec{A} and \vec{F} there are other possible set. For example, Hertz vector potentials (Π_a and Π_b). Here, we only concentrate on \vec{A} and \vec{F}
- The path for solving EM field configuration is then as follows



- Depending on problem at hand, path-2 maybe easier than path-1
- Traditionally \vec{E} and \vec{B} are viewed as physical field quantities, whereas vector potential (\vec{A}) and its scalar counter part (ϕ_e) are considered as mathematical constructs. However, there are diverging views on this point!!!
- It is interesting to note that Maxwell himself derived many of his results by using the concept of vector potential (\vec{A}) which he called "electromagnetic momentum." However this approach was later criticized by other practitioners such as Hertz and Heaviside.

The question of the propagation of, not merely the electric potential Ψ but the vector potential \vec{A} ... when brought forward, prove to be one of a metaphysical nature ... the electric force \vec{E} and the magnetic force \vec{H} ... actually represent the state of the medium everywhere. Heaviside, *Philosophical Magazine*, 1889.

• Here is what Hertz says about Maxwell's approach:

I may mention the predominance of the vector potential in [Maxwell's] fundamental equations. In the construction of new theory the potential served as a scaffolding ... it does not appear to me that any ... advantage is attained by the introduction of the vector potential in the fundamental equations. C. A. Mead, Collective electrodynamics, 2000.

• Here is different (more modern) point of view:

... the vector potential which appears in quantum mechanics in an explicit form produces a classical force which depends only on its derivatives. In quantum mechanics what matters is the interference between nearby paths; it always turns out that the effects depend only on how much the filed \bar{A} changes from point to point, and therefore only on the derivatives of \bar{A} and not on the value itself. Nevertheless, the vector potential \bar{A} (together with the scalar potential ϕ that goes with it) appears to give the most direct description of the physics. This becomes more and more apparent the more deeply we go into the quantum theory. In the general theory of quantum electrodynamics, one takes the vector and scalar potentials as the fundamental quantities in a set of equations that replace the Maxwell equations: \vec{E} and \vec{B} are slowly disappearing from the modern expression of physical laws, they are being replaced by \vec{A} and ϕ . Feynman, Leighton, and Sands, Lectures on Physics, Vol. II, 1984.

Equations governing vector potential \vec{A}

• Since
$$\nabla \cdot \vec{B} = 0 \Rightarrow$$
 (1)

$$\vec{B}_A = \nabla \times \vec{A}$$
 and (2)

$$\bar{H}_A = \frac{1}{\mu} \nabla \times \bar{A} \tag{3}$$

Subscript A is to remind us that \vec{B}_A and \vec{H}_A are due to vector potential A

• For
$$\vec{M} = 0$$
 (no magnetic source)

$$\nabla \times \vec{E}_A = -j\omega\mu \, \vec{H}_A$$
 (Faraday's Law) (4)

• Use (3) in (4) \Rightarrow

$$\nabla \times \vec{E}_{A} = -j\omega\mu \left(\frac{1}{\mu}\nabla \times \vec{A}\right) \Rightarrow \nabla \times \left(E_{A} + j\omega\vec{A}\right) = 0 \tag{5}$$

• Since curl of gradient of any scalar is zero, i.e., $\nabla \times (-\nabla \phi_e) = 0$, then from (5) we have $\vec{E}_A + j\omega\vec{A} = -\nabla \phi_e \Rightarrow \vec{E}_A = -j\omega\vec{A} - \nabla \phi_e$ where (6) $\phi_e = \text{Scalar potential}$ $\vec{A} = \text{Vector potential}$

- Equations (6) and (3) are the expression for \vec{E} and \vec{H} in terms of \vec{A} and ϕ_e
- We note that from $\vec{H}_A = \frac{1}{\mu} \nabla \times \vec{A}$, for a homogeneous medium we can write $\mu \nabla \times \vec{H}_A = \nabla \times \nabla \times \vec{A} \Rightarrow \mu \nabla \times \vec{H}_A = \nabla \left(\nabla \cdot \vec{A}\right) \nabla^2 \vec{A}$ (7)

• Using Ampere's Law
$$\nabla \times \vec{H}_A = \vec{J} + j\omega\varepsilon\vec{E}_A$$
 in (7) we have
$$\mu \vec{J} + j\omega\varepsilon\mu\vec{E}_A = \nabla(\nabla \cdot \vec{A}) - \nabla^2\vec{A}$$
 (8)

• Previously we found the expression for \vec{E}_A to be $\vec{E}_A = -j\omega\vec{A} - \nabla\phi_e$. Using this in (8) we have

$$\mu \vec{J} + j\omega \varepsilon \mu \left[-j\omega \vec{A} - \nabla \phi_e \right] = \nabla \left(\nabla \cdot \vec{A} \right) - \nabla^2 \vec{A} \tag{9}$$

- Recall that $\omega^2 \mu \varepsilon = \beta^2$ then (9) can be written as $\nabla^2 \vec{A} + \beta^2 \vec{A} = \nabla (\nabla \cdot \vec{A} + j\omega \varepsilon \mu \phi_e) \mu \vec{J}$
- We have defined the curl of \vec{A} as $\vec{B}_A = \nabla \times \vec{A}$, we are at liberty to define the $\nabla \cdot \vec{A}$.

• In light of
$$\nabla^2 \vec{A} + \beta^2 \vec{A} = \nabla (\nabla \cdot \vec{A} + j\omega \varepsilon \mu \phi_e) - \mu \vec{J}$$
 (1)

let us define the divergence of \vec{A} to be

$$\nabla \cdot \vec{A} = -j\omega \varepsilon \mu \phi_e \tag{2}$$

• Using (2) in (1) we have

$$\nabla^2 \vec{A} + \beta^2 \vec{A} = -\mu \vec{J} \qquad \text{and} \tag{3}$$

$$\phi_e = -\frac{1}{i\omega\varepsilon\mu}\nabla\cdot\vec{A} \tag{4}$$

• Finally, our expressions for \vec{E}_A and \vec{H}_A in the last page [Eqs. (6) and (3)] can be written as

$$\vec{E}_A = -\nabla \phi_e - j\omega \vec{A} = \frac{-j}{\omega \mu \varepsilon} \nabla (\nabla \cdot \vec{A}) - j\omega \vec{A}$$
 (5)

$$\bar{H}_A = \frac{1}{\mu} \nabla \times \bar{A} \tag{6}$$

• Now, equations (5) and (6) are expressions for \vec{E}_A and \vec{H}_A in terms of \vec{A} only subject to Lorentz gauge.

Equations governing the vector potential \vec{F}

• Consider a region of space free of charges, i.e. $q_{\mathrm{ave}} = 0$, then

$$\nabla \cdot \vec{D} = 0 \Longrightarrow \tag{1}$$

$$\vec{D}_F = -\nabla \times \vec{F} \Longrightarrow \tag{2}$$

$$\vec{E}_F = -\frac{1}{c} \nabla \times \vec{F} \tag{3}$$

Subscript F is to remind us \vec{D}_F is due to vector potential \vec{F}

• Recall that Ampere's Law with $\vec{J}=0$, is given by

$$\nabla \times \vec{H}_F = j\omega\varepsilon \, \vec{E}_F \Rightarrow \vec{E}_F = \frac{1}{j\omega\varepsilon} \nabla \times \vec{H}_F \tag{4}$$

• Use (4) in (3) and we have

$$\frac{1}{j\omega\varepsilon}\nabla\times\vec{H}_{F} = -\frac{1}{\varepsilon}\nabla\times\vec{F} \Rightarrow \nabla\times\vec{H}_{F} = -j\omega\nabla\times\vec{F} \Rightarrow \nabla\times\left(\vec{H}_{F} + j\omega\vec{F}\right) = 0 \tag{5}$$

• Compare $\nabla \times (\vec{H}_F + j\omega \vec{F}) = 0$ with null identity $\nabla \times (-\nabla \phi_m) = 0$, then it is clear that $\vec{H}_F + j\omega \vec{F} = -\nabla \phi_m \Longrightarrow$

$$\vec{H}_F = -j\omega \, \vec{F} - \nabla \phi_m \tag{1}$$

• For homogenous media, from $\vec{E}_F = -\frac{1}{\varepsilon} \nabla \times \vec{F}$ we have $\nabla \times \vec{E}_F = -\frac{1}{\varepsilon} \nabla \times \nabla \times \vec{F} \Rightarrow$

$$\nabla \times \vec{E}_F = -\frac{1}{\varepsilon} \nabla \left(\nabla \cdot \vec{F} \right) + \frac{1}{\varepsilon} \nabla^2 \vec{F} \tag{2}$$

• From Faraday's Law we have

$$\nabla \times \vec{E}_F = -\vec{M} - j\omega\mu \,\vec{H}_F \,, \tag{3}$$

then substitute (3) in (2)

$$-\vec{M} - j\omega\mu \,\vec{H}_F = -\frac{1}{\varepsilon}\nabla(\nabla \cdot \vec{F}) + \frac{1}{\varepsilon}\nabla^2 \vec{F} \tag{4}$$

• But we already found an expression for \vec{H}_F in (1). Use (1) in (4), and we have

$$\beta^{2}\vec{F} + \nabla^{2}\vec{F} = -\varepsilon\vec{M} + \nabla(\nabla \cdot \vec{F} + j\omega\mu\varepsilon\phi_{m})$$
(5)

Where again $\beta^2 = \omega^2 \mu \varepsilon$

• Once again curl of \vec{F} is defined by $\vec{D}_F = -\nabla \times \vec{F}$. We are at liberty to choose the divergence of \vec{F} . Let

$$\nabla \cdot \vec{F} = -j\omega\mu\varepsilon\phi_m \Longrightarrow \tag{6}$$

$$\phi_{m} = \frac{-1}{j\omega\varepsilon\mu} \nabla \cdot \vec{F} \tag{7}$$

• Using (6), (5) simplifies to

$$\nabla^2 \vec{F} + \beta^2 \vec{F} = -\varepsilon \vec{M} \tag{8}$$

• Finally, note that \vec{H}_F [Eq. (1)] and \vec{E}_F [Eq. (3) of last page)] can be written in terms of \vec{F} according to

$$\vec{H}_F = -j\omega\vec{F} - \nabla\phi_m = -j\omega\vec{F} - \frac{j}{\omega\varepsilon\mu}\nabla(\nabla\cdot\vec{F})$$

$$\vec{E}_F = -\frac{1}{\varepsilon} \nabla \times \vec{F}$$

Summary

1. Find
$$\vec{A}$$
 from $\nabla^2 \vec{A} + \beta^2 \vec{A} = -\mu J$ $\beta^2 = \omega^2 \mu \varepsilon$ (1)

2. Find
$$\vec{F}$$
 from $\nabla^2 \vec{F} + \beta^2 \vec{F} = -\varepsilon \vec{M}$ (2)

3. Find
$$\vec{H}_A$$
 from $\vec{H}_A = \frac{1}{\mu} \nabla \times \vec{A}$ (3)

4. **Find**
$$\vec{E}_A$$
 from $\vec{E}_A = -j\omega \vec{A} - j\frac{1}{\omega\mu\varepsilon}\nabla(\nabla \cdot \vec{A})$ or $\vec{E}_A = \frac{1}{j\omega\varepsilon}\nabla \times \vec{H}_A$ (4)

5. Find
$$\vec{E}_F$$
 from $\vec{E}_F = -\frac{1}{\varepsilon} \nabla \times \vec{F}$ (5)

6. Find
$$\vec{H}_F$$
 from $\vec{H}_F = -j\omega \vec{F} - j\frac{1}{\omega\mu\varepsilon}\nabla(\nabla \cdot \vec{F})$ or $\vec{H}_F = \frac{-1}{j\omega\mu}\nabla \times \vec{E}_F$ (6)

7. The total \vec{E} is given by

$$\vec{E} = \vec{E}_A + \vec{E}_F = -j\omega\vec{A} - j\frac{1}{\omega\mu\varepsilon}\nabla(\nabla\cdot\vec{A}) - \frac{1}{\varepsilon}\nabla\times\vec{F}$$
(7)

or

$$\vec{E} = \vec{E}_A + \vec{E}_F = \frac{1}{j\omega\varepsilon} \nabla \times \vec{H}_A - \frac{1}{\varepsilon} \nabla \times \vec{F}$$
 (8)

8. The total \vec{H} is given by

$$\vec{H} = \vec{H}_A + \vec{H}_F = \frac{1}{\mu} \nabla \times \vec{A} - j\omega \, \vec{F} - j \frac{1}{\omega \mu \varepsilon} \nabla (\nabla \cdot \vec{F})$$
(9)

or

$$\vec{H} = \vec{H}_A + \vec{H}_F = \frac{1}{\mu} \nabla \times \vec{A} - \frac{1}{i\omega\mu} \nabla \times \vec{E}_F \tag{10}$$

Solutions for \vec{A} and \vec{F}

• Recall that governing differential equations for \bar{A} and \bar{F} are

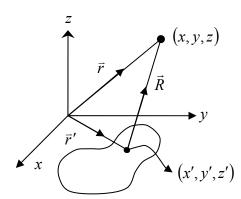
$$\nabla^2 \vec{A} + \beta^2 \vec{A} = -\mu \vec{J}$$

$$\nabla^2 \vec{F} + \beta^2 \vec{F} = -\varepsilon \vec{M}$$

• For source located at (x', y', z') and observation point distance R from the source, the solutions to (1) and (2) are given by

$$\vec{A}(x,y,z) = \frac{\mu}{4\pi} \iiint_{x'} \vec{J}(x',y',z') \frac{e^{-j\beta R}}{R} dv'$$
 (3)

$$\bar{F}(x,y,z) = \frac{\varepsilon}{4\pi} \iiint_{x'} \vec{M}(x',y',z') \frac{e^{-j\beta R}}{R} dv'$$
 (4)



where \vec{J} and \vec{M} have dimensions proportional to $1/\text{m}^2$

• For \vec{J}_s and \vec{M}_s dimensions proportional to 1/m we have

$$\vec{A}(x,y,z) = \frac{\mu}{4\pi} \iint_{S} \vec{J}_{s}(x',y',z') \frac{e^{-j\beta R}}{R} ds'$$
 (5)

$$\vec{F}(x,y,z) = \frac{\varepsilon}{4\pi} \iint_{s'} \vec{M}_{s}(x',y',z') \frac{e^{-j\beta R}}{R} ds'$$
 (6)

• For electric and magnetic current densities \vec{I}_e [Ampere] and \vec{I}_m [volt] we have

$$\vec{A}(x,y,z) = \frac{\mu}{4\pi} \int \vec{I}_e(x',y',z') \frac{e^{-j\beta R}}{R} dl'$$
 (7)

$$\vec{F}(x,y,z) = \frac{\varepsilon}{4\pi} \int \vec{I}_m(x',y',z') \frac{e^{-j\beta R}}{R} dl'$$
 (8)

TEM, TE and TM modes

- The transverse electromagnetic field configuration is a mode for **which electric and magnetic field components are transverse to a given direction**. This direction often, but not always, is the path that the wave is traveling.
- For TE mode the electric field is transverse to a given direction and for TM mode the magnetic field is transverse to a given direction. Again, for TE and TM modes the aforementioned direction is often, but not always, the direction of propagation.

The conditions on auxiliary vector potentials \vec{A} and \vec{F} for TEM, TE and TM modes

• Recall that \vec{E} and \vec{H} in terms of \vec{A} and \vec{F} were given by

$$\vec{E} = \vec{E}_A + \vec{E}_F = -j\omega\vec{A} - j\frac{1}{\omega\mu\varepsilon}\nabla(\nabla\cdot\vec{A}) - \frac{1}{\varepsilon}\nabla\times\vec{F}$$
 (1)

$$\vec{H} = \vec{H}_A + \vec{H}_F = \frac{1}{\mu} \nabla \times \vec{A} - j\omega \, \vec{F} - j \frac{1}{\omega \mu \varepsilon} \nabla (\nabla \cdot \vec{F})$$
 (2)

Let

$$\vec{A} = A_x(x, y, z)\hat{a}_x + A_y(x, y, z)\hat{a}_y + A_x(x, y, z)\hat{a}_z$$
(3)

$$\vec{F} = F_x(x, y, z)\hat{a}_x + F_y(x, y, z)\hat{a}_y + F_z(x, y, z)\hat{a}_z$$
(4)

• Use (3) and (4) in (1) and (2). We get

$$\begin{split} \bar{E} &= \hat{a}_x \Bigg[-j\omega A_x - j\frac{1}{\omega\mu\varepsilon} \Bigg(\frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_y}{\partial x \partial y} + \frac{\partial^2 A_z}{\partial x \partial z} \Bigg) - \frac{1}{\varepsilon} \Bigg(\frac{\partial F_z}{\partial y} - \frac{\partial F_y}{\partial z} \Bigg) \Bigg] + \\ \hat{a}_y \Bigg[-j\omega A_y - j\frac{1}{\omega\mu\varepsilon} \Bigg(\frac{\partial^2 A_x}{\partial x \partial y} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_z}{\partial y \partial z} \Bigg) - \frac{1}{\varepsilon} \Bigg(\frac{\partial F_x}{\partial z} - \frac{\partial F_z}{\partial x} \Bigg) \Bigg] + \\ \hat{a}_z \Bigg[-j\omega A_z - j\frac{1}{\omega\mu\varepsilon} \Bigg(\frac{\partial^2 A_x}{\partial x \partial z} + \frac{\partial^2 A_y}{\partial y \partial z} + \frac{\partial^2 A_z}{\partial z^2} \Bigg) - \frac{1}{\varepsilon} \Bigg(\frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} \Bigg) \Bigg] \end{split}$$

• For \vec{H} we have

$$\vec{H} = \hat{a}_{x} \left[-j\omega F_{x} - j\frac{1}{\omega\mu\varepsilon} \left(\frac{\partial^{2}F_{x}}{\partial x^{2}} + \frac{\partial^{2}F_{y}}{\partial x\partial y} + \frac{\partial^{2}F_{z}}{\partial x\partial z} \right) + \frac{1}{\mu} \left(\frac{\partial A_{z}}{\partial y} - \frac{\partial A_{y}}{\partial z} \right) \right] + \\
\hat{a}_{y} \left[-j\omega F_{y} - j\frac{1}{\omega\mu\varepsilon} \left(\frac{\partial^{2}F_{x}}{\partial x\partial y} + \frac{\partial^{2}F_{y}}{\partial y^{2}} + \frac{\partial^{2}F_{z}}{\partial y\partial z} \right) + \frac{1}{\mu} \left(\frac{\partial A_{z}}{\partial z} - \frac{\partial A_{y}}{\partial x} \right) \right] + \\
\hat{a}_{z} \left[-j\omega F_{z} - j\frac{1}{\omega\mu\varepsilon} \left(\frac{\partial^{2}F_{x}}{\partial x\partial z} + \frac{\partial^{2}F_{y}}{\partial y\partial z} + \frac{\partial^{2}F_{z}}{\partial z^{2}} \right) + \frac{1}{\mu} \left(\frac{\partial A_{y}}{\partial x} - \frac{\partial A_{y}}{\partial y} \right) \right] \right] \tag{1}$$

- From expression for \vec{E} and \vec{H} in terms of \vec{A} and \vec{F} we can see there are at least 3 ways for which we can obtain a TEM mode with respect to z-direction, i.e. TEM^z (HW)
- For example if all the condition listed below are satisfied we have a TEM^z mode

$$A_x = A_y = A_z = 0$$
 and $F_x = F_y = 0$ and y and $\frac{\partial}{\partial x} \neq 0$ and $\frac{\partial}{\partial y} \neq 0$ and $F_z = F_z^+(x,y)e^{-j\beta z} + F_z^-(x,y)e^{+j\beta z}$, then

$$E_{z} = -\frac{0}{j\omega A_{z}} - \frac{j}{\omega\mu\varepsilon} \left(\frac{\partial^{2} A_{x}}{\partial x \partial z} + \frac{\partial^{2} A_{y}}{\partial y \partial z} + \frac{\partial^{2} A_{z}}{\partial z^{2}} \right) - \frac{1}{\varepsilon} \left(\frac{\partial^{2} A_{y}}{\partial x} - \frac{\partial^{2} A_{z}}{\partial y} \right) = 0$$
 (2)

$$H_{z} = -j\omega F_{z} - j\frac{1}{\omega\mu\varepsilon} \left(\frac{\partial^{2}F_{x}}{\partial x\partial z} + \frac{\partial^{2}F_{y}}{\partial y\partial z} + \frac{\partial^{2}F_{z}}{\partial z^{2}} \right) + \frac{1}{\mu} \left(\frac{\partial^{2}A_{y}}{\partial x} - \frac{\partial^{2}A_{y}}{\partial y} \right) = 0$$

$$-j\omega F_z + \frac{j\beta^2}{\omega u\varepsilon} \left[F_z^+(x,y) e^{-j\beta z} + F_z^-(x,y) e^{j\beta z} \right] = -j\omega F_z + j\omega F_z = 0$$
 (3)

- Note that from (2) and (3) $E_z = H_z = 0$.
- We can further calculate the E_{x} , E_{y} , H_{x} , and H_{y} to be

$$E_{x} = -\frac{1}{j\omega A_{x}} - j\frac{1}{\omega\mu\varepsilon} \left(\frac{\partial^{2} A_{x}}{\partial x^{2}} + \frac{\partial^{2} A_{y}}{\partial x\partial y} + \frac{\partial^{2} A_{z}}{\partial x\partial z} \right) - \frac{1}{\varepsilon} \left(\frac{\partial F_{z}}{\partial y} - \frac{\partial F_{y}}{\partial z} \right) \Rightarrow$$

$$E_{x} = -\frac{1}{\varepsilon} \frac{\partial}{\partial y} F_{z}^{+}(x, y) e^{-j\beta z} - \frac{1}{\varepsilon} \frac{\partial}{\partial y} F_{z}^{-}(x, y) e^{j\beta z} = E_{x}^{+} + E_{x}^{-}$$

$$E_{y} = -j\omega A_{y} - j\frac{1}{\omega\mu\varepsilon} \left(\frac{\partial^{2} A_{x}}{\partial x \partial y} + \frac{\partial^{2} A_{y}}{\partial y^{2}} + \frac{\partial^{2} A_{z}}{\partial y \partial z} \right) - \frac{1}{\varepsilon} \left(\frac{\partial^{2} F_{x}}{\partial z} - \frac{\partial F_{z}}{\partial x} \right) = \frac{1}{\varepsilon} \frac{\partial F_{z}}{\partial x} \Rightarrow$$
(1)

$$E_{y} = \frac{1}{\varepsilon} \frac{\partial}{\partial x} F_{z}^{+}(x, y) e^{-j\beta z} + \frac{1}{\varepsilon} \frac{\partial}{\partial x} F_{z}^{-} e^{j\beta z} = E_{y}^{+} + E_{y}^{-}$$
(2)

and it can be shown

$$H_x = H_x^+ + H_x^- = -\sqrt{\frac{\varepsilon}{\mu}} E_y^+ + \sqrt{\frac{\varepsilon}{\mu}} E_y^-$$
 (HW)

$$H_{y} = H_{y}^{+} + H_{y}^{-} = \sqrt{\frac{\varepsilon}{\mu}} E_{x}^{+} - \sqrt{\frac{\varepsilon}{\mu}} E_{x}^{-}, \text{ (HW)}$$

Where expression for $E_y^+, E_y^-, E_x^+, E_x^-$ were given previously (e.g.

$$E_x^+ = -\frac{1}{\varepsilon} \frac{\partial}{\partial y} F_z^+(x, y) e^{-j\beta z} \text{ and } E_x^- = -\frac{1}{\varepsilon} \frac{\partial}{\partial y} F_z^-(x, y) e^{+j\beta z}$$
 (5)

Transverse magnetic wave WRT z-direction (TMz)

• To ensure that wave is a transverse magnetic (TM) field WRT z-direction, it is sufficient to ensure the auxiliary vector potential \vec{A} has only z-component and $\vec{F} = 0$.

• For TM²

$$\vec{A} = \hat{a}_z A_z(x, y, z) \text{ and } \vec{F} = 0$$
(6)

• The field components are then given by

$$E_{x} = -j \frac{1}{\omega \mu \varepsilon} \frac{\partial^{2} A_{z}}{\partial x \partial z} \tag{7}$$

$$E_{y} = -j \frac{1}{\omega \mu \varepsilon} \frac{\partial^{2} A_{z}}{\partial y \partial z} \tag{8}$$

$$E_z = -j \frac{1}{\omega \mu \varepsilon} \left(\frac{\partial^2}{\partial z^2} + \beta^2 \right) A_z \tag{9}$$

$$H_x = \frac{1}{\mu} \frac{\partial}{\partial v} A_z \tag{10}$$

$$H_{y} = -\frac{1}{\mu} \frac{\partial A_{z}}{\partial x} \tag{11}$$

$$H_z = 0 ag{12}$$

• All the field components of the $\mathrm{TM}^{\mathbf{z}}$ mode can also be expressed in terms of E_z

Transverse electric field WRT z-direction (TE^z)

- To have TE^z we require \vec{F} to have only z-component and $\vec{A} = 0$, i.e., $\vec{A} = 0$ and $\vec{F} = \hat{a}_z F_z(x, y, z)$ (1)
- The field components are given by

$$\begin{split} E_x &= -\frac{1}{\varepsilon} \frac{\partial F_z}{\partial y} \\ E_y &= \frac{1}{\varepsilon} \frac{\partial F_z}{\partial x} \\ E_z &= 0 \\ H_x &= -j \frac{1}{\omega \mu \varepsilon} \frac{\partial^2 F_z}{\partial x \partial z} \\ H_y &= -j \frac{1}{\omega \mu \varepsilon} \frac{\partial^2 F_z}{\partial y \partial z} \\ H_z &= -j \frac{1}{\omega \mu \varepsilon} \left(\frac{\partial^2}{\partial z^2} + \beta^2 \right) F_z \end{split}$$

 \bullet All the field components of the $\mathrm{TE^z}$ mode can also be expressed in terms of H_z

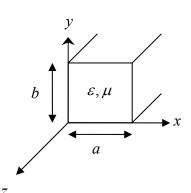
Rectangular metallic wave guide

- Rectangular metallic waveguides are routinely **used at RF and microwave frequencies**. Their study is not only motivated by their use as RF/microwave components, but will help us **better understand the concept of mode** and guided wave propagation
- In studying the guided wave structures we are usually interested in parameters such as: **field configurations (modes)** that are supported by the structure, the structure **cutoff frequency**, **guided wavelength**, **wave impedance**, **phase constant**, **attenuation constant**, etc.
- For metallic rectangular waveguide, it can be shown that although TEM field configuration is the lowest order mode, it does not satisfy the boundary conditions and as such, the waveguide does not support TEM modes
- However, the TE and TM modes satisfy the required boundary conditions and as such are supported by the structure

Transverse Electric Field TE^z

- Consider the **metallic waveguide of size** $a \times b$ as shown. The **waveguide is infinite in** the **z-direction**
- From our previous discussion we have seen that TE^z modes are obtained if $\vec{A} = 0$ and $\vec{F} = \hat{a}_z F_z(x, y, z)$ which implied

$$\begin{split} E_{x} &= -\frac{1}{\varepsilon} \frac{\partial F_{z}}{\partial y} \\ H_{x} &= -j \frac{1}{\omega \mu \varepsilon} \frac{\partial^{2} F_{z}}{\partial x \partial z} \\ E_{y} &= \frac{1}{\varepsilon} \frac{\partial F_{z}}{\partial x} \\ H_{y} &= -j \frac{1}{\omega \mu \varepsilon} \frac{\partial^{2} F_{z}}{\partial y \partial z} \\ E_{z} &= 0 \\ H_{z} &= -j \frac{1}{\omega \mu \varepsilon} \left(\frac{\partial^{2}}{\partial z^{2}} + \beta^{2} \right) F_{z} \end{split}$$



- \vec{F} must satisfy the vector differential equation $\nabla^2 \vec{F} + \beta^2 \vec{F} = 0 \Rightarrow \nabla^2 F_z(x, y, z) + \beta^2 F_z(x, y, z) = 0 \Rightarrow \frac{\partial^2 F_z}{\partial x^2} + \frac{\partial^2 F_z}{\partial y^2} + \frac{\partial^2 F_z}{\partial z^2} + \beta^2 F_z = 0$
- Note that $F_z(x, y, z)$ is a scalar function that can be written as (using separation of variables) $F_z(x, y, z) = f(x)g(y)h(z)$
- Also recall that solutions to $\nabla^2 F_z + \beta^2 F_z = 0$ are either standing waves (sinusoidal) or traveling waves (exponential with complex argument)
- The particular form (standing wave or traveling wave) is chosen based on the boundary conditions to be satisfied
- In the case of our metallic waveguide solutions in x and y must be standing waves and solution in z-direction (guide is infinite in the z-direction) must be traveling wave

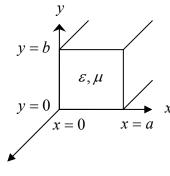
Hence

$$F_{z}(x, y, z) = f(x)g(y)h(z)$$

$$= [C_{1}\cos(\beta_{z}x) + D_{1}\sin(\beta_{x}x)] \cdot [C_{2}\cos(\beta_{y}y) + D_{2}\sin(\beta_{y}y)] \cdot [A_{3}e^{-j\beta_{z}z} + B_{3}e^{+j\beta_{z}z}]$$
with
$$\beta_{x}^{2} + \beta_{y}^{2} + \beta_{z}^{2} = \beta^{2} = \omega^{2}\mu\varepsilon$$

$$\beta_x^2 + \beta_y^2 + \beta_z^2 = \beta^2 = \omega^2 \mu \varepsilon$$

- Recall that for $e^{j\omega t}$ time dependency, $e^{-j\beta_z z}$ is a positively traveling wave (wave travels in positive z-direction) and $e^{+j\beta_z z}$ is a negatively traveling wave (wave travels in negative *z*-direction)
- If source is located such that only positively traveling wave is present, then $B_3 e^{+j\beta_z z} = 0 \Longrightarrow B_3 = 0$
- If source is located such that only negatively traveling wave is present, then $A_3 e^{-j\beta_z z} = 0 \Longrightarrow A_3 = 0$
- If both positively and negatively traveling waves are present (a waveguide terminated on a load that is not matched), then both $A_3e^{-j\beta_z z}$ and $B_3e^{+j\beta_z z}$ must be included
- Here, for simplicity, we assume that only positive traveling wave exist $\Rightarrow B_3 = 0$



•The F_z is then given by

$$F_{z}^{+}(x,y,z) = \left[C_{1}\cos(\beta_{x}x) + D_{1}\sin(\beta_{x}x)\right] \cdot \left[C_{2}\cos(\beta_{y}y) + D_{2}\sin(\beta_{y}y)\right] A_{3}e^{-j\beta_{z}z}$$
(1)

- We impose the boundary conditions on the top, bottom, left and right walls of the metallic waveguide, assuming a perfect electric conductor (PEC) boundary condition, i.e. \vec{E} and \vec{H} tangential are zero on the walls
- The boundary conditions are:

$$E_x(0 \le x \le a, y = 0, z) = E_x(0 \le x \le a, y = b, z) = 0$$
, Bottom and top walls for E_x (2)

$$E_z(0 \le x \le a, y = 0, z) = E_z(0 \le x \le a, y = b, z) = 0$$
, Bottom and top walls for E_z (3)

$$E_v(x = 0.0 \le y \le b, z) = E_v(x = a.0 \le y \le b, z) = 0$$
, Left and right walls for E_v (4)

$$E_z(x=0.0 \le y \le b, z) = E_z(x=a.0 \le y \le b, z) = 0$$
, Left and right walls for E_z (5)

• Note that the boundary conditions (3) and (5) are not independent and they represent the same boundary conditions as (2) and (4).

- The necessary and sufficient conditions are to satisfy either (2) or (3) (E_x and E_z at bottom and top walls) and either (4) or (5) (E_y and E_z at the left and right walls)
- Furthermore, note that for \mathbf{TE}^z modes by definition E_z is zero. This means that the necessary and sufficient B.C.'s for \mathbf{TE}^z are (2) and (4) of the last page (E_x at the bottom and the top and E_y at the left and right walls)

$$E_x(0 \le x \le a, y = 0, z) = E_x(0 \le x \le a, y = b, z) = 0$$

 $E_y(x = 0, 0 \le y \le b, z) = E_y(x = a, 0 \le y \le b, z) = 0$

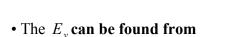
• Recall that the **vector potential for TE^z was given as** [Eq. (1), last page] $F_x^+(x,y,z) = \left[C_1\cos(\beta_x x) + D_1\sin(\beta_x x)\right] \cdot \left[C_2\cos(\beta_y y) + D_2\sin(\beta_y y)\right] A_3 e^{-j\beta_z z} \ .$ We then have

$$E_x = -\frac{1}{\varepsilon} \frac{\partial F_z^+}{\partial y} = -A_3 \frac{\beta_y}{\varepsilon} \left[C_1 \cos(\beta_x x) + D_1 \sin(\beta_x x) \right] \cdot \left[-C_2 \sin(\beta_y y) + D_2 \cos(\beta_y y) \right] A_3 e^{-j\beta_z z}$$

- From $E_x(0 \le x \le a, y = 0, z) = 0 \Rightarrow D_2 = 0$
- From $E_x(0 \le x \le a, y = b, z) = 0 \Rightarrow \sin(\beta_y b) = 0 \Rightarrow \beta_y b = n\pi$ n = 0,1,2,3 or equally,

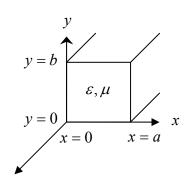
$$\beta_y = \frac{n\pi}{b} \quad n = 0,1,2,3$$

- β_y is sometimes referred to as eigenvalue
- If we use our newly found results, we have $F_z^+(x,y,z) = \left[C_1 \cos(\beta_x x) + D_1 \sin(\beta_x x)\right] C_2 \cos\left(\frac{n\pi}{h}y\right) A_3 e^{-j\beta_z z}$



$$E_{y} = \frac{1}{\varepsilon} \frac{\partial F_{z}}{\partial x} = \frac{\beta_{x}}{\varepsilon} \left[-C_{1} \sin(\beta_{x}x) + D_{1} \cos(\beta_{x}x) \right] C_{2} \cos\left(\frac{n\pi}{b}y\right) A_{3}e^{-j\beta_{z}x}$$

- Boundary conditions for E_y at left wall is $E_y(x = 0.0 \le y \le b, z) = 0 \Rightarrow D_1 = 0$
- Boundary condition for E_y at right wall is $E_y(x = a, 0 \le y \le b, z) = 0 \Rightarrow \sin(\beta_x a) = 0 \Rightarrow$



$$\beta_x a = m\pi \ m = 0,1,2,3$$
 or equally

$$\beta_x = \frac{m\pi}{a} m = 0,1,2,3$$

• Putting it all together, the vector potential F_z^+ is given by

$$F_z^+(x,y,z) = C_1 \cos\left(\frac{m\pi}{a}x\right) C_2 \cos\left(\frac{n\pi}{b}y\right) A_3 e^{-j\beta_z z} = A_{mn} \cos\left(\frac{m\pi}{a}x\right) \cos\left(\frac{n\pi}{b}y\right) e^{-j\beta_z z}$$
with $m = 0,1,2,3$ but $m = n \neq 0$

$$A_{mn} \text{ is a constant} = C_1 C_2 A_3$$

Propagation constant (wave numbers) and wavelengths in the x, y and z direction

• From our previous discussion it is clear that **propagation constant (or wave number)** along $x(\beta_x)$ and along $y(\beta_y)$ can be written as

$$\beta_x = \frac{m\pi}{a} = \frac{2\pi}{\lambda x} \Rightarrow \lambda_x = \frac{2a}{m}; m = 0, 1, 2$$
 (1)

$$\beta_{y} = \frac{n\pi}{b} = \frac{2\pi}{\lambda y} \Rightarrow \lambda_{y} = \frac{2b}{n}; n = 0, 1, 2 \text{ and with } m = n \neq 0,$$
 (2)

where we have also defined the wavelength along x to be λ_x and along y to be λ_y

• Recall that $\beta_x^2 + \beta_y^2 + \beta_z^2 = \beta^2 = \omega^2 \mu \varepsilon$ or equally well:

$$\frac{1}{\lambda_x^2} + \frac{1}{\lambda_y^2} + \frac{1}{\lambda_z^2} = \frac{1}{\lambda^2}$$
 where λ is the wavelength in the medium with ε and

 μ (material inside the guide)

- From (1) and (2) note that β_x and β_y are discrete (one can say they are quantized), where as β_z is a continuous parameter.
- Note that in principle there are **infinite numbers of possible** β_x and β_y (eigenvalues) hence there are **infinite number of TE^z modes that satisfy the wave equation** and the given boundary condition.

• From
$$\beta_x = \frac{m\pi}{a}$$
 and $\beta_y = \frac{n\pi}{b}$ and $\beta_x^2 + \beta_y^2 + \beta_z^2 = \beta^2 = \omega^2 \mu \varepsilon$ we can see that

$$\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2 + \beta_z^2 = \beta^2 \Rightarrow \beta^2 - \beta_z^2 = \left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2 = \beta_c^2,$$

where by definition: $\beta_c \equiv \text{cutoff propagation constant or cutoff wave number}$

• Note that
$$\beta_c = \beta|_{\beta_z=0} = \omega \sqrt{\mu \varepsilon}|_{\beta_z=0} = \omega_c \sqrt{\mu \varepsilon} = 2\pi f_c \sqrt{\mu \varepsilon} = \sqrt{\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2}$$
.

• Hence, the cutoff frequency (f_c) is given by

$$(f_c)_{\min} = \frac{1}{2\pi\sqrt{\mu\varepsilon}} \sqrt{\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2} \quad m = 0,1,2,3 \atop n = 0,1,2,3 \rbrace m = n \neq 0$$

- From the expression $\beta_c = \beta \big|_{\beta_z=0}$ we can see why β_c is called the cutoff propagation constant. For this wave number, $\beta_z = 0$ and the wave no longer travels along the z-direction.
- The above can be more clearly seen from

$$\beta_z^2 = \beta^2 - (\beta_x^2 + \beta_y^2) = \beta^2 - \left(\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2\right) = \beta^2 - \beta_c^2. \text{ Clearly for}$$

$$\beta = \beta_c \Rightarrow \beta_z = 0$$

• The field components for TE_{mn}^{+z} are now given by

$$E_{x}^{+} = A_{mn} \frac{\beta_{y}}{\varepsilon} \cos(\beta_{x}x) \sin(\beta_{y}y) e^{-j\beta_{z}z}$$

$$E_{y}^{+} = -A_{mn} \frac{\beta_{x}}{\varepsilon} \sin(\beta_{x}x) \cos(\beta_{y}y) e^{-j\beta_{z}z}$$

$$E_{z}^{+} = 0$$

$$H_{x}^{+} = A_{mn} \frac{\beta_{x}\beta_{z}}{\omega\mu\varepsilon} \sin(\beta_{x}x) \cos(\beta_{y}y) e^{-j\beta_{z}z}$$

$$H_{y}^{+} = A_{mn} \frac{\beta_{y}\beta_{z}}{\omega\mu\varepsilon} \cos(\beta_{x}x) \sin(\beta_{y}y) e^{-j\beta_{z}z}$$

$$H_{z}^{+} = -jA_{mn} \frac{\beta_{c}^{2}}{\omega\mu\varepsilon} \cos(\beta_{x}x) \sin(\beta_{y}y) e^{-j\beta_{z}z}$$

• To appreciate the importance of the cutoff conditions consider the following:

$$\beta_z^2 = \beta^2 - \beta_c^2 = \beta^2 - \left[\left(\frac{m\pi}{a} \right)^2 + \left(\frac{n\pi}{b} \right)^2 \right] \Rightarrow$$

$$(\beta_z)_{mn} = \pm \sqrt{\beta^2 - \beta_c^2} = \pm \beta \sqrt{1 - \left(\frac{\beta_c}{\beta}\right)^2}$$

$$= \pm \beta \sqrt{1 - \left(\frac{f_c}{f}\right)^2} = \pm \beta \sqrt{1 - \left(\frac{\lambda}{\lambda_c}\right)^2}$$
for $\beta > \beta_c \iff f > f_c$

for
$$\beta > \beta_c \Leftrightarrow f > f_c$$

$$\bullet \left(\beta_z\right)_{mn} = 0$$

for
$$\beta = \beta_c \Leftrightarrow f = f_c$$

•
$$(\beta_z)_{mn} = \pm j\sqrt{\beta_c^2 - \beta^2} = \pm j\beta\sqrt{\left(\frac{\beta_c}{\beta}\right)^2 - 1}$$

$$= \pm j\beta\sqrt{\left(\frac{f_c}{f}\right)^2 - 1} = \pm j\beta\sqrt{\left(\frac{\lambda}{\lambda_c}\right)^2 - 1} \qquad \text{for } \beta_c > \beta \Leftrightarrow f_c > f$$

for
$$\beta_c > \beta \Leftrightarrow f_c > f$$

• If we only consider the positively traveling wave we must choose the sign in front of the square root appropriately, i.e.

$$(\beta_z)_{mn} = \beta \sqrt{1 - \left(\frac{\beta_c}{\beta}\right)^2} = \beta \sqrt{1 - \left(\frac{f_c}{f}\right)^2} = \beta \sqrt{1 - \left(\frac{\lambda}{\lambda_c}\right)^2}$$

for
$$\beta_c < \beta \Leftrightarrow f_c < f$$

$$\left(\beta_z\right)_{mn}=0$$

for
$$\beta_c = f_c = 0$$

$$(\beta_z)_{mn} = 0 \qquad \text{for } \beta_c = f_c = 0$$

$$(\beta_z)_{mn} = -j\beta\sqrt{\left(\frac{\beta_c}{\beta}\right)^2 - 1} = -j\beta\sqrt{\left(\frac{f_c}{f}\right)^2 - 1} = -j\beta\sqrt{\left(\frac{\lambda}{\lambda_c}\right)^2 - 1} \qquad \text{for } \beta_c > \beta \Leftrightarrow f_c > f$$

for
$$\beta_c > \beta \Leftrightarrow f_c > f$$

• Since electric and magnetic fields are proportional to $e^{-jeta_z z}e^{j\omega t}$ then

 $e^{-j\beta\sqrt{1-\left(\frac{f_c}{f}\right)^2}z}e^{j\omega t}$ represents a propagating wave for $f_c < f$ $e^{j\omega t}e^{-j0z} = e^0e^{j\omega t} = 1e^{j\omega t}$ represents a standing wave for $f_c = f$

$$e^{-j\left(-j\beta\sqrt{\left(\frac{f_c}{f}\right)^2-1}\right)z}e^{j\omega t} = e^{-\beta z\left[\sqrt{\left(\frac{f_c}{f}\right)^2-1}\right]z}e^{j\omega t}$$
 represents an attenuated (evanescent) wave for $f_c > f$