

HW #5

Q1) A vector field $\vec{A} = \hat{a}_\rho (3\cos\phi) - \hat{a}_\phi (2\rho) + 5\hat{a}_z$ is expressed in cylindrical coordinates. Find its representation in rectangular coordinate system.

Sol: ①
$$\begin{pmatrix} A_x \\ A_y \\ A_z \end{pmatrix} = \begin{pmatrix} \cos\phi & -\sin\phi & 0 \\ \sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} A_\rho \\ A_\phi \\ A_z \end{pmatrix} \Rightarrow$$

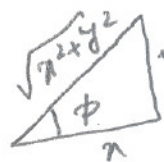
② $A_x = \cos\phi A_\rho - \sin\phi A_\phi = \cos\phi (3\cos\phi) - \sin\phi (-2\rho) = 3\cos^2\phi + 2\rho\sin\phi$

③ $A_y = \sin\phi A_\rho + \cos\phi A_\phi = \sin\phi (3\cos\phi) + \cos\phi (-2\rho) = 3\cos\phi\sin\phi - 2\rho\cos\phi$

④ $A_z = A_z = 5$

* Now we need to know how to convert $\cos\phi$, $\sin\phi$ & ρ to rectangular coordinates. Recall

$x = \rho\cos\phi$
 $y = \rho\sin\phi$
 $x^2 + y^2 = \rho^2$
 $\tan\phi = y/x$



$\cos\phi = \frac{x}{\sqrt{x^2 + y^2}}$

$\sin\phi = \frac{y}{\sqrt{x^2 + y^2}}$

$\rho = \sqrt{x^2 + y^2}$

$A_x = 3\cos^2\phi + 2\rho\sin\phi = 3 \frac{x^2}{x^2 + y^2} + 2\sqrt{x^2 + y^2} \frac{y}{\sqrt{x^2 + y^2}} \Rightarrow$

$$A_x = \frac{3x^2}{x^2 + y^2} + 2y$$

$A_y = 3\cos\phi\sin\phi - 2\rho\cos\phi = 3 \frac{x}{\sqrt{x^2 + y^2}} \frac{y}{\sqrt{x^2 + y^2}} - 2\sqrt{x^2 + y^2} \frac{x}{\sqrt{x^2 + y^2}} \Rightarrow$

$$A_y = \frac{3xy}{x^2 + y^2} - 2x$$

$A_z = 5$ then

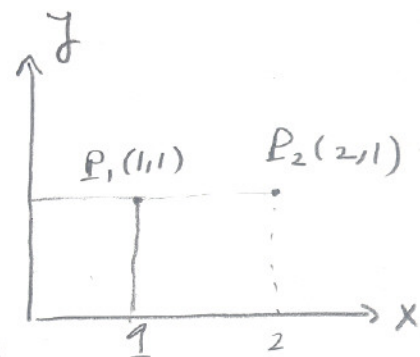
$$\vec{A} = A_x \hat{a}_x + A_y \hat{a}_y + A_z \hat{a}_z = \left(\frac{3x^2}{x^2 + y^2} + 2y \right) \hat{a}_x + \left(\frac{3xy}{x^2 + y^2} - 2x \right) \hat{a}_y + 5\hat{a}_z$$

Q2: Consider the central force $\vec{F} = \frac{1}{r^2} \hat{a}_r$. calculate the work done in presence of the above field in moving from $P_1(1,1)$ to $P_2(2,1)$ along the line $P_1 P_2$

Sol: We convert the $\vec{F} = \frac{1}{r^2} \hat{a}_r$ to rectangular

Coordinates-

$$\begin{pmatrix} F_x \\ F_y \\ F_z \end{pmatrix} = \begin{pmatrix} \sin\theta \cos\phi & \cos\theta \cos\phi & -\sin\phi \\ \sin\theta \sin\phi & \cos\theta \sin\phi & \cos\phi \\ \cos\theta & -\sin\theta & 0 \end{pmatrix} \begin{pmatrix} F_r \\ F_\theta = 0 \\ F_\phi = 0 \end{pmatrix} \Rightarrow$$



$$\begin{aligned} F_x &= \sin\theta \cos\phi F_r \\ F_y &= \sin\theta \sin\phi F_r \\ F_z &= \cos\theta F_r \end{aligned}$$

here since we are only in two dimensions, i.e. we are in x-y plane for which $\theta = \pi/2$ we have

$$\begin{aligned} F_x &= \cos\phi F_r = \cos\phi \frac{1}{r^2} \\ F_y &= \sin\phi F_r = \sin\phi \frac{1}{r^2} \\ F_z &= 0 \end{aligned}$$

* The relation between (x, y, z) & (r, θ, ϕ) in 3-D is given by

$$\begin{aligned} x &= r \sin\theta \cos\phi \\ y &= r \sin\theta \sin\phi \\ z &= r \cos\theta \end{aligned}$$

In 2D (x-y plane) $\theta = \pi/2 \Rightarrow$

$$\begin{aligned} x &= r \cos\phi \\ y &= r \sin\phi \\ z &= 0 \end{aligned} \Leftrightarrow \begin{aligned} x^2 + y^2 &= r^2 \\ \cos\phi &= \frac{x}{r} = \frac{x}{\sqrt{x^2 + y^2}} \\ \sin\phi &= \frac{y}{r} = \frac{y}{\sqrt{x^2 + y^2}} \end{aligned}$$

then

$$F_x = \cos \phi \frac{1}{r^2} = \frac{x}{\sqrt{x^2+y^2}} \frac{1}{x^2+y^2} = \frac{x}{(x^2+y^2)^{3/2}}$$

$$F_y = \sin \phi \frac{1}{r^2} = \frac{y}{\sqrt{x^2+y^2}} \frac{1}{x^2+y^2} = \frac{y}{(x^2+y^2)^{3/2}}$$

$$\vec{F} = F_x \hat{a}_x + F_y \hat{a}_y = \frac{1}{(x^2+y^2)} \left[\frac{x}{\sqrt{x^2+y^2}} \hat{a}_x + \frac{y}{\sqrt{x^2+y^2}} \hat{a}_y \right]$$

$$W = \int \vec{F} \cdot d\vec{r} = \int (F_x \hat{a}_x + F_y \hat{a}_y) \cdot (dx \hat{a}_x + dy \hat{a}_y)$$

$$= \int F_x dx + F_y dy$$

but in going from P_1 to P_2 we move along the line $y=1 \Rightarrow dy=0 \Rightarrow$

$$W = \int F_x dx = \int_{x=1}^{x=2} \frac{x}{(x^2+y^2)^{3/2}} dx$$

we need to express y in terms of x . Note that in going from P_1 to P_2 y is constant & equal to 1 $\Rightarrow$

$$W = \int_{x=1}^{x=2} \frac{x}{(x^2+1)^{3/2}} dx$$

$$\text{let } u = x^2+1 \\ du = 2x dx \Rightarrow$$

$$\frac{1}{2} du = x dx \Rightarrow$$

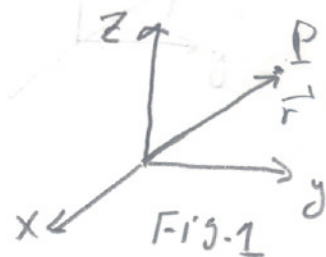
$$W = \int \frac{1}{2} \frac{du}{u^{3/2}} = \frac{1}{2} \left(\frac{u^{-1/2}}{-1/2} \right) =$$

$$-\left(\frac{1}{\sqrt{x^2+1}} \right) \Big|_{x=1}^{x=2} = \frac{1}{\sqrt{2}} - \frac{1}{\sqrt{5}}$$

Q3 ✓

a) Let $\vec{r}$ be the position vector, pointing from origin to the point of observation P. show that

$\nabla |\vec{r}| = \nabla r = \frac{\vec{r}}{|\vec{r}|} = \frac{\vec{r}}{r} = \hat{a}_r$ where $\hat{a}_r$ is the unit, normal in the direction of $\vec{r}$.



b) let function $g(r)$ depend only on the distance between the source points (Primed coordinates)

& the observation point (Un primed coordinates), see Fig 2.

prove that $\nabla g(r) = \nabla f(R) = \hat{a}_R \frac{\partial f(R)}{\partial R}$. Use this information to calculate the gradient of $g(x, y, z) = f(R) = \sin\left(\pi \frac{R^2}{4}\right)$

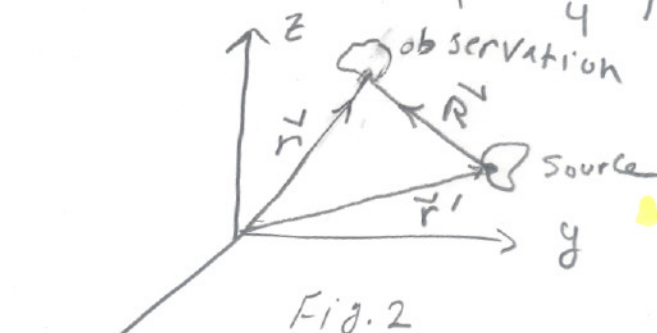
sol:

a) $\vec{r} = x \hat{a}_x + y \hat{a}_y + z \hat{a}_z$
 $|\vec{r}| = r = [x^2 + y^2 + z^2]^{1/2}$

$$\nabla |\vec{r}| = \nabla r = \frac{2x}{2\sqrt{x^2 + y^2 + z^2}} \hat{a}_x +$$

$$\frac{2y}{2\sqrt{x^2 + y^2 + z^2}} \hat{a}_y + \frac{2z}{2\sqrt{x^2 + y^2 + z^2}} \hat{a}_z$$

$$= \frac{x \hat{a}_x + y \hat{a}_y + z \hat{a}_z}{\sqrt{x^2 + y^2 + z^2}} = \frac{\vec{r}}{|\vec{r}|} = \hat{a}_r$$



b) we note the following

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$$\vec{R} = (x-x')\hat{x} + (y-y')\hat{y} + (z-z')\hat{z} \quad \&$$

$$R = |\vec{R}| = [(x-x')^2 + (y-y')^2 + (z-z')^2]^{1/2} \quad \text{then}$$

$$\nabla |\vec{R}| = \nabla R = \frac{(x-x')\hat{x} + (y-y')\hat{y} + (z-z')\hat{z}}{\sqrt{(x-x')^2 + (y-y')^2 + (z-z')^2}}$$

$$= \frac{\vec{R}}{|\vec{R}|} = \hat{R}$$

Also from chain rule for differentiation

$$\nabla g(r) = \nabla f(R) = \frac{\partial f(R)}{\partial R} \nabla R = \frac{\partial f(R)}{\partial R} \hat{R}$$

Using the above to calculate

$$\nabla f(R) = \nabla \left[\sin\left(\pi \frac{R^2}{4}\right) \right] = \frac{\partial}{\partial R} \sin\left(\pi \frac{R^2}{4}\right) \hat{R}$$

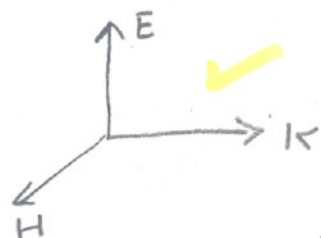
$$= \frac{2\pi R}{4} \cos\left(\pi \frac{R^2}{4}\right) \hat{R} = \frac{\pi R}{2} \cos\left(\pi \frac{R^2}{4}\right) \hat{R}$$

Q4: Consider a plane wave $\vec{E} = \vec{E}_0 e^{-j\vec{k} \cdot \vec{r} + j\omega t}$ propagating in a homogeneous, lossless, source free region for which $\epsilon > 0$ & $\mu > 0$ & $\vec{E}_0$ is constant.

a) show that $\vec{k} \perp \vec{E}$ & $\vec{k} \perp \vec{H}$

b) show that $\vec{k}$, $\vec{E}$ & $\vec{H}$ form a right hand triplet (Hint

$$\vec{k} \times \vec{E} = \omega \mu \vec{H} \text{ \& \> } \vec{k} \times \vec{H} = -\epsilon \omega \vec{E}$$



Sol: since source free $\nabla \cdot \vec{E} = 0$ &

$$\nabla \cdot \vec{B} = 0$$

From vector calculus $\nabla \cdot (\rho \vec{F}) = (\nabla \cdot \vec{F}) \rho + \nabla \rho \cdot \vec{F}$

$$\text{then } \nabla \cdot (\vec{E}_0 e^{-j\vec{k} \cdot \vec{r} + j\omega t}) = (\nabla \cdot \vec{E}_0) e^{-j\vec{k} \cdot \vec{r} + j\omega t} + \nabla(e^{-j\vec{k} \cdot \vec{r} + j\omega t}) \cdot \vec{E}_0$$

since $\vec{E}_0$ is constant $\nabla \cdot \vec{E}_0 = 0 \Rightarrow$

$$\nabla \cdot (\vec{E}_0 e^{-j\vec{k} \cdot \vec{r} + j\omega t}) = \nabla(e^{-j\vec{k} \cdot \vec{r} + j\omega t}) \cdot \vec{E}_0 = -j\vec{k} e^{-j\vec{k} \cdot \vec{r} + j\omega t} \cdot \vec{E}_0 = -j(\vec{k} \cdot \vec{E}_0) e^{-j\vec{k} \cdot \vec{r} + j\omega t}$$

but from (1) we must have

$$-j(\vec{k} \cdot \vec{E}_0) e^{-j\vec{k} \cdot \vec{r} + j\omega t} = 0 \Rightarrow \vec{k} \cdot \vec{E}_0 = 0 \Rightarrow \vec{k} \perp \vec{E}_0 \Rightarrow \vec{k} \perp \vec{E} \quad (8)$$

* using equation (2) & similar argument, i.e

$$\nabla \cdot \vec{B} = 0 \Rightarrow \nabla \cdot \vec{H} = 0 \Rightarrow \nabla \cdot (\vec{H}_0 e^{-j\vec{k} \cdot \vec{r} + j\omega t}) = 0 \Rightarrow$$

$$\vec{k} \cdot \vec{H}_0 = 0 \Rightarrow \vec{k} \perp \vec{H}_0 \Rightarrow \vec{k} \perp \vec{H} \quad (10)$$

b) sin wave source free & simple medium (12)

$$(11) \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \xrightarrow{\text{Time Harmonic}} \boxed{\nabla \times \vec{E} = -j\omega \vec{B} = -j\omega \mu \vec{H}} \quad (12)$$

$$(13) \nabla \times \vec{H} = +\frac{\partial \vec{D}}{\partial t} \xrightarrow{\text{Time Harmonic}} \boxed{\nabla \times \vec{H} = j\omega \vec{D} = j\omega \epsilon \vec{E}} \quad (14)$$

Let us calculate (15) $\nabla \times \vec{E} = \nabla \times (\vec{E}_0 e^{-j\vec{k} \cdot \vec{r} + j\omega t})$

The following identity holds

$$(16) \nabla \times (f \vec{F}) = \nabla f \times \vec{F} + f \nabla \times \vec{F}$$

Using (16) in (15)

$$\begin{aligned} \nabla \times \vec{E} &= \nabla \times (\vec{E}_0 e^{-j\vec{k} \cdot \vec{r} + j\omega t}) = \\ &= (\nabla e^{-j\vec{k} \cdot \vec{r} + j\omega t}) \times \vec{E}_0 + e^{-j\vec{k} \cdot \vec{r} + j\omega t} \nabla \times \vec{E}_0 \\ &= -j\vec{k} e^{-j\vec{k} \cdot \vec{r} + j\omega t} \times \vec{E}_0 = -j\vec{k} \times \vec{E}_0 e^{-j\vec{k} \cdot \vec{r} + j\omega t} \Rightarrow \end{aligned}$$

$$\boxed{\nabla \times \vec{E} = -j\vec{k} \times \vec{E}} \quad (17)$$

Sub (17) in (12) $\Rightarrow -j\vec{k} \times \vec{E} = -j\omega \mu \vec{H} \Rightarrow$

$$(18) \boxed{\vec{k} \times \vec{E} = \omega \mu \vec{H}}$$

* We now use $\vec{H} = \vec{H}_0 e^{-j\vec{k} \cdot \vec{r} + j\omega t}$ to calculate $\nabla \times \vec{H}$ & use the result in (14) to obtain the following

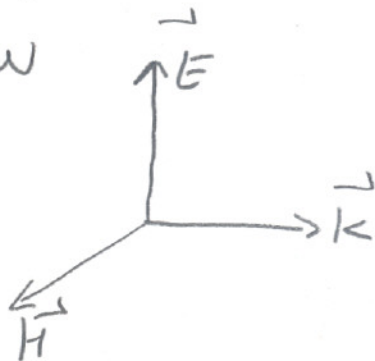
$$\textcircled{19} \quad -j \vec{k} \times \vec{H} = j\omega \epsilon \vec{E} \Rightarrow \textcircled{20} \quad \boxed{\vec{k} \times \vec{H} = -\omega \epsilon \vec{E}}$$

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To summarize we have shown

$$\vec{k} \perp \vec{E}, \vec{k} \perp \vec{H}, \vec{k} \times \vec{E} = \omega \mu \vec{H} \text{ \& \& } \vec{k} \times \vec{H} = -\omega \epsilon \vec{E}$$

from these we see that $\vec{k}, \vec{E}$ & $\vec{H}$ form a Right Hand triplet as shown below



Q5: Starting with differential form of the Maxwell's I equations, find their integral form formulation.

sol:

* $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$ Faraday's law

$$\iint_S \nabla \times \vec{E} \cdot d\vec{s} = -\frac{\partial}{\partial t} \iint_S \vec{B} \cdot d\vec{s} \text{ use Stokes's theorem}$$

$$\oint_C \vec{E} \cdot d\vec{l} = -\frac{\partial}{\partial t} \Phi_B \text{ where } \Phi_B = \iint_S \vec{B} \cdot d\vec{s}$$

* $\nabla \times \vec{H} = \frac{\partial \vec{D}}{\partial t} + \vec{J}$ Ampere's law. use Stokes's theorem

$$\iint_S \nabla \times \vec{H} \cdot d\vec{s} = \frac{\partial}{\partial t} \iint_S \vec{D} \cdot d\vec{s} + \iint_S \vec{J} \cdot d\vec{s} \Rightarrow$$

$$\oint \vec{H} \cdot d\vec{l} = \frac{\partial}{\partial t} \iint_S \vec{D} \cdot d\vec{s} + I \text{ where } I = \iint_S \vec{J} \cdot d\vec{s}$$

* $\nabla \cdot \vec{D} = \rho_e$ Gauss law. use divergence theorem

$$\iiint_V \nabla \cdot \vec{D} dV = \iiint_V \rho_e dV \Rightarrow$$

$$\oiint_S \vec{D} \cdot d\vec{s} = Q_{enc} \text{ where } Q_{enc} = \iiint_V \rho_e dV$$

* $\nabla \cdot \vec{B} = 0$ use divergence theorem

$$\iiint_V \nabla \cdot \vec{B} dV = 0 \Rightarrow \oiint_S \vec{B} \cdot d\vec{s} = 0$$